Continuum Gyrokinetic code simulations in a noncyclic finite-width radial annulus

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Introduction and Motivation

- Gyrokinetic code GYRO to contains all physics of low frequency (<< ion cyclotron) plasma turbulence assuming only that the ion gyroradius is less than magnetic field gradient length</p>
 - Nonlinear
 - Electromagnetic and finite β
 - Real tokamak geometry
- Continuum (fluid-like) methods in 5-dimensional space (r, θ , n, ϵ , λ)
 - Possible advantage over particle codes: implicit advance of electron parallel motion
- 3-modes of operation:
 - flux-tube or high-n ballooning mode representation BMR $\Delta n=5-10 \rho^* \rightarrow 0$ to be bench-marked with Dorland 's new gyrokinetic flux tude code GS2
 - wedge or full radius Δn =5-10 ρ^* small but finite
 - full torus $\Delta n=1$ Global MHD modes
- Why full radius? Shear in the ExB velocity known to have a powerful stabilizing effect. But shear in the diamagnetic velocity can be just as large and cannot be treated at ρ* = 0. Also to quantify *avalanches* and *action at a distance* effects



Some fundamentals about flux tube codes

- "Flux tube" codes follow a field line to make (Δr , $r\Delta \theta$, $R\Delta \phi$) covers of a radial (r, θ) annulus and have cyclic radial boundary conditions
- $\Delta r \ X \ r \Delta \theta$ is typically 100 $\rho_s \ X \ 100 \rho_s$ but ρ_s is vanishingly small.

Since $ky\rho_s = (nq/r)\rho_s$ is finite (say .05 to 0.9), the toroidal mode numbers n are arbitrarily large.

• Although, $1/LT = -d \ln T/dr$ is finite, the variation of $T = \Delta r/LT$ or any other plasma variable is insignificant, i.e. there are no profile (shear) variation effects.

...only magnetic shear s^=d ln q (r)/d ln r

- Because of there are no variation of coefficients and we have cyclic BC, most flux tube code have a radial Fourier transform space: $r_m = r_0 + x_m$ grid is replaced with a $k_x = -i d/dr$ grid. For finite s^, this is called the Ballooning Mode Representation
- Because we want to study general profile variation, not just ExB velocity shear, but diamagnetic velocity shear at finite ρ_s/r , in a finite Δr annulus with noncyclic radial BC, we are developing a code GYRO with a radial grid.

___The 1D linear modes (for a given n,k_x) became 2D modes (for a given n) : much more difficult

• In our first stage (where we are now), the profile variation is turned off and we have cyclic BC to benchmark with the Ballooning Mode code GS2 with a kx grid

_This talk is a progress report on the first stage



The next stage: non-cyclic BC finite radial annulus at finite ρ s

• The next stage will operate with non-cyclic BC (e.g. 0 gradient BC) over a finite annulus, say r=0.4 to 0.6 with general profile variation. We don't want 0 BC which allows no in-out flow.

• Since in-flow will not equal out-flow, and the driving temperature gradients will begin to relax, we need a scheme to add a running "incremental" sources to the n = 0 gyrokinetic equation:

$$d[F(r) + \tilde{f}_{0}(r,\theta)/dt + r^{-1}d/dr[r\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)] = r^{-1}d/dr[r\left\langle\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle\right\rangle + r^{-1}d/dr[r\left\langle\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle\right\rangle + r^{-1}d/dr[r\left\langle\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle\right\rangle + r^{-1}d/dr[r\left\langle\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle\right\rangle + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)\right\rangle + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)] + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)] + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)] + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)\tilde{f}_{n}(r,\theta)] + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}(r,\theta)\tilde{f}_{n}(r,\theta)] + r^{-1}d/dr[r\left\langle\sum_{n}\tilde{V}_{ExB}$$

F(r) is the input fixed background Maxwellian, $\tilde{f}_0(r,\theta)$ is the n=0 (zonal flow) perturbation, $\sum_n \tilde{V}_{ExB_x=n}(r,\theta)\tilde{f}_n(r,\theta)$ in the nonlinear term is the x-directed flux, and $r^{-1}d/dr[r\left\langle\left\langle\sum_n \tilde{V}_{ExB_x=n}(r,\theta)\tilde{f}_n(r,\theta)\right\rangle\right\rangle$ is the incremental source.

 $\langle\langle \rangle\rangle$ is local time-local space maxwellized average \Rightarrow defined scale separation

• We hope to approach "full radius" say r=0.3 to 0.7 then r=0.2 to 0.8 as resolution allows: 200-300 r-grid replacing the current 100 r-grid.



Motivation

- To compare a simulation χ's directly with experiment, in addition to the ITG drive, we need trapped electrons, finite-beta (passing electrons), equilibrium scale ExB shear stabilization and finite ρs profile shear effects.
- To treat the finite ρ_s profile shear effects, we need a finite radial annulus without cyclic BC, but still maintaining the input profiles.
- The plan for direct annulus comparison of experiments with a few simulations having truly comprehensive physics (including finite-β and real geometry), is a different strategy from previous work.

Namely, make many runs with limited physics (e.g. ITG only) to normalize transport models with more comprehensive physics, e.g. GLF23



- Poisson's Equation: $-\lambda_{D0}^2 \nabla^2 \hat{\phi} = \sum_s \iint z \left[-(z\hat{n}/\hat{T})\hat{\phi} + \langle g \rangle \right]$, $\langle g \rangle$ is non-adia. gyro-ave. DF
- Ampere's Law: $-\rho_{s0}^2 \nabla^2 \hat{A}_{||} = (\beta_{e0}/2) \sum_s \iint z \hat{v}_{||} \langle \hat{g} \rangle$,

where the phase space integral $\iint \Rightarrow \Sigma_{\sigma} \pi^{-3/2} \int_{0}^{\infty} d\hat{\varepsilon} \hat{\varepsilon}^{1/2} \exp(-\hat{\varepsilon})(\pi/2) \int_{0}^{1/B} d\lambda B/(1-\lambda B).$

• Nonlinear Gyrokinetic Equation [2,3]:

$$\partial_{\hat{t}}\hat{g} + \hat{v}_{\parallel}(\hat{b}\cdot\hat{\nabla}\theta)\partial_{\theta}\hat{g} = z\hat{n}/\hat{T}\partial_{\hat{t}}\langle\hat{U}\rangle \\ -i\omega_{E}(-(z\hat{n}/\hat{T})\langle\hat{U}\rangle + \langle g\rangle) + i\varpi_{D}\hat{g} - i\hat{n}\varpi_{*}\langle\hat{U}\rangle + \left\{\langle\hat{U}\rangle,\hat{g}\right\} - \left\{\hat{g},\langle\hat{U}\rangle\right\} + C\hat{g},$$

where "hat" quantities are normalized, and $U = \hat{\phi} - \hat{v}_{||} \hat{A}_{||}$ is the effective potential.

• The low-n MHD rule of neglecting A_{\perp} while forcing the curvature drift to equal the grad-B drift is very good even for high-n.



• The curvature drift operator which acts only on \hat{g} is

 $\hat{\varpi}_D = -iz\hat{T}(2/R_0)\rho_{s0}(B_0/B)\{C(\theta,\hat{\varepsilon},\lambda) \ [inq/\hat{r}] + S(\theta,\varepsilon,\lambda) \ [i(nq/\hat{r})\eta_k + (|\nabla r|/\eta_q)D_{\hat{r}}]\}.$

where C is the cosine-like normal curvature, S the sine-like geodesic curvature [1]

• The diamagnetic term is $\varpi_* = -i(B_0/B_{unit})\rho_{s0}[inq/\hat{r}][1/\hat{L}_n+1/\hat{L}_T(\hat{\epsilon}-3/2)].$

• The E×B equilibrium rotation frequency is $\hat{\omega}_E = -i(B_0 / B_{unit}) \partial_{\hat{r}} \hat{\Phi}_0 \rho_{s0} [inq / \hat{r}]$.

• The nonlinear term $\{X,Y\} = \sum_{n',n''=n-n'} (B_0 / B_{unit}) \rho_{s0} [in''q/\hat{r}] X_{n''} [\partial_r + i(n'q/\hat{r})\eta_k \eta_q / |\nabla r|] Y_{n'}$

_parallel nonlinearity $O(\rho^*)$ not shown

• We define $[inq/\hat{r}] \equiv inq/\hat{r} + (B_t/B)(\hat{R}q/\hat{r})(\hat{b}\cdot\hat{\nabla}\theta)\partial_{\theta}$. $B_{unit} = B_0\rho d\rho/rdr$

The nq/r terms are *fast* and the ∂_{θ} terms are *slow*. where again we use Dr when ∂_{r} acts on g.

• C is the pitch angle scattering operator.



Field Line Following Coordinate System most efficient

- (r, θ , α) r = midplane minor radius flux surface label
 - θ = poloidal angle labeling Miller's local MHD equilibrium^[1]

which generalizes infinite aspect ratio circular s- α model with finite aspect ratio, Shafranov shift, ellipticity, and triangularity

 $\alpha = \zeta - \int_{0}^{\theta} \hat{q} d\theta$ field aligned angle in place of toroidal angle ζ

$$\hat{q} = \hat{b} \cdot \nabla \zeta / \hat{b} \cdot \nabla \theta, \ \hat{b} \cdot \nabla \alpha = 0, \ \hat{b} \cdot \nabla r = 0, \ q = \int_0^{2\pi} \hat{q} d\theta / 2\pi$$

- Fourier decomposition of perturbations: $\phi = \sum_n \phi_n(r, \theta) \exp(-in\alpha)$ requires $\phi_n(r, \pi) = \phi_n(r, -\pi) \exp(-in2\pi q)$ where *phase factor* $\exp(-in2\pi q)$ is 1 at singular surfaces
- parallel derivative $\nabla_{\parallel} = (\hat{b} \cdot \nabla \theta) \partial_{\theta} \Longrightarrow (1/Rq) \partial_{\theta}$
- perpendicular derivatives on *fast* part : $exp(-in\alpha)$

• additional *slow* derivatives on $\phi_n(r,\theta)$: $\nabla^S_{\perp y} = (B_t / B_p)(\hat{b} \cdot \nabla \theta)\partial_{\theta}$ radial derivative is a mixture of *fast* and *slow*: $\nabla^{fs}_{\perp x} = |\nabla r|\partial_r$ $|\nabla r| \Rightarrow 1$

Ballooning Mode Representation(BMR) retains only the fast not slow $O(\rho^*)$ derivatives



Normalizing Units, Parameters, and Gyro-Average

• Te(0) and ne(0) for temperature and density a = r of last closed flux surface for length $c_{s0} = [T_e(0)/M_i]^{1/2}$ for velocity a/c_{s0} for time $|e|\phi/T_e(0) = \hat{\phi}$ and $(c_{s0}/c)|e|A/T_{e0} = \hat{A}$ for potentials

•
$$g = \hat{g}(r, \theta, \hat{\varepsilon}, \lambda, \sigma)n_e(0)F_M$$
 for non-adiabatic distribution function
 $\hat{\varepsilon} = \varepsilon/T, \lambda = \mu/\varepsilon, \sigma = \operatorname{sgn}(v_{\parallel})$ and since (ε, μ) are the constants of motion
 $\partial_r \hat{g} = n_e(0)F_M D_r \hat{g}$ where $D_r \hat{g} = \partial_r \hat{g} + \partial_r \lambda \partial_\lambda + (\hat{\varepsilon}/L_T)\partial_{\hat{\varepsilon}} \hat{g} - [(\hat{\varepsilon} - 3/2)/L_T]\hat{g}$
Note all terms beyond $\partial_r \hat{g}$ are small $O(\rho^*)$ dropped in BMR limit.

- Parameters: the central $\rho_{s0} = c_{s0} / (eB_0 / M_i c)$], Debye length λ_{D0} , and electron beta β_{e0} .
- The gyro average $\langle \phi \rangle = \sum_n \exp(-in\alpha) \langle \phi \rangle_n$ expand the arguments of $\langle \phi \rangle_n$ to first order ρ_{\perp} / r , so that $\langle \phi \rangle_n = \oint d\alpha_g / 2\pi \exp(-in\overline{\rho}_{\perp} \cdot \nabla \alpha) \phi_n (r + \overline{\rho}_{\perp} \cdot \nabla r, \theta + \overline{\rho}_{\perp} \cdot \nabla \theta)$.

As a first approximation the *slow* $\overline{\rho}_{\perp} \cdot \nabla \theta$ can be neglected.



Numerical Methods

- Electron parallel motion term is much faster than drift frequencies we are trying to follow, hence need an implicit method which solves for the fields U simultaneously with the advance of g
- We use a split time step method: g1 = g0 + dt * RHS1, g2=g1+RHS2,
- $\epsilon, \lambda, \theta$ -parallel process
 - Nonlinear step: 4-th order Runge-Kutta with sub stepping at constant U.

Conservative form with centered multi-point derivatives crucial for $\sum_{n=m} |g_{n,m}|^2$ conservation.

- $_$ n, $\epsilon,$ r-parallel process
 - Pitch-angle collision step: n, ϵ , r-parallel
- _ n, ϵ, λ -parallel process
 - r-step: g-advance for geodesic curvature drift motion (d/dr part) with high order derivative.
 - θ-step: implicit g advance of parallel, linear ExB, normal curvature drift motion (kx =-i d/dr=0 part), with Poisson-Ampere field simultaneous U-solve
- Most difficult numerical problem has been to stability advance the neutrally stable n=0, low-kx component over very long run times. Required the θ-step in special conservative form griding and r-step & θ-step repeated as a corrector on a predictor
- Used high-k_x damper for electron runs. This avoids resolving singular surface electron layer
- "banding" or nearest neighbor in gyro-averaging and 5-pt radial derivatives to avoid Nr² scaling.



Ballooning Mode (kx-space) Analysis





 $ky\rho_s = 0.3$, a/LT=3, a/Ln=1, R/a=3, r/a=0.5, s=1, q=2, Te=Ti, $\beta e= 0.004$ ($\beta e_crit = 0.055$)

ne=5 =(3,2), n λ =26, n θ =32/2 π , nr=5 (x=m Δr , kx = p Δk x) $\phi(x_m, \theta) = \sum_{p=-2}^{p=2} \phi_p(\theta) \exp(i\pi mp/2)$



Linear Growth Rates and Frequencies: GYRO vs GKS

ITG adiabatic-electron standard case



a/LT=3, a/Ln=1, R/a=3, r/a=0.5, s=1, q=2, Te=Ti, ne=5 =(3,2), n λ =26, n θ =32/2 π , nr=96, Lx=80 ρ s, nn= 15



Linear Growth Rates and Frequencies: GYRO vs GKS

electrostatic nonadiabatic electron standard case



a/LT=3, a/Ln=1, R/a=3, r/a=0.5, s=1, q=2, Te=Ti, ne=5 =(3,2), n λ =26, n θ =32/2 π , nr=96, Lx= 80 ρ s, nn= 15



n=0 radial mode (Zonal Flow) decay to Rosenbluth-Hinton residual

geodesic acoustic mode (GAM)



R/r=6, r/a=0.5, q=2, Te=Ti, (s=1), kxps =0.078 (lowest mode) RH residual = 6% ne=5 =(3,2), n λ =26, n θ =16/ π , nr=96, Lx= 80 ps



Scaling of n=0 radial mode residuals at kx->0 and vs. kx



R/r=5, r/a=0.5, q=1.4, Te=Ti, (s=1)

 $n_{e}=5 = (3,2), n_{\lambda}=26, n_{\theta}=32/2\pi$

kx-plot agrees with GS2 F. Jenko, W. Dorland, et al Phys Plas. 7 (2000) 19



Nonlinear Simulation

ITG adiabatic electron standard case



a/LT=3, a/Ln=1, R/a=3, r/a=0.5, s=1, q=2, Te=Ti,

 $n_e=5 = (3,2), n_\lambda = 14, n_\theta = 16/2\pi, dt = 0.05a/c_s: 60 hrs on 45ps GA Stella LINUX cluster 16000step: n_r=96, L_x= 80 \rho_s, n_r= 14: ky \rho_s = 0.0, 0.06, 0.12, 0.18...0.78, kx \rho_s_min = 0.078, kx \rho_s_max=3.6$



How to measure avalanche fraction

Hypothesis: $\chi_{rms_variation}/\chi_{rms_average}$

- Avalanches are intermittent events
- Spikes in χ are correlated in time with Flux(r,t) streamers interpreted as avalanches
- Example from standard case χ rms_variation/ χ rms_average = 0.48/3.25 = 14.7%



Nonlinear Simulation Spectrum

ITG adiabatic electron standard case.....continued



kxps=p 0.078 p= - 48 ->+48 kxps=(n/70) 0.70 n=0,6,12,18.....78



Nonlinear Simulation Visualization

ITG adiabatic electron standard case.....continued

• Annulus contour plot of physical $[\tilde{n}_e/n_{e0}](r,\theta) = \Phi(r,\theta) - \langle \Phi(r,\theta) \rangle_{\theta-ave}$ at $\zeta=0$ reconstructed from $\phi_n(r,\theta)$:

$$\Phi(r,\theta) = \sum_{n} \exp[-inq(r)\theta_{fine_scale}]\phi_n(r,\theta_{course_scale})$$

 $\alpha = \zeta - q(r)\theta$; n=±0,5,10,15,....70; 80 ρ_s from r=0.4 to 0.6; ρ_s =2.5e-3

The simulation is done on a course scale θ -grid for ϕ_n , but reconstruction requires a fine scale grid for the eikonal. Otherwsie the eddies could not be seen. This illustrates the efficiency of the field line following (α, θ, r)-grid in place of the toroidal (ϕ, θ, