

Error Field Measurement Techniques for ITER using Plasma Response

by
E.J. Strait

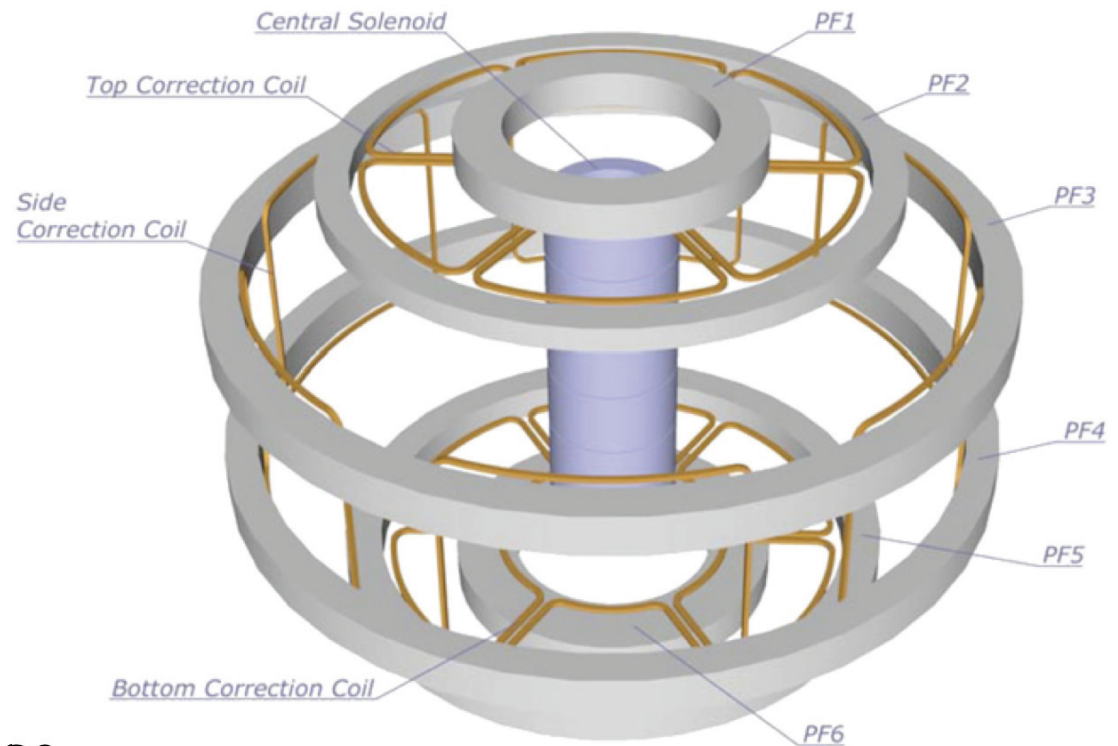
with
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**Presented at the
52nd Annual Meeting of the
APS Division of Plasma Physics
Chicago, Illinois**

