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## **HIGH INTERNAL INDUCTANCE FOR STEADY-STATE OPERATION IN ITER AND A REACTOR**

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## High Internal Inductance for Steady-State Operation in ITER and a Reactor

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Increased confinement and ideal stability limits at relatively high 1.8 values of the internal inductance  $(l_i)$  have enabled an attractive scenario for steady-state tokamak operation to be demonstrated in The potential of the DIII-D. scenario was shown in double-null 6.0 divertor discharges with both high elongation and triangularity in which  $\beta_N > 4.5$  was achieved at  $l_i \approx 1.3$  [Fig. 1(a,b)]. This high value of  $\beta_N$  just reached the ideal n=1 kink stability limit calculated without the effect of a stabilizing vacuum vessel wall, with the ideal-wall limit still higher at  $\beta_N > 5.5$ . Confinement is well above the H-mode level with



Fig. 1. Parameters in high  $l_i$  discharges in (a,b) a double-null divertor shape, (c-e) the ITER shape scaled to fit the DIII-D vacuum vessel.  $\beta_N$  (with-wall) and  $\beta_N$  (no-wall) are the calculated n=1 ideal MHD stability limits with and without the DIII-D vacuum vessel, respectively.

 $H_{98}\approx 1.8$ . This type of discharge is a candidate for a reactor that could either operate stably at  $\beta_N\approx 4$  without the requirement for a nearby conducting wall or  $n\geq 1$  active stabilization coils, or at  $\beta_N\approx 5$  with wall stabilization.

For ITER, operation at  $l_i \approx 1$  is a promising option for the steady-state mission. Improved core confinement at high  $l_i$  could compensate for reduced H-mode pedestal confinement if a low pedestal height results from pedestal physics and/or ELM-stabilization using 3D fields. At  $l_i \approx 1$ , the self-driven bootstrap current fraction would be  $f_{BS} \approx 0.5$  with the remainder from external current drive that is efficient because the current is driven near the axis. This scenario has been tested in the scaled ITER shape in DIII-D at  $\beta_N \approx 3.4$  with performance appropriate for the ITER Q=5 mission,  $\beta_N H_{89}/q_{95}^2 > 0.3$  [Fig. 1(c,e)]. High  $l_i$  discharges thus far take advantage of inductively driven current density near the axis as a partial substitute for externally-driven current. Modeling with self-consistent heating, current drive and transport of a potential stationary, fully noninductive double-null divertor discharge in DIII-D finds a solution calculated stable without a conducting wall at  $\beta_N=4$ ,  $l_i=1.07$ , and  $f_{BS}=0.5$  with electron cyclotron current drive (ECCD) and neutral beam current drive near the axis (Fig. 2). A similar solution at  $\beta_N=5$  is calculated to be stable with the vacuum vessel wall.

Operation in steady-state requires a compromise between high  $l_i$  and high  $f_{BS}$ . Increased  $\beta_N$  and strong discharge shaping to raise the  $\beta_N$  limit increase the bootstrap current density in the outer half of the plasma, including in the H-mode pedestal region. Thus  $l_i$  will decrease as  $f_{BS}$  increases. The discharges in the scaled ITER shape aimed at a compromise set of parameters expected to be self-consistent for steady-state operation [1] with  $l_i \approx 1$ ,  $\beta_N \approx 4$ ,  $f_{BS} \approx 0.5$ . The experiment thus far has reached somewhat lower  $\beta_N$  at  $q_{95}$ =4.8, yielding  $f_{BS} \approx 0.4$ 

and noninductive current fraction  $f_{\text{NI}}\approx0.7$  [Fig. 1(c)]. In contrast, with high  $\beta_{\text{N}}$  and relatively high  $q_{95}=7$ , the double null divertor discharge is overdriven with  $f_{\text{BS}}\approx0.8$ ,  $f_{\text{NI}}>1$  and negative surface voltage [Fig. 1(a)]. The noninductive current overdrive was confirmed through an increase in the total plasma current when the inductive coil current was held constant.

Reduced H-mode pedestal height self-consistently results in increased  $l_i$  through the reduction in pedestal bootstrap current density. Thus a high  $l_i$  scenario is compatible with variants of H-mode in which ELMs are absent and the pedestal pressure and current density are somewhat reduced (e.g. I-mode, 3D field ELM stabilization). This self-consistency was explored in DIII-D through the use of n=3 fields to modify the pedestal. Increased  $l_i$  was observed as the n=3 field amplitude was increased and the pedestal pressure decreased. Optimization to the minimum possible q(0) also increased  $l_i$  leading to  $q(0)\approx 1$  but without observation of sawteeth.

Global, ideal, low toroidal mode number pressure and current driven instabilities, which are expected to set the ultimate limit to pressure in these discharges, have not yet been observed. The limit to performance is normally an m=2/n=1 resistive tearing mode which is often triggered by an m=1/n=1 fishbone instability-like burst. At  $q_{95}$ =4.5 to 6, the resistive n=1 mode limited the maximum  $\beta_N$  to 3.8–4 in both discharge shapes even though the calculated, ideal n=1  $\beta_N$  limits in the scaled ITER shape are below those in the double-null shape (Fig. 1). However, at  $q_{95}$ =7 in the double null shape,  $\beta_N$  was limited to just below 5, not by instability, but rather by available heating power.

Modeling projects that parameters for stationary, high  $l_i$ , fully noninductive operation are attainable in DIII-D. Studies with model equilibria documented the scaling of  $l_i$  with the pedestal current density [Fig. 2(a)]. An increase of  $l_i$  from 0.75 to 1.3 requires a factor of two decrease in the pedestal current, with  $l_i \approx 1$  at about 75% of the reference experimental value. There is a corresponding increase in the n=1 no-wall  $\beta_N$  limit, which reaches  $\beta_N \approx 5$  with  $l_i \approx 1.3$ , similar to what was observed in the double-null experimental discharges. Thus there is

significant advantage in а stability if current density is shifted from the pedestal region to the core. In order to maintain q(0) > 1 to avoid sawteeth, the width of the current density peak near the axis must increase as  $q_{95}$  is reduced, so that some of the externally-driven current located off-axis. must be Studies with the FASTRAN transport code using the TGLF energy transport model explored how the increased current drive power in a proposed DIII-D upgrade (13



Fig. 2. (a) Scaling in model equilibria of  $l_i$  (squares) and the calculated n=1 no-wall  $\beta_N$  limit (circles) with the H-mode pedestal current density, and (b) current density profiles in the  $\beta_N$ =4 transport code-modeled steady-state solution for DIII-D.

MW off-axis neutral beam, 9 MW ECCD) could be applied to maintain a stationary,  $f_{\rm NI}=1$  high  $l_i$  discharge. In the solution, the bootstrap current density profile is broad [Fig. 2(b)] and off-axis neutral beam current drive coupled with ECCD close to the axis is used to generate the current density peak extending to about  $\rho \approx 0.4$  that maintains the increased value of  $l_i$ .

Thus, modeling and experiment are showing the potential of a high  $l_i$  discharge for fully noninductive, stationary operation. Keys to full development of this scenario are an understanding of how to maximize  $l_i$  through access to appropriate pedestal parameters, avoidance of the performance limiting n=1 tearing mode, and demonstration of the total required externally-driven current near the axis.

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<sup>[1]</sup> Y.R. Lin-Liu, et al., Phys. Plasmas 6, 3934 (1999).