# Locked Neoclassical Tearing Mode Control on DIII-D by Electron Cyclotron Current Drive and Magnetic Perturbations

Cyclotron

By Francesco Volpe

With

R.J. La Haye, R. Prater, E.J. Strait

Presented at
Forty-Ninth APS Meeting of
the Division of Plasma Physics
Orlando, Florida

harmonics

Vessel

q=2

surface

I-coil

Poloidal Field
Sensor

November 12–16, 2007

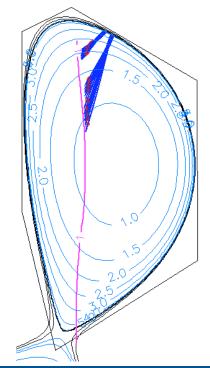


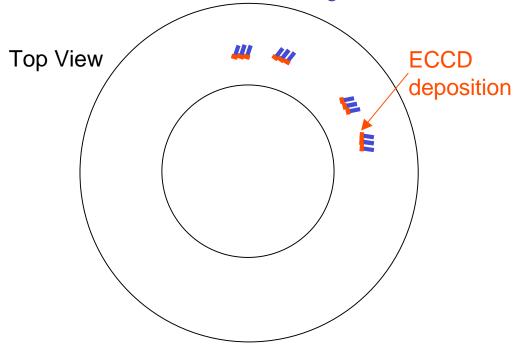


### Motivation

- Locking of 2/1 Tearing Mode very likely in ITER (due to reduced NBI torque and consequent low rotation)
- Locking is a recurrent cause of disruptions
- ECCD suppresses rotating NTMs
- However, island can lock in a position not accessible by ECCD:

Poloidal section



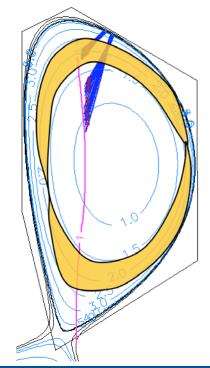


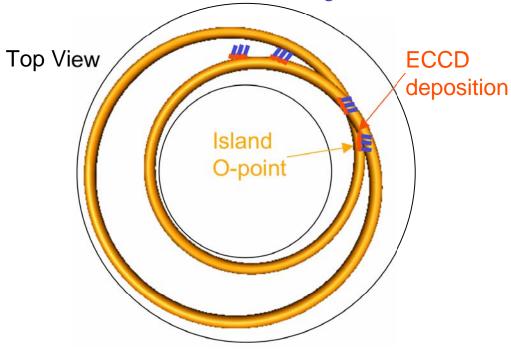


### Motivation

- Locking of 2/1 Tearing Mode very likely in ITER (due to reduced NBI torque and consequent low rotation)
- Locking is a recurrent cause of disruptions
- ECCD suppresses rotating NTMs
- However, island can lock in a position not accessible by ECCD:

Poloidal section



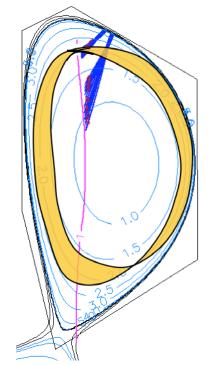


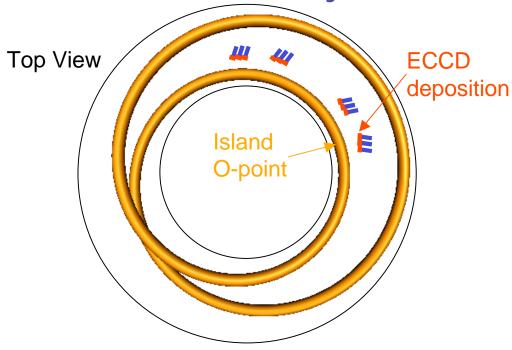


### Motivation

- Locking of 2/1 Tearing Mode very likely in ITER (due to reduced NBI torque and consequent low rotation)
- Locking is a recurrent cause of disruptions
- ECCD suppresses rotating NTMs
- However, island can lock in a position not accessible by ECCD:

Poloidal section







### Magnetic Perturbations Can <u>Unlock</u> and <u>Reposition</u> or <u>Spin</u> the Mode and So Assist Its ECCD Control

Bootstrap deficit → island ≅ wire carrying ctr-current → wire can be moved by external B

#### Approach 1 ("preferential locking"):

Island is dragged into a new position accessible by gyrotrons.

**ECCD: CW** 

#### Approach 2 ("sustained rotation" or "entrainment"):

Externally applied rotating B unlocks the mode and forces it to rotate.

**ECCD:** CW or modulated

Both Approaches can also be applied pre-emptively, for Locked Mode Avoidance



# Magnetic Measurements Detect Locked Mode or Imminent Locking and Trigger Response

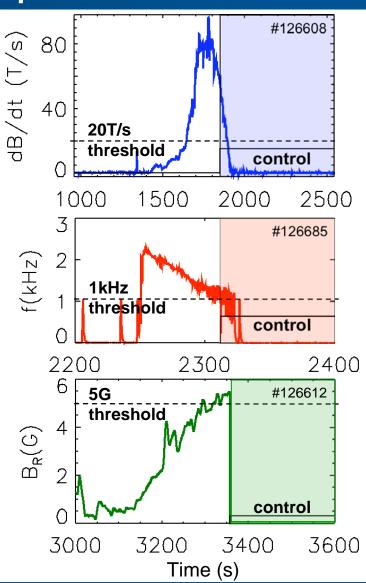
Mirnov Coils (poloidal field sensors) measure mode amplitude at >100Hz

Mirnov Coils+Frequency Counter measure angular frequency of mode, detect slowing down

Saddle loops (radial field sensors)

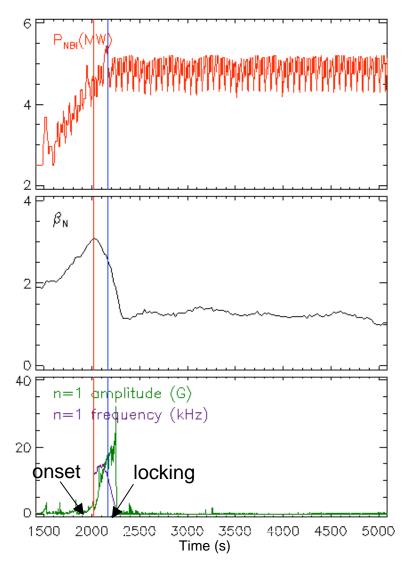
measure mode amplitude at <100Hz.

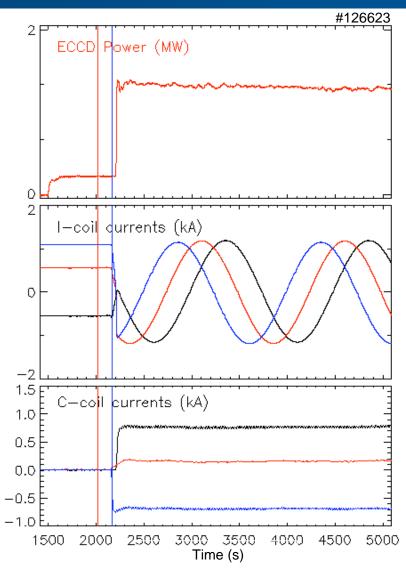
Suitable for "born locked" modes





## Slowly Rotating Field Used to Drag Plasma and Toroidally Align Island to ECCD





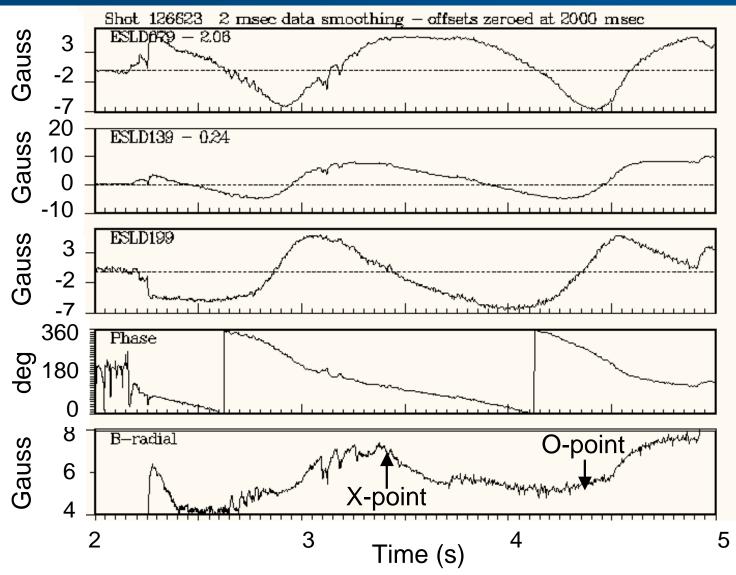


# The Island, Rotated by Magnetic Perturbations and Illuminated by ECCD, Changes Amplitude

B<sub>R</sub> as measured by pairs of Saddle Loops in 3 different toroidal locations

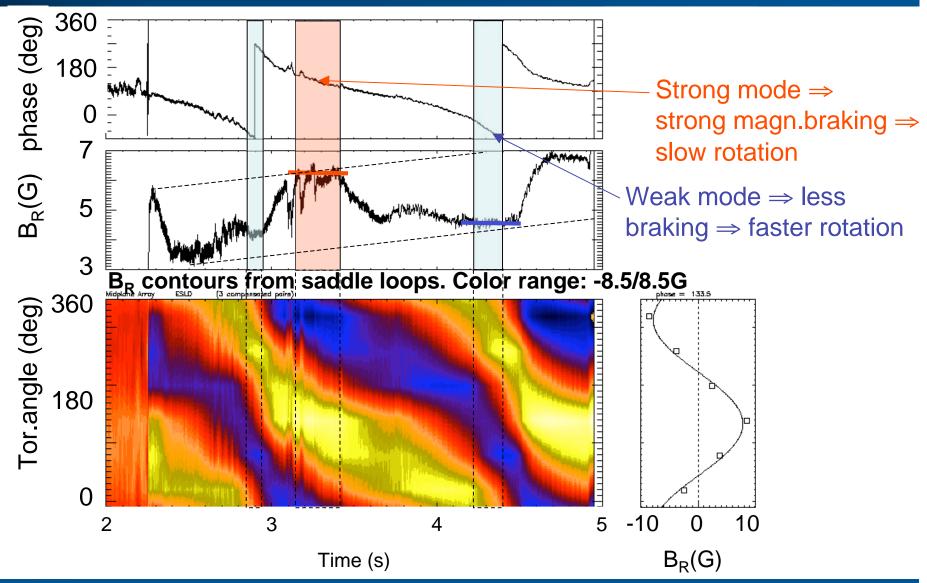
n=1 toroidal phase

n=1 "absolute" amplitude of island varies  $B_R$ =4-7.5G



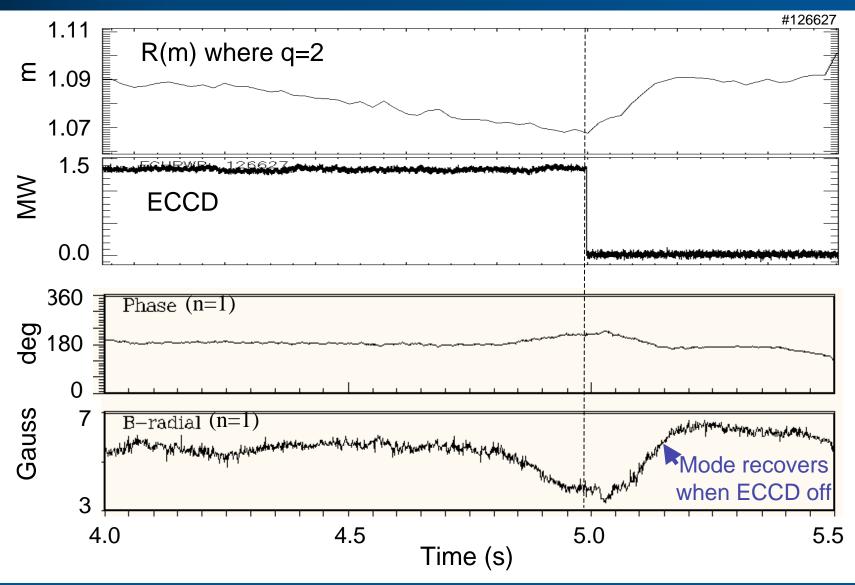


### Subtraction of Vacuum Field Confirms That Locked Mode Changes Amplitude When Toroidally Steered in Presence of ECCD



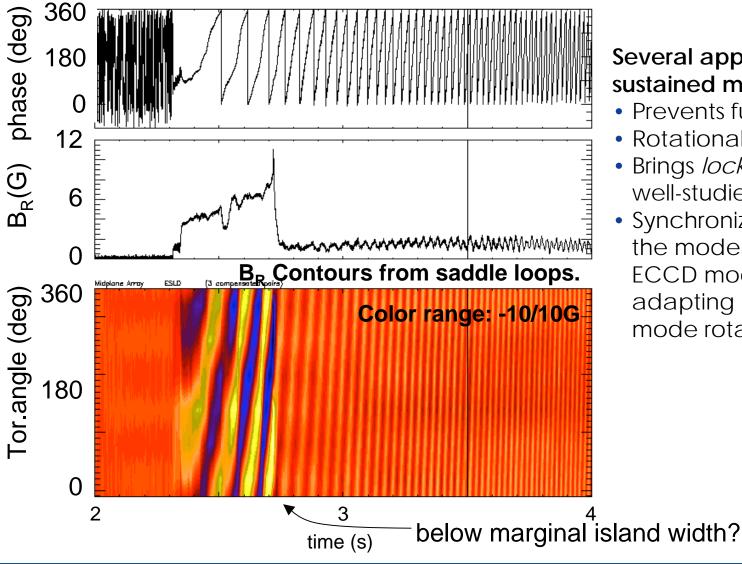


## Radial Jog of Plasma at Fixed Optimum Phase for O-Point: Mode Amplitude Decreases With ECCD Aligned, Increases When ECCD is off





### **Proof of Principle of Fast Sustained Rotation** No ECCD Yet



#### Several applications of sustained mode rotation:

- Prevents further locking
- Rotational mitigation
- Brings locked mode case in well-studied rotating NTM case
- Synchronizes and phase-locks the mode rotation to the ECCD modulation. Easier than adapting ECCD to natural mode rotation



### **Summary and Conclusions**

- Demonstrated "Preferential Locking" of NTM to a (static) toroidal phase such that it can be accessed by ECCD for stabilization
- Optimal toroidal phase was found by slowly steering the mode (0.66Hz) while applying cw ECCD
- ECCD radially aligned to locked island as to rotating ones
- Reduction of mode amplitude from 6 to 3G with 1.2MW ECCD
  - Future work: more power and good alignment for t>400ms
- Sustained Mode Rotation up to 60Hz by means of I-coil travelling wave
- Travelling wave needs to be applied gently (0-60Hz ramp in 1s)
  - Future work: add ECCD, modulated at frequency and phase of applied rotation

