

Evaluating Electron Cyclotron Current Drive Stabilization of Neoclassical Tearing Modes in ITER: Implications of Experiments in ASDEX Upgrade, DIII-D, JET and JT-60U

by
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for
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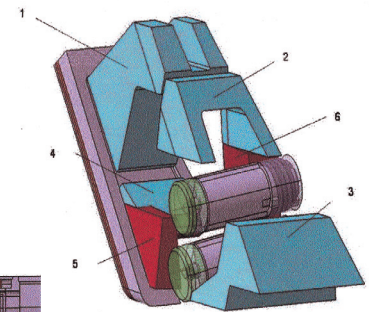
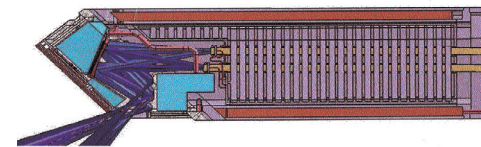
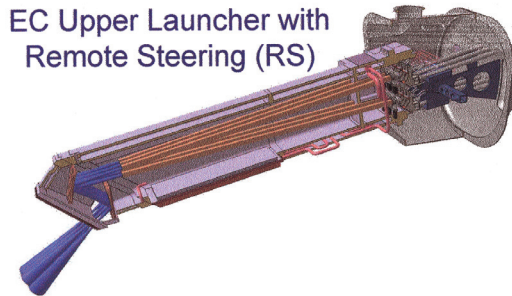
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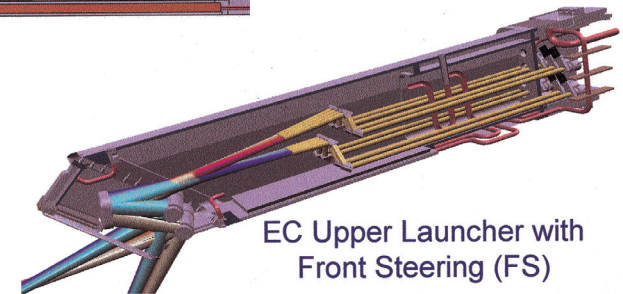
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EC Upper Launcher with
Remote Steering (RS)



FZK-Fusion



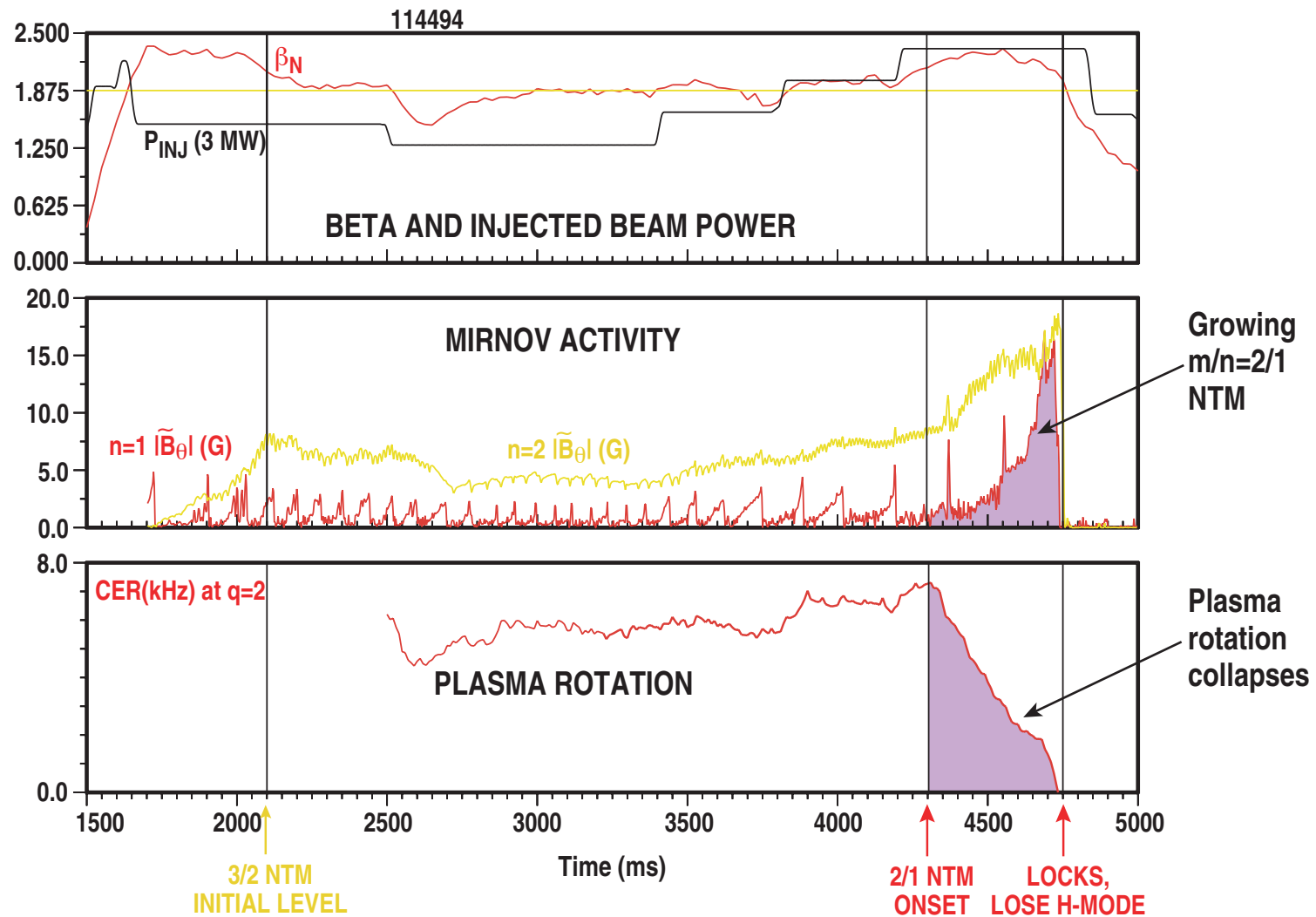
EC Upper Launcher with
Front Steering (FS)

Outline

- **NTMs will be the principal limit to performance in ITER with operation well below the ideal kink beta limit**
- **An NTM can be avoided by removing the “metastable” condition with continous well-aligned ECCD**
 - or an NTM can potentially be limited in size by ECCD modulated in phase with the island O-point
- **Existing devices (ASDEX Upgrade, DIII-D, JET, JT-60U) can be used to:**
 - benchmark the NTM physics
 - model the ECCD power requirement for stabilization
- **The ITER ECCD high launch system is adequate for the job**
 - front steering (Henderson et al., 2005) narrower than remote steering ... thus requires less EC power
 - but benefits of modulation need to be confirmed

Tearing Modes Degrade Confinement and Rotation

- Plasma can lock, lose H-mode, disrupt with $m/n=2/1$ NTM



Slow Plasma Rotation in ITER Makes Locking Problematic

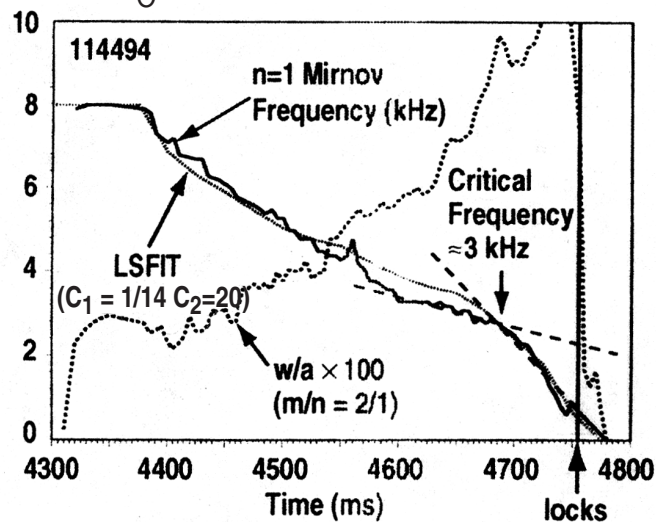
- Modeling yields $m/n=2/1$ critical island of 5 cm in ITER for locking

★ $\omega_0/2\pi = 0.42$ kHz at $q = 2$ (Y. Gribov, ASTRA, 2005)

... $\tau_{A0} = 3.0$ μ s (Y. Gribov, 2005)

... $\tau_W = 0.188$ s (Y. Liu, 2005)

... $\tau_{M0} \equiv \tau_{E0} = 3.7$ s (J. Cordey 2004)



Mode locking of an $m/n = 2/1$ mode in DIII-D. The least square fit (LSFIT) is to the Nave-Wesson wall eddy current model and a 'belt' model of the effect of the island on viscosity (La Haye, et al., 2006)

$$\frac{d\omega}{dt} = \frac{\omega_0 (\tau_M/\tau_{M0}) - \omega}{\tau_M} - \frac{C_1}{2\tau_{A0}^2} \frac{(w/a)^3}{\omega\tau_W}$$

$$\tau_M = \tau_{M0}/(1 + C_2 w/a),$$

$$\tau_A^2 = \frac{\mu_0 R_0^2}{B_\theta^2(r_s)} \left(\frac{r_s}{a}\right) n_e m_i \frac{w}{a} \equiv \tau_{A0}^2 \frac{w}{a},$$

$$\omega = \frac{\omega_0}{2(1 + C_2 w/a)} + \frac{1}{2} \sqrt{\frac{\omega_0^2}{(1 + C_2 w/a)^2} - \frac{2C_1 \tau_{M0} (w/a)^3}{(1 + C_2 w/a) \tau_{A0}^2 \tau_W}}$$

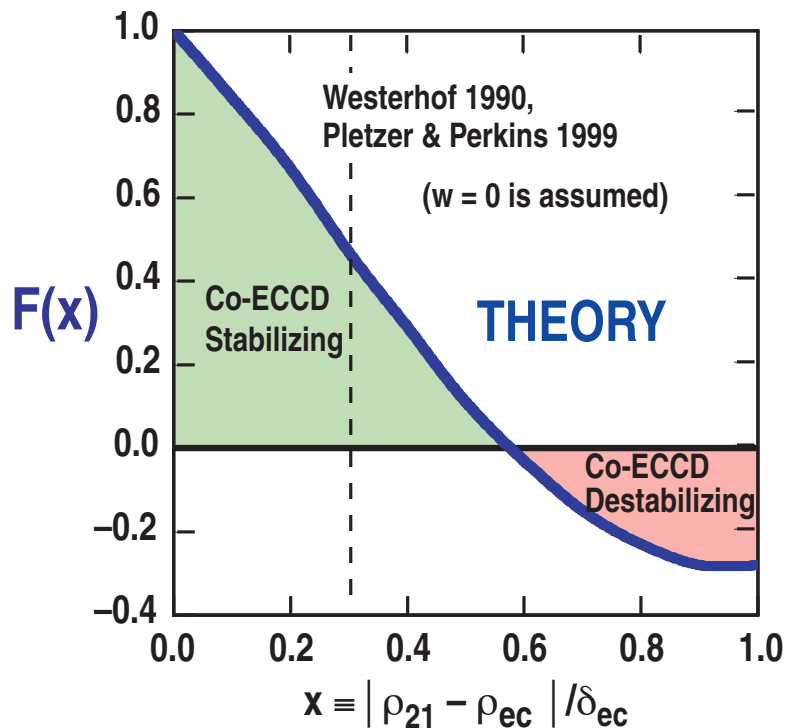
For the $\sqrt{\quad}$ equal to zero further drag results in locking. This gives a **critical island width**

$$\left(\frac{w}{a}\right)^3 (1 + C_2 w/a) = \frac{\omega_0^2 \tau_{A0}^2}{2C_1} \left(\frac{\tau_W}{\tau_{M0}}\right)$$

I. ECCD Can Remove the Metastable Condition by More Negative Δ'

$$\frac{\tau_R}{r} \frac{dw}{dt} = \Delta'_0 r + \underbrace{\delta\Delta' r}_{\text{ECCD Change}} + a_2 \frac{j_{bs}}{j_{||}} \frac{L_q}{w} \left[1 - \frac{w_{\text{marg}}^2}{3w^2} - K_1 \frac{j_{ec}}{j_{bs}} \right] \quad \text{Modified Rutherford Eqn.}$$

- Co-ECCD can make Δ' more negative



- alignment must be good

★ $x = |\delta\rho/\delta_{ec}| < 0.3$
 ... δ_{ec} is FWHM

• $\delta\Delta' r \approx \frac{-5\pi^{3/2}}{32} a_2 \frac{L_q}{\delta_{ec}} F(x) \frac{j_{ec}}{j_{||}}$

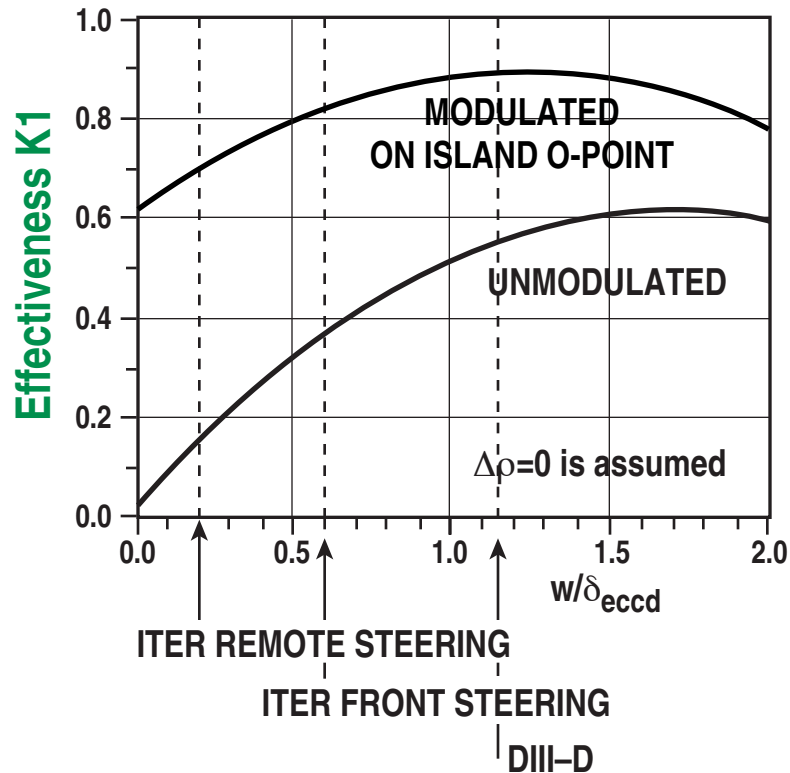
★ $\delta\Delta' r \propto \frac{j_{ec}}{\delta_{ec}} \propto \frac{P_{ec}}{\delta_{ec}^2}$

... favors narrow ECCD

II. ECCD Can Also Remove the Metastable Condition by Replacing the Missing Bootstrap Current

$$\frac{\tau_R}{r} \frac{dw}{dt} = \Delta'_0 r + \delta \Delta' r + a_2 \frac{j_{bs}}{j_{||}} \frac{Lq}{w} \left[1 - \frac{w_{marg}^2}{3w^2} - K_1 \frac{j_{ec}}{j_{bs}} \right] \text{ Modified Rutherford Eqn.}$$

- Co-ECCD can replace the “missing” bootstrap current in island

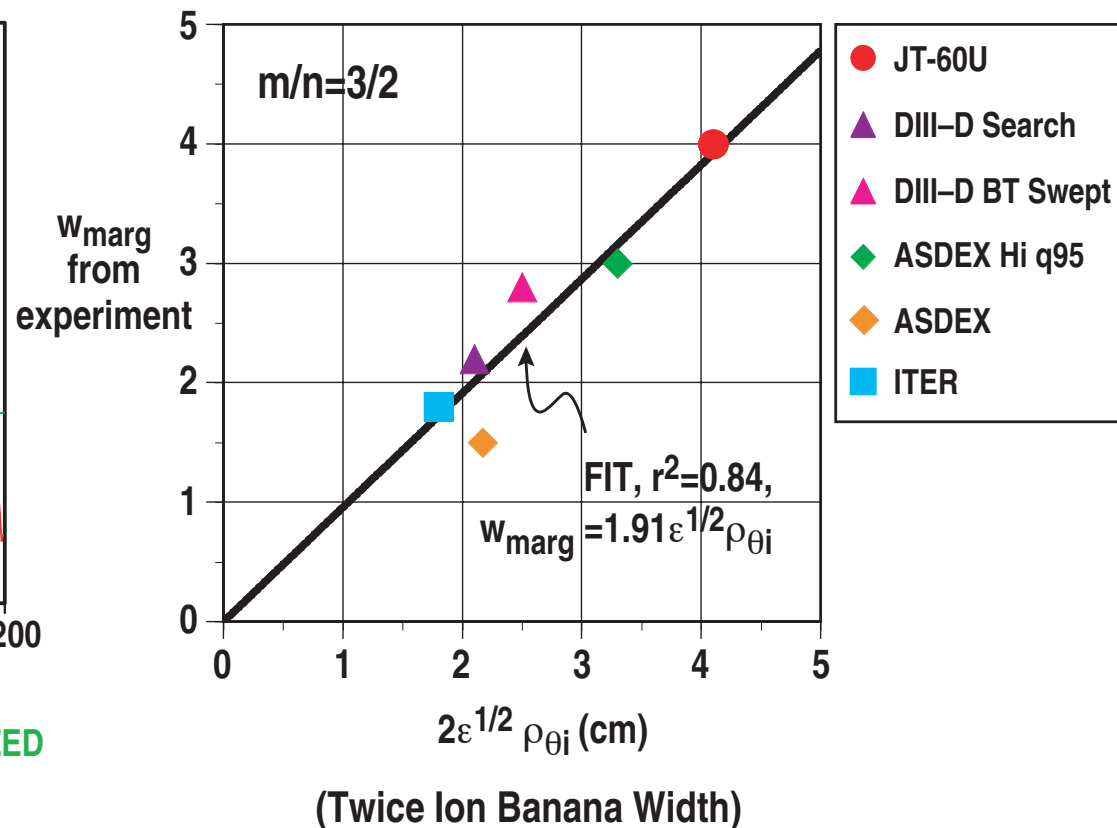
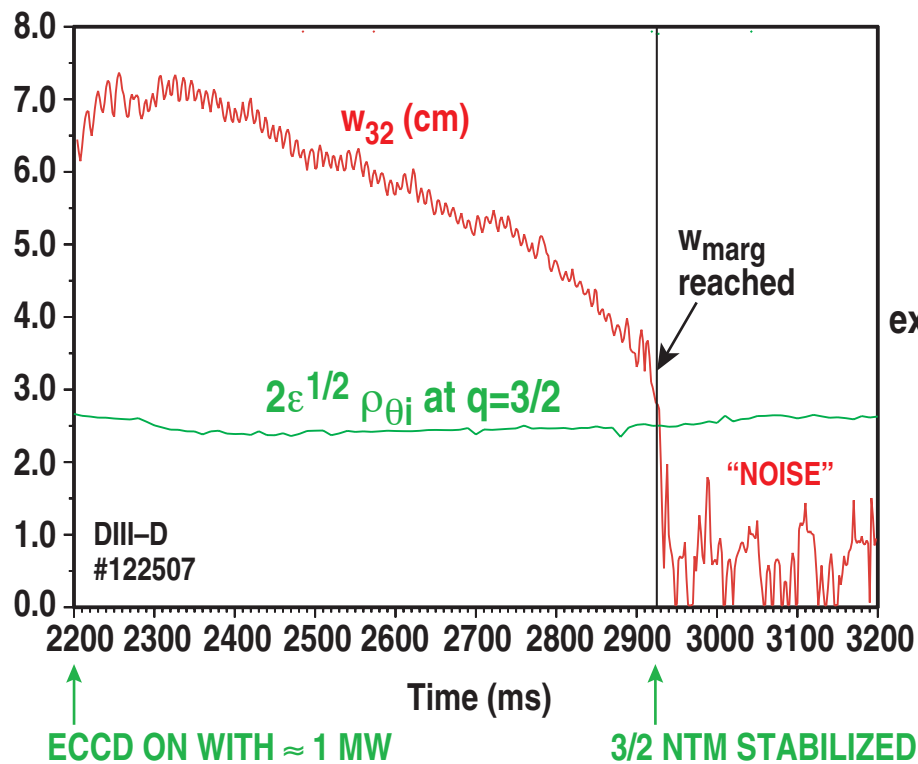


- for $w/\delta_{ec} \ll 1$, modulation is desirable
 - ★ existing devices have $w/\delta_{ec} \geq 1$
 - ★ ITER has relatively small w/δ_{ec} ... front steering advantageous
- modulation has drawbacks
 - ★ $\delta \Delta' r$ halved
 - ★ need to operate at $w \geq w_{marg}$

(Hegna & Callen 97, Zohm 97, Perkins et al, 97)

Experimental Case Studies of ECCD Stabilization of $m/n = 3/2$ Mode Yield the Marginal Condition

- All “suddenly” stabilize when $w \approx 2\varepsilon^{1/2} \rho_{\theta i}$, “marginal” island width
- ★ w_{marg}/r is relatively smaller in ITER



Benchmarking m/n=3/2 NTM Suppression by ECCD Experiments Checks Model for m/n = 2/1 Control in ITER

- Saturated island before/without ECCD

$$\star \frac{a_2}{-\Delta_0' r} = \frac{(w_{\text{sat}}/L_q)}{(j_{\text{bs}}/j_{\text{ll}})} \left[\frac{1}{1 - (w_{\text{marg}}^2/3w_{\text{sat}}^2)} \right]$$

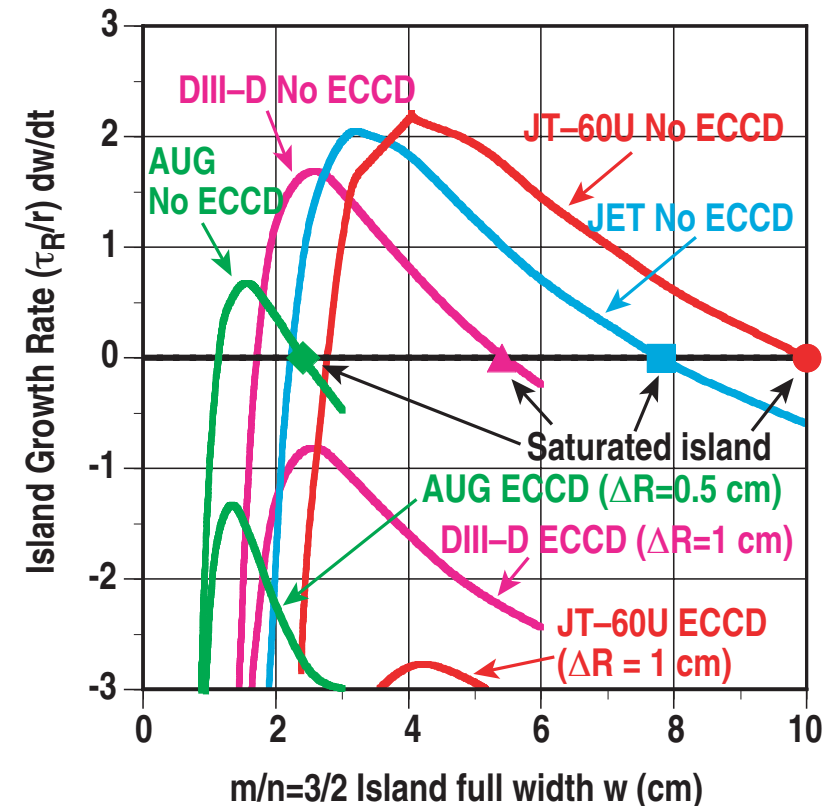
... AUG, DIII-D, JET, JT-60U = 0.8, 1.3, 1.2, 1.0
 — $\langle a_2 \rangle \approx 3.2$ for $\Delta_0' r \approx -3$

- Unmodulated ECCD applied

- ★ 3/2 mode stabilized experimentally
- ... model has no adjustable constants, given a_2 and $\Delta_0' r$
- consistency check for yes/no

See also R. Prater EX/4-2 for m/n=2/1 NTM stabilization in DIII-D

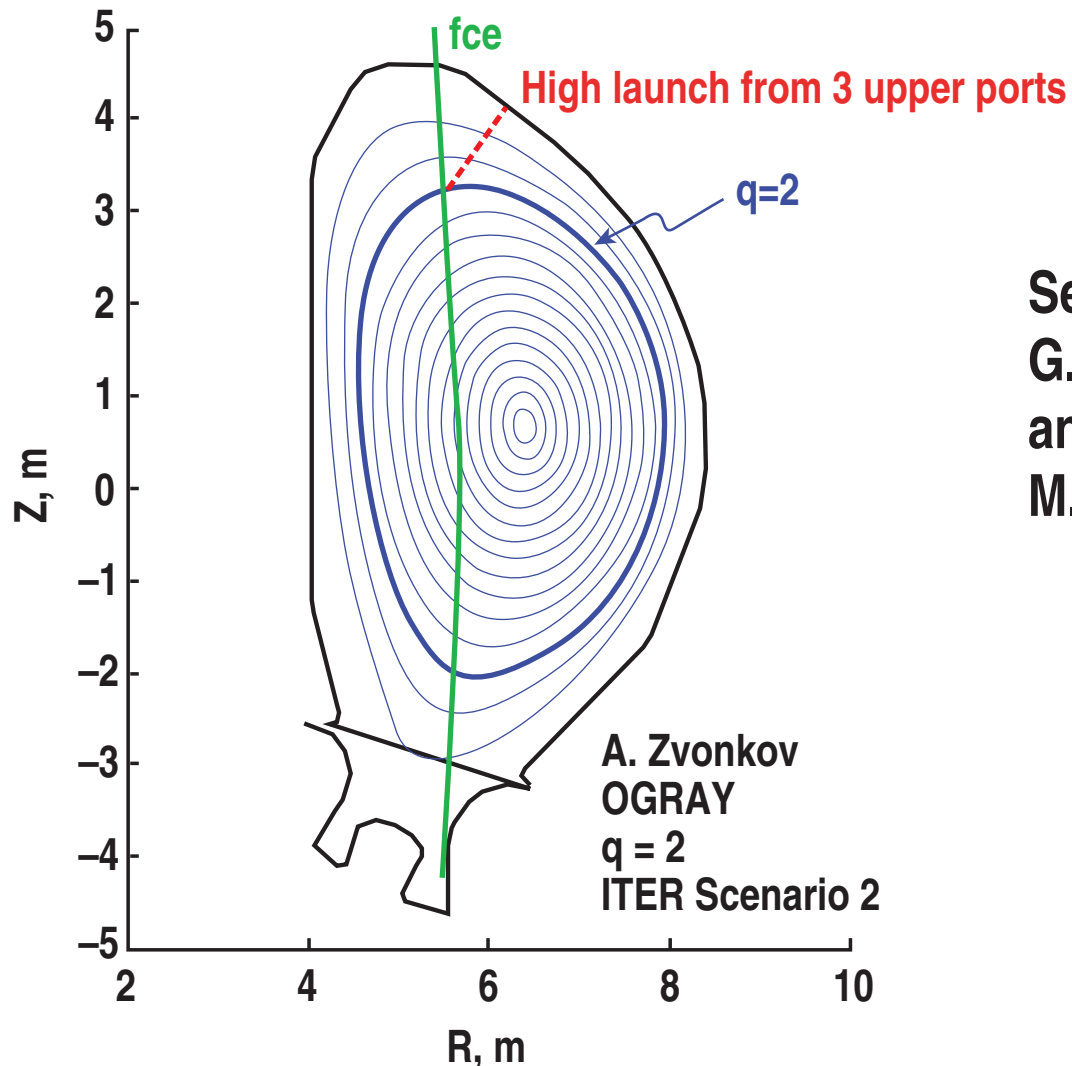
| Device | Shot # | β_N | q_{95} | $j_{\text{ec}}/j_{\text{bs}}$ | $j_{\text{bs}}/j_{\text{ll}}$ |
|--------|--------|-----------|----------|-------------------------------|-------------------------------|
| AUG | 19713 | 2.7 | 3.85 | 3.1 | 0.21 |
| DIII-D | 122507 | 1.9 | 3.5 | 0.9 | 0.15 |
| JET | 47276 | 1.9 | 3.4 | — | 0.14 |
| JT-60U | E41666 | 1.5 | 3.8 | 1.2 | 0.19 |



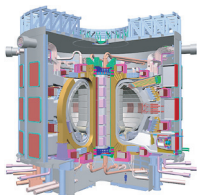
ITER rf Launching Point is Constrained by Shielding

- “High” launch is not best for narrow current drive

★ ITER has $\delta_{eC}/2\varepsilon^{1/2}\rho_{\theta i} \approx 5.4 \gg 1$ (remote steering) or ≈ 1.8 (front steering)
– AUG, DIII-D, JT-60U experiments have 0.4~2



See also
G. Saibene, IT/P2-14
and
M. Henderson, IT/P2-15



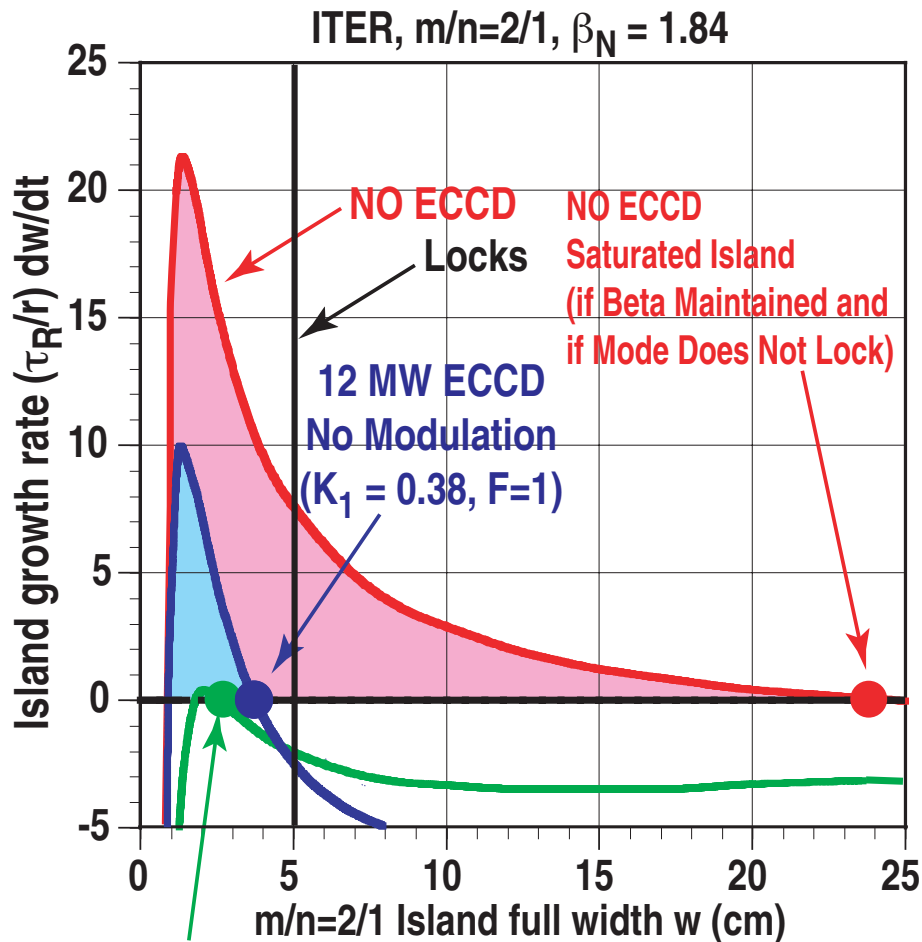
Minimum Necessary Peak ECCD Should Occur by Matching ECCD Width to “Marginal” Island

- **ECCD effectiveness K_1 ($\Delta\rho/\delta_{ec} \equiv 0$)**
 - ★ peaks at $K_1 \approx 1/\sqrt{3}$ at $w/\delta_{ec} \approx \sqrt{3}$ without modulation
... too wide δ_{ec} makes only partial use of rf current
 - ★ peaks at $K_1 \approx 7/8$ at $w/\delta_{ec} \approx 5/4$ with modulation
... insensitive to width δ_{ec}
- **NTM has (with no rf) largest dw/dt at $w_{marg} \approx 2\varepsilon^{1/2} \rho_{\theta i}$**
- **Taken together, $\dot{w} \equiv 0$ and $\partial\dot{w}/\partial w \equiv 0$ for stabilization**
 - ★ \Rightarrow min j_{ec} required at $\delta_{ec} \approx 1/\sqrt{3} \sim 4/5$ of w_{marg}
... should design rf launcher accordingly to minimize rf power
 - favors front steering in ITER over remote steering

Remote Steering ECCD in ITER Can Mitigate the 2/1 NTM

- **No ECCD**

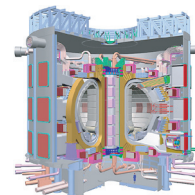
- ★ j_{bs} , $j_{||}$, r , L_q from equilibrium
- $\Delta' r = -2$, $\alpha_2 = 2.8$



12 MW ECCD
50/50 Modulation
($K_1 = 0.74$, $F = 0.5$)

- **With ECCD directed at $q = 2$**

- ★ Wide current drive
 - $\delta_{ec} = 7.5$ cm
 - ... $\delta_{ec}/2\epsilon^{1/2} \rho_{\theta i} = 5.4 \gg 1$
- ★ Adjust modulated j_{ec} (no misalignment)
 - for $w_{sat} \gtrsim 2\epsilon^{1/2} \rho_{\theta i}$ need 12 MW
 - ... $\delta\Delta' r = -2.6$ for $\Delta' r = -4.6$
- ★ Unmodulated less effective
 - but within locking limit



Front Steering ECCD in ITER Requires Less Power

- Again assume no misalignment

★ as in remote steering

- With ECCD directed at $q = 2$

★ Narrow current drive

– $\delta_{ec} = 2.6 \text{ cm}$

... $\delta_{ec}/2\epsilon^{1/2} \rho_{\theta i} = 1.8 \geq 1$

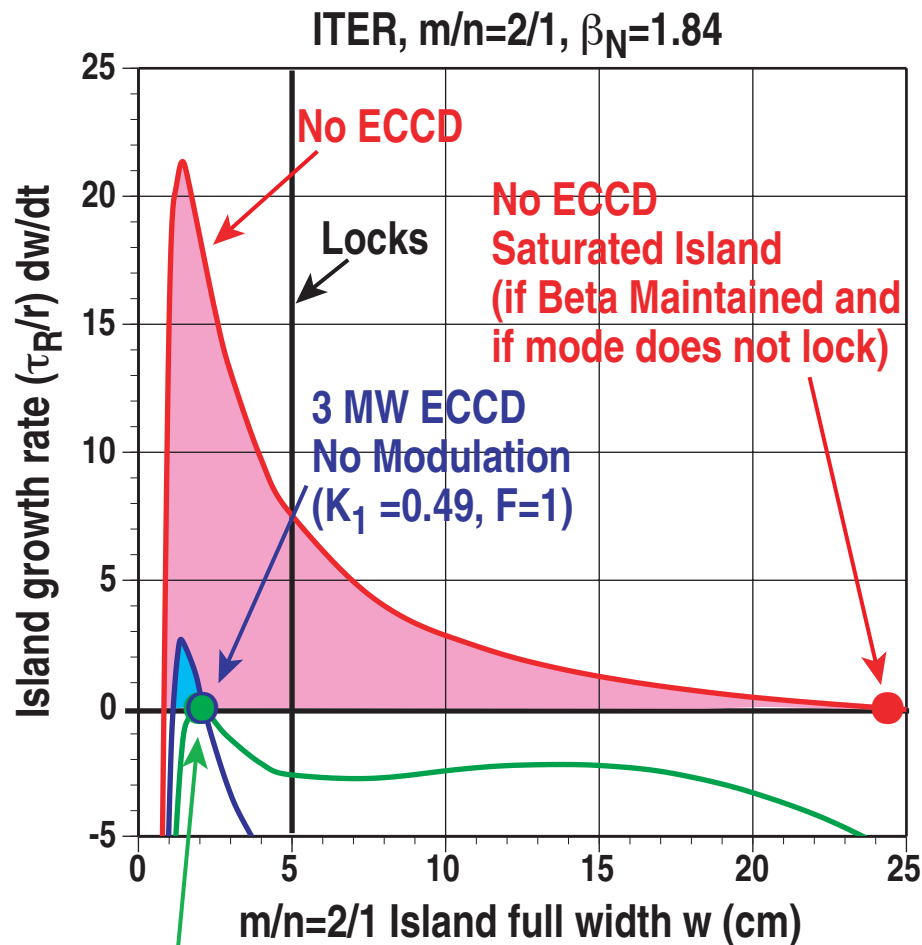
★ Adjust modulated j_{ec}
(no misalignments)

– for $w_{sat} \geq 2\epsilon^{1/2} \rho_{\theta i}$ need 3 MW

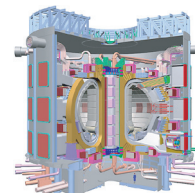
... $\delta\Delta'r = -5.3$ for $\Delta'r = -7.3$

★ Unmodulated as effective

– more margin from 5 cm locking
... than remote steering

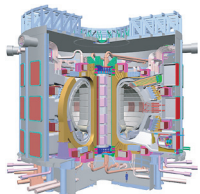
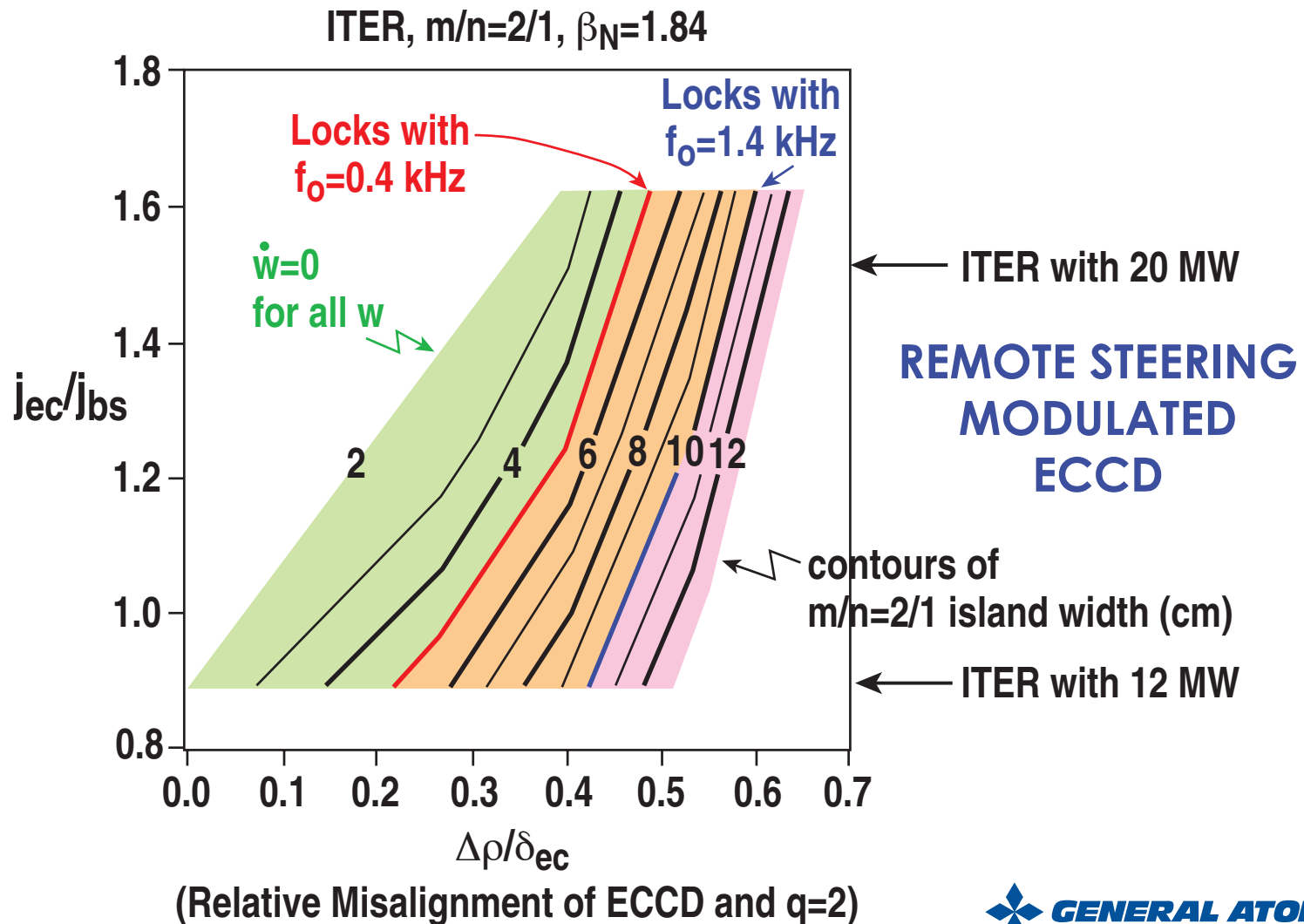


3 MW ECCD
50/50 Modulation
($K_1=0.86, F=0.5$)



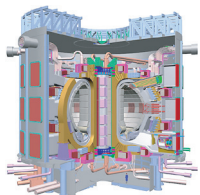
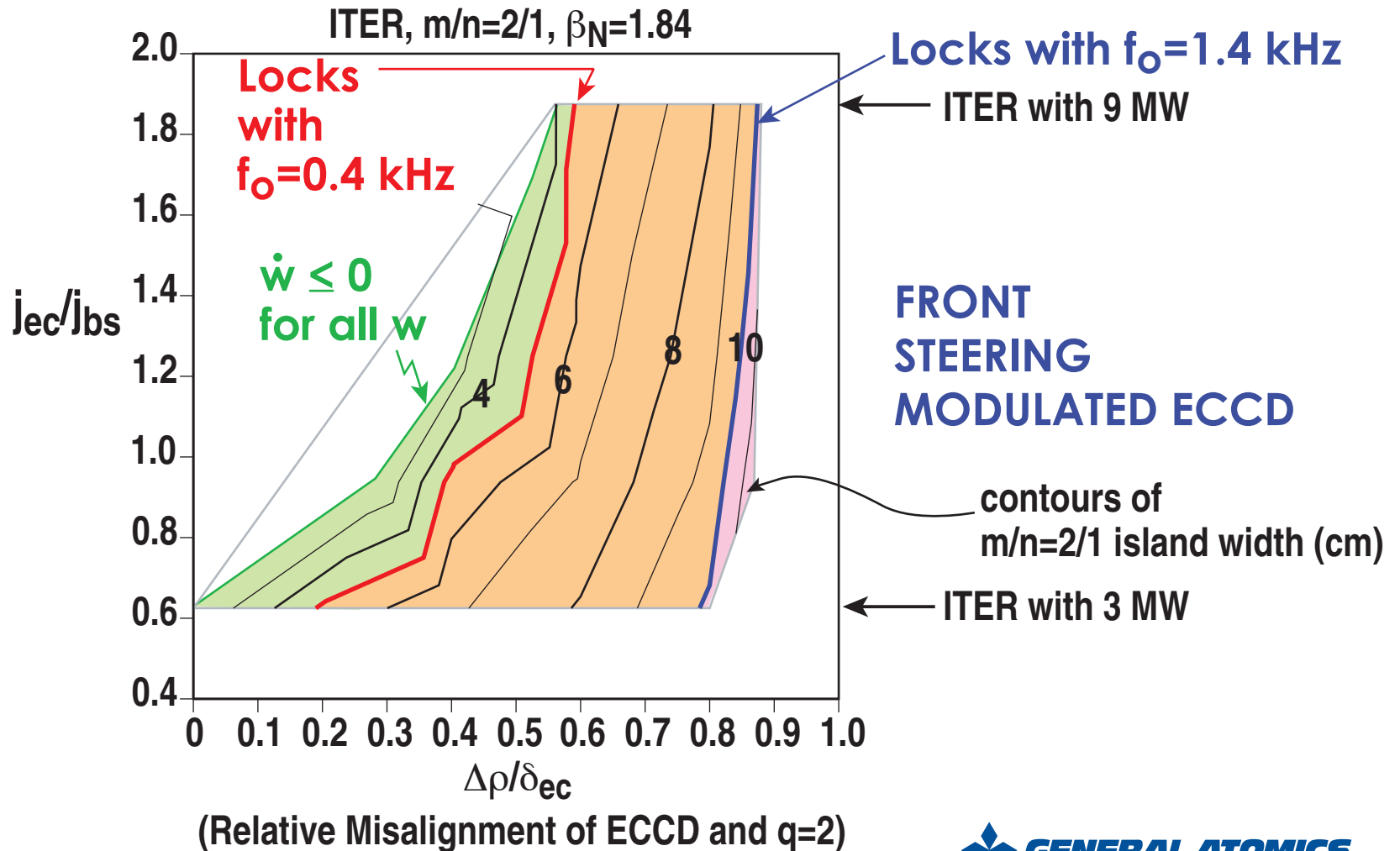
Well-aligned Remote ECCD Can Avoid m/n=2/1 Mode Locking in ITER

- $|\Delta\rho/\delta_{ec}| \lesssim 0.2$, ($|\Delta R| \lesssim 1.5$ cm), is necessary with 12 MW
 - ★ tolerance increases with more EC power and/or more plasma rotation
 - ... little “extra” power for m/n = 3/2 NTM control



Front Steering ECCD Requires Less Power for Avoiding m/n=2/1 Mode Locking in ITER

- But $|\Delta\rho/\delta_{ec}| \leq 0.2$ is a very difficult $|\Delta R| \leq 0.5$ cm with 3 MW
 - ★ tolerance increases to $|\Delta R| \leq 1.5$ cm with ≈ 7 MW
 - ... leaving $20-7 \approx 13$ MW for m/n=3/2 NTM control



Conclusions for ITER NTM Stabilization by ECCD

- **Proposed 20 MW injected, 170 GHz, “high launch” system**
 - ★ adequate to avoid mode locking of the 2/1 NTM
 - ... front steering favored as narrower, needs less EC power
 - but tolerance on misalignment is tighter
- **More plasma rotation would expand the stable operational space**
- **Existing devices need to confirm the advantage of modulation**
 - ★ ASDEX Upgrade (this conference) and DIII-D (2007 planned)
 - ... see also A. Isayama to rapp. H. Zohm, EX/4-1Rb

