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and THE DIII-D and NSTX TEAMS

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New processes have been identified in the interaction of 3-D fields with tearing mode stability that raise concern for H-modes at modest β_N . These arise from the plasma response at the tearing resonant surface, which is expected to depend on plasma rotation and underlying tearing stability [1]. This leads to additional sensitivities to those previously identified at low density [2] or high β_N , where ideal MHD responses amplify the applied fields [3]. In particular, the field threshold to induce modes falls to zero as natural tearing β_N limits are approached, and plasma responses are further enhanced at low rotation. Typical field thresholds to induce modes in torque-free $\beta_N \sim 1.5$ H-modes are well below those in Ohmic plasmas, or even plasmas above the no-wall ideal kink β_N limit, and scale differently to Ohmic regimes. Comprehensive scans have been executed on DIII-D and NSTX to explore the underlying physics, probe and distinguish between the ideal and resistive responses, and determine the principle scalings to next step devices.

Underlying tearing stability and plasma rotation play critical roles in the criterion for 3-D fields to induce a mode. Although rotation helps shield the field, a residual tearing response and associated braking torque can overcome this, leading to widespread tearing; the nature of this response and the degree of rotation set the threshold for mode formation. To explore this and discriminate from changes in the ideal plasma response, new studies on DIII-D scanned magnetic probing response and field threshold with rotation and β_N . As low rotation leads to lower tearing β limits [4], this has helped decouple tearing and ideal responses. Figure 1 shows two key effects: for a given level of beam driven torque, the required field to induce a mode falls to zero as the neoclassical tearing mode (NTM) β_N limit is approached, in relaxed plasmas that are well below ideal β_N limits; and for a given β_N , the field threshold falls as co-injected beam torque and plasma rotation (which remains parallel to I_p) fall. The behavior suggests the 3-D

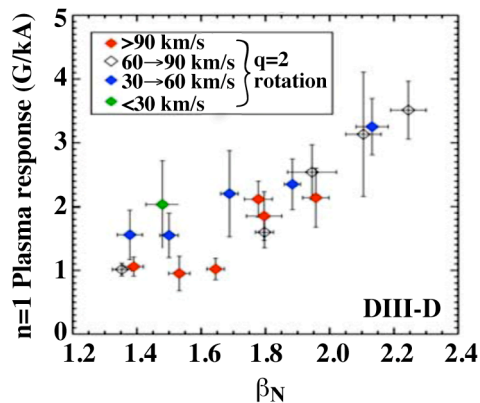


Fig. 2. Plasma response to 10 Hz $n=1$ field prior to mode onset.

field interaction becomes strongly enhanced when in proximity to tearing instability. This is confirmed by magnetic probing prior to mode onset (Fig. 2), with plasma response increasing substantially with β_N , thus less applied field is needed to cause braking. At constant β_N , the response also rises as rotation falls, particularly evident at low β_N in Fig. 2. This shows that the easier destabilization of modes at low rotation, is not just because the plasma has less inertia or a lower torque balance, but because the plasma responds more strongly – a different and additional mechanism to ideal responses that amplify fields at high β_N [2].

An important further aspect is the interaction with the NTM. In most cases in H-mode plasmas, the tearing mode forms rotating, and so cannot be driven directly by the 3-D field. Rather the NTM stability must be changing, most likely through rotation braking [4]. This aspect was explored on NSTX, utilizing its capability to deploy $n=1$ and $n=3$ fields, and decouple rotation from rotation shear. Various mixes of field were applied during β ramps to access the 2/1 NTM. The clearest effect on rotating mode threshold is a trend of bootstrap drive (related to β , but captures more NTM physics) with rotation shear (Fig. 3), confirming previous observations in NTM β limit scaling on NSTX [5], but accessed here through 3-D field braking. Exploring the interaction in more

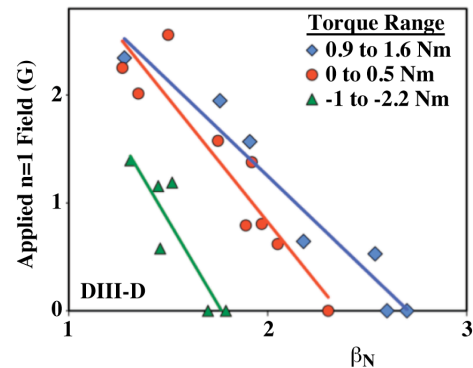


Fig. 1. $n=1$ 3-D field required to trigger 2/1 mode vs β_N and neutral beam torque.

depth (Fig. 4), both resonant ($n=1$) and non-resonant ($n=3$) fields have progressive and similar magnitude effects in braking the plasma and leading to modes (though the balance between rotation and rotation shear braking varies with $n=1:n=3$ field mix). This indicates that the influence on stability is most likely through the braking, rather than a resonant interaction of the field directly with the mode, though braking may be partly a resonant effect. Further, there appears to be a critical $\sim 50\%$ level of braking beyond which modes form locked, with braking response on the approach to this initially weak, and modes forming close to their natural β limit, and then rising rapidly, and modes triggered with less bootstrap drive. This provides a basis for a unifying criteria for the critical field to trigger a mode, akin to, but effectively an extension of, the original Fitzpatrick model [1]. Simply put, in stable plasmas below the tearing β limit, once enough field is applied to achieve substantial braking then a mode will result. The criteria for mode onset can then be discussed in terms of field threshold, effectively to achieve significant braking, irrespective of whether a rotating or locked mode results.

On this basis, new scalings for error field sensitivity of H-modes are required and have been obtained. $n=1$ field thresholds for modes were measured as a function of main plasma parameters in constant $\beta_N=1.8$ torque-free H-modes, using balanced beam injection on DIII-D. As in [2] rotation is treated as a hidden self-generated parameter, its value implicitly assumed to vary as part of the scaling (though adding torque would be a method to raise thresholds), and a dimensional constraint invoked to deduce machine size scaling. While density scaling is stronger and more favorable for next step devices than previous Ohmic scalings, the toroidal field scaling is worse (Fig. 5), and generally thresholds are a factor ~ 6 below Ohmic predictions. Modeling of these recent results is underway with the MARS and NIMROD codes to test this understanding and confirm that the scale of effects matches current theoretical models. These results have far-reaching implications, suggesting that tearing mode stability needs to be considered in assessing magnetic field symmetry requirements, or the impact of 3D field control systems and operating points of future devices, and it is vital to make such assessments at relevant torques or plasma rotations.

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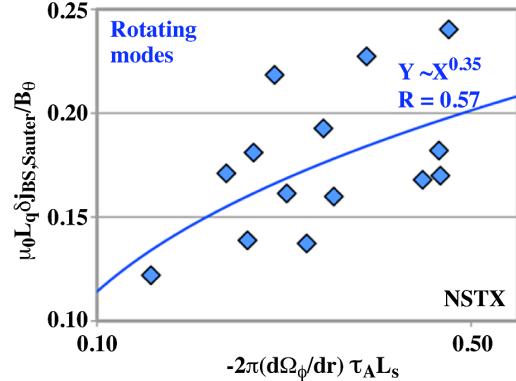


Fig. 3. Bootstrap drive vs rotation shear normalized to Alfvén inverse time and magnetic shear for rotating mode onset.

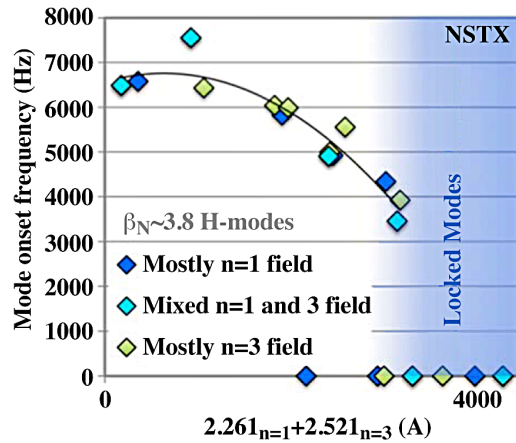


Fig. 4. Incidence of modes with various forms and levels of magnetic braking.

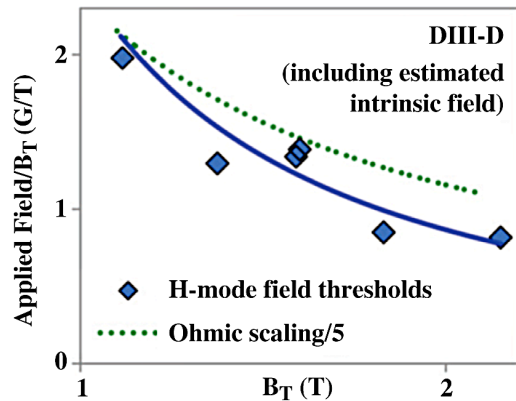


Fig. 5. Toroidal field scaling of mode threshold.