November 8-12, 2010

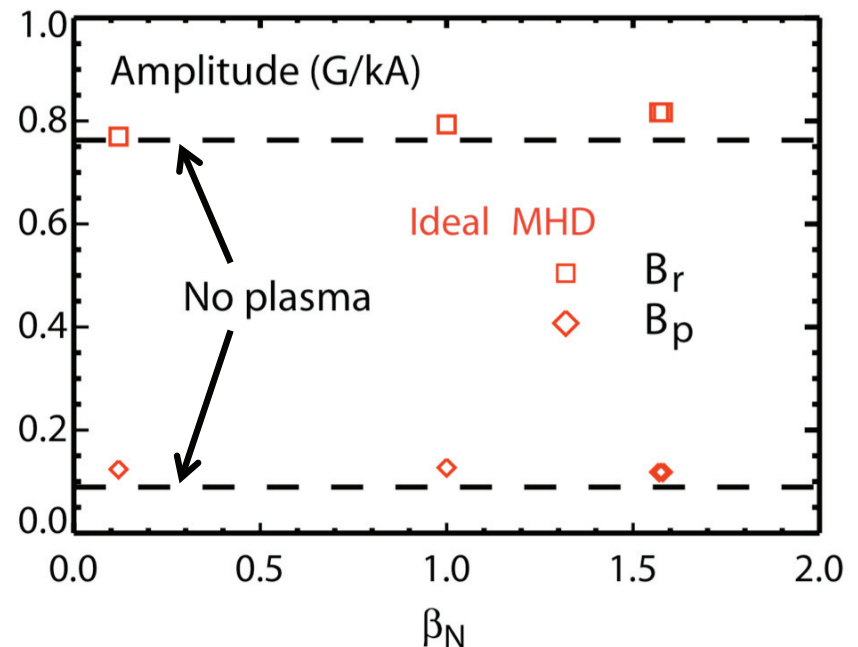


Introduction

- **Error field measurement and correction will be essential in the early operation of ITER**
 - Avoid locked modes and disruptions
 - Optimize error correction during operation with reduced parameters
- **Error field sources are difficult to predict or measure directly**
 - Displaced coils, induced currents, ferromagnetic materials, ...
- **Plasma is a very sensitive error field detector**
- **We consider plasma-based approaches to error field measurement and correction in low- β plasmas**
 - Nonlinear magnetic plasma response
 - Braking of plasma rotation

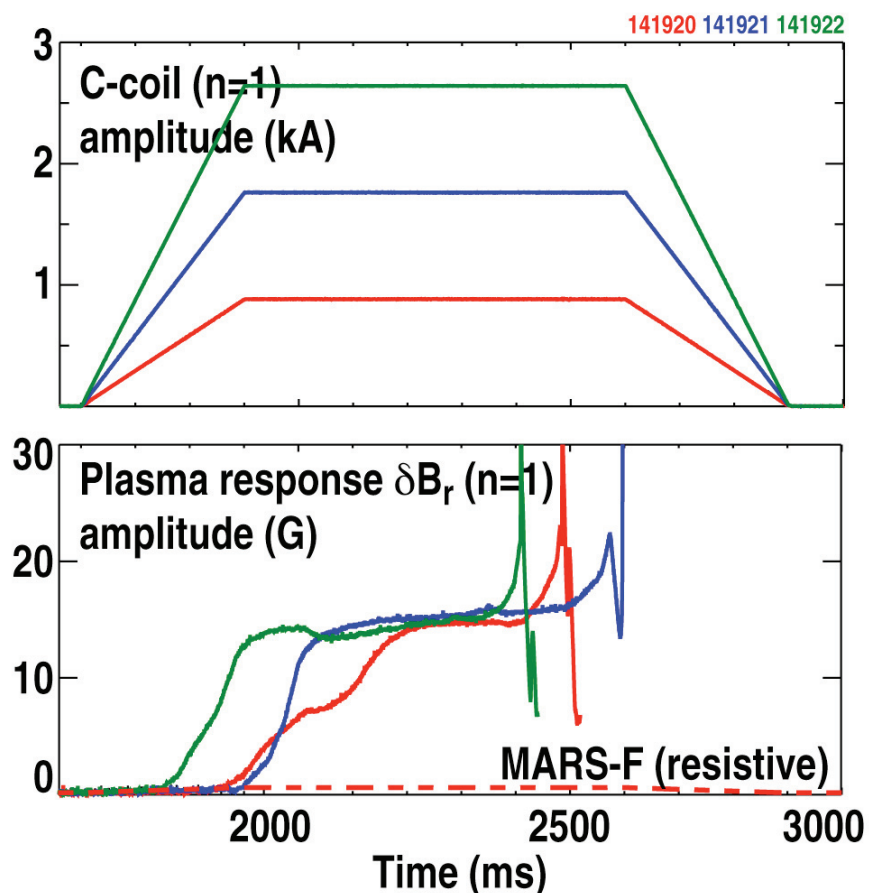
Linear Ideal MHD Plasma Response is Unlikely to be Useful in Early ITER Operation

- Plasma “amplification” of error fields is used in existing tokamaks at high β
 - Can provide input for feedback control of error fields
- Ideal MHD plasma response is small in ITER baseline scenario
 - MARS-F study, based on CORSICA simulation of Scenario 2
 - Applied $n=1$ field from side EFC coil
 - Plasma response \ll applied field



Strong Non-linear, Resistive Plasma Response can be Used in Low- β Plasmas

- Response to an increasing $n=1$ “error field”



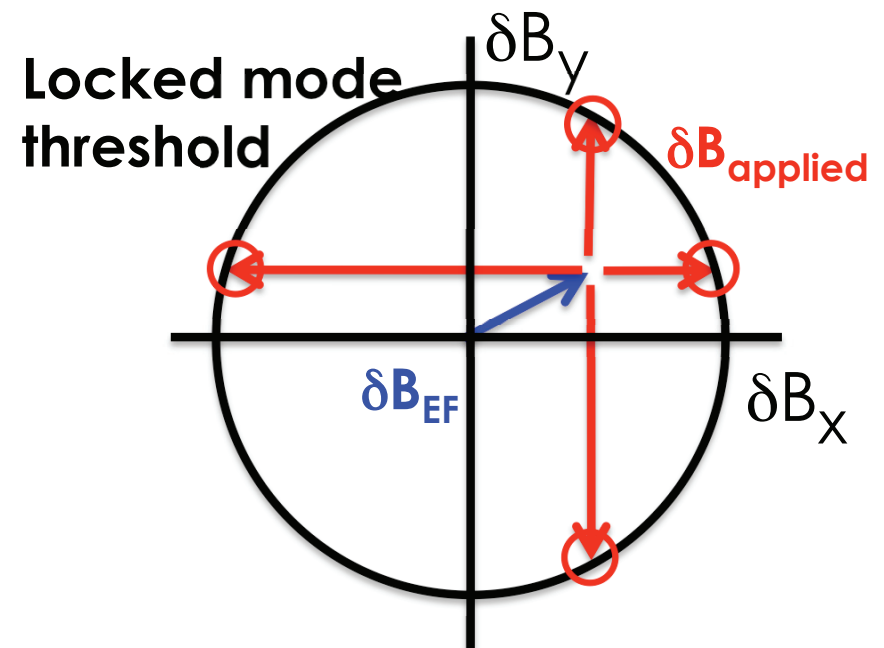
- **Locked mode response:**
 - Penetration of applied field, island growth, and saturation
 - Not described by linear model
- **Saturated amplitude is**
 - Independent of applied field
 - Much larger than linear resistive prediction (MARS-F)

→ Single-mode error correction

- Correct the component that drives the least stable mode
- **Error and correction fields are described by a 2-D phasor**
 - Amplitude and toroidal phase

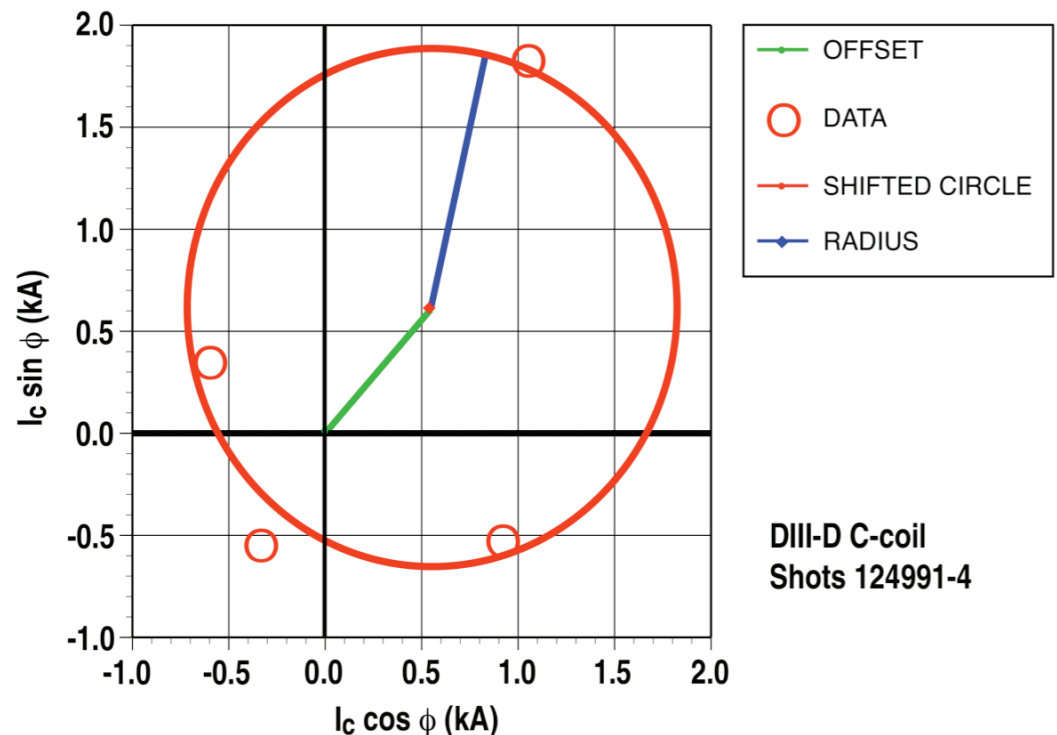
Locked Mode Onset is a Standard Approach to Low- β Error Field Correction in Existing Tokamaks

- **Locked mode threshold forms a circle in the complex plane**
 - Depends on $|\delta\mathbf{B}_{\text{ext}}| = |\delta\mathbf{B}_{\text{EF}} + \delta\mathbf{B}_{\text{applied}}|$, independent of toroidal phase
- **Ramp an applied $n=1$ field in 4 quadrants, to find the threshold**
- **Offset of the fitted circle yields the “intrinsic” error field**



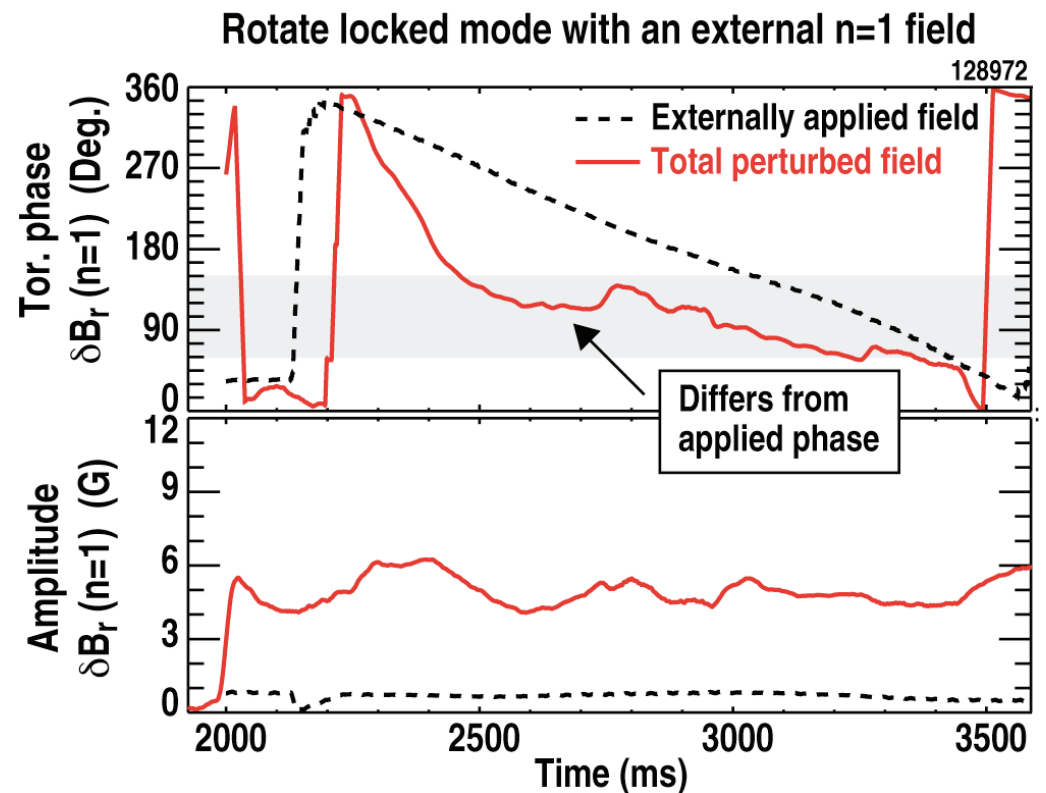
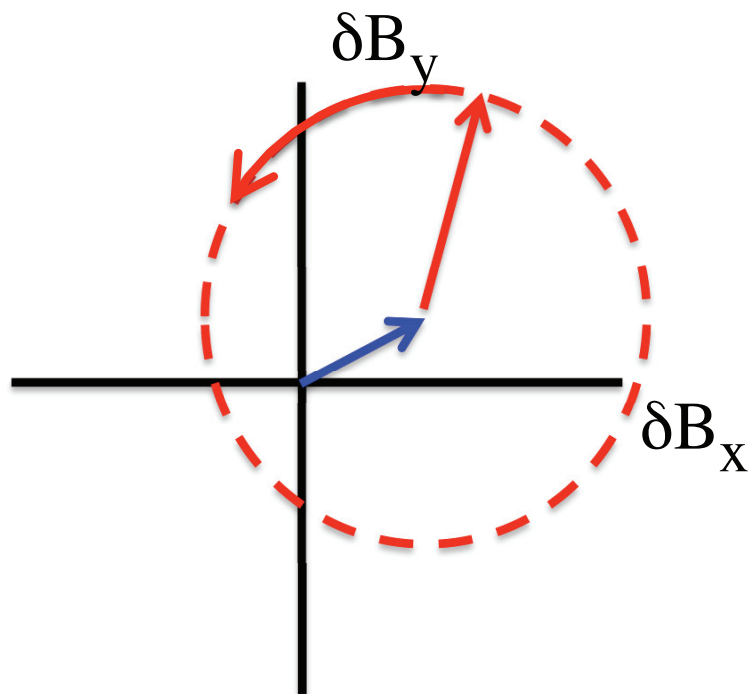
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- **Ramp an applied $n=1$ field in 4 quadrants, to find the threshold**
- **Offset of the fitted circle yields the “intrinsic” error field**
 - Standard method for DIII-D
- **Drawbacks for ITER:**
 - Time-consuming: requires several shots for one case
 - Not suitable for real-time control



Toroidal Phase of a Saturated Island Yields Error Field Measurement

- Rotate the toroidal phase of an externally applied $n=1$ field
 - Island phase depends on total external field $\delta\mathbf{B}_{\text{ext}} = \delta\mathbf{B}_{\text{EF}} + \delta\mathbf{B}_{\text{applied}}$
- Measured island phase shows a preferred direction

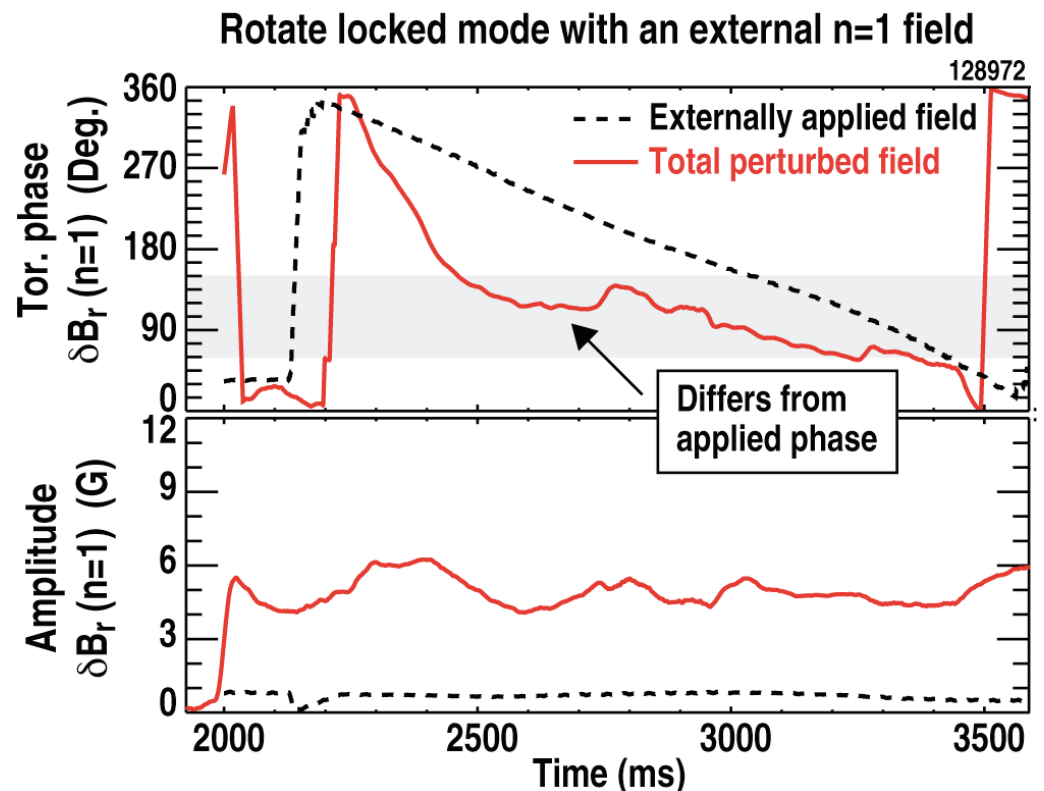


F. Volpe, et al., Phys. Plasmas 16, 102502 (2009).

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- **Measured island phase shows a preferred direction**
 - Analysis yields $\delta\mathbf{B}_{\text{EF}}$
- **Advantages for ITER:**
 - Continuous data
- **Drawbacks for ITER:**
 - Large island (high q_{95} can minimize risk of disruption)

Relation of mode phase to external field is still a subject of research



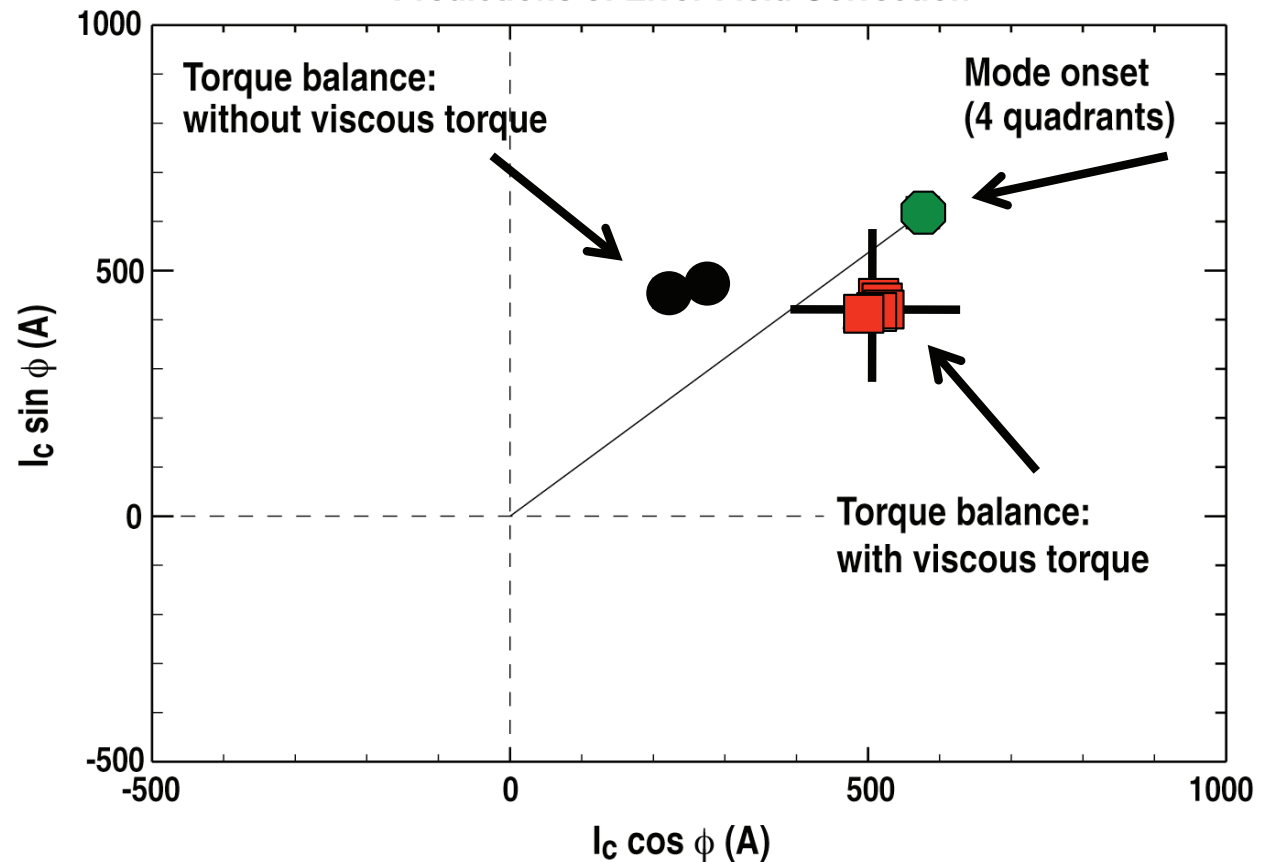
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Torque Balance Model for Saturated Island Gives Reasonable Results

$$\underbrace{K_{EM} (I_{EF} + I_{COIL}) \times B_m}_{\text{Electromagnetic torque}} + \underbrace{K_V |B_m|^\alpha}_{\text{Viscous torque}} = 0$$

Electromagnetic torque Viscous torque

Predictions of Error Field Correction



- Inclusion of viscous torque term yields:

- Better fit to data
- Consistency with mode-onset method

Braking of Plasma Rotation May be Suitable for Real-time Error Field Correction Without an Island

- **Apply n=1 field with rotating phase**
 - Observe modulation of plasma rotation
- **Solve equation of motion to obtain $\delta\mathbf{B}_{EF}$:**

$$\frac{dL}{dt} = T_{NBI} - \frac{L}{\tau_L} - K \left| \delta\mathbf{B}_{EF} + \delta\mathbf{B}_{applied} \right|^2$$

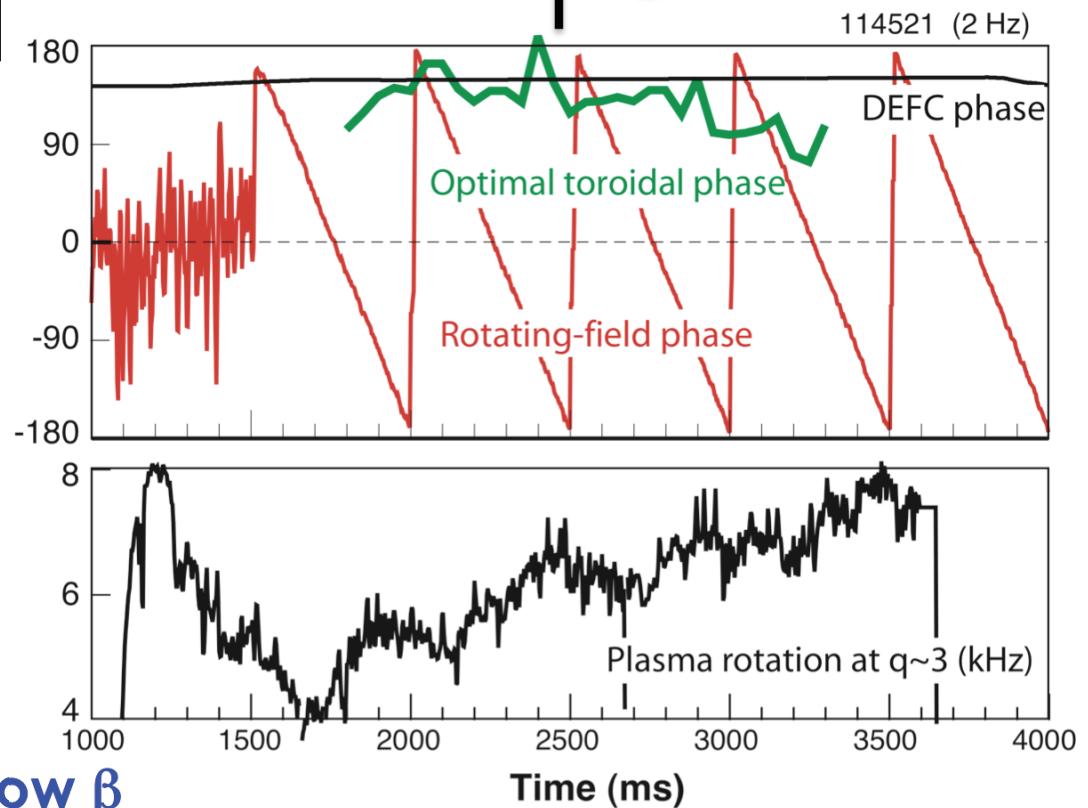
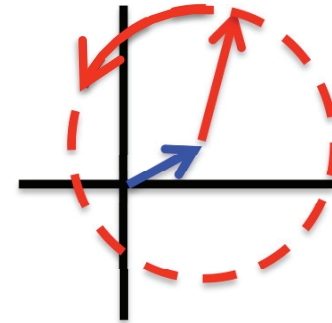
- Consistent with feedback controlled error correction

- **Advantages for ITER:**

- Continuous data
- No instabilities

- **Drawbacks for ITER:**

- Requires NBI torque
- Long integration time

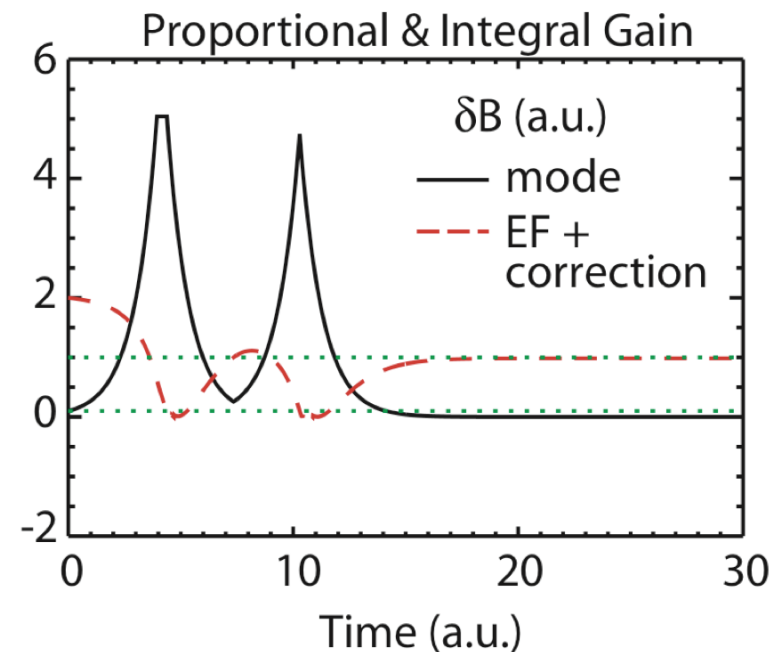
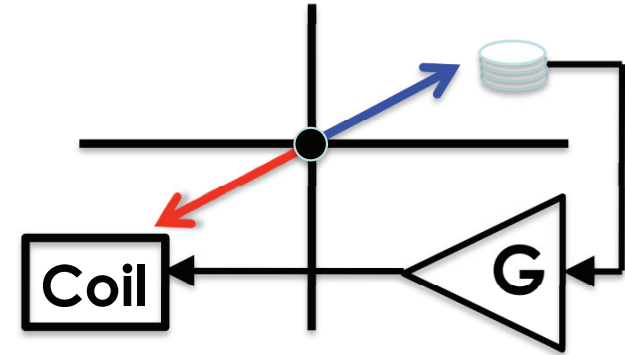


Needs experimental test at low β

Direct Feedback Control of Locked Mode May Allow Error Field Correction

- Simple model suggests that direct feedback control may be feasible
- Nonlinear, two-state model for locked mode island:
 - Locked/Growing or Unlocked/Decaying
 - Two thresholds: δB (Unlock) \ll δB (Lock)
- **Result: converges to unlocked state**
 - Net error field is nonzero, but below the threshold for locking
 - Requires integral gain
- **Advantages for ITER:**
 - Continuous error field correction
 - Locked mode suppression

Needs experimental test



Several Plasma-response Methods are Candidates for Error Field Measurement and Correction at Low β

Method	Real-time	Island	Experimental Experience	Additional comments
Locked mode onset threshold	No	Transient	Extensive	Time-consuming
Toroidal phase of saturated island	Yes	Saturated	Limited	
Magnetic braking of plasma rotation	Yes (slow)	Stable	Limited	Requires NBI torque
Direct feedback control of locked mode	Yes	Suppressed	None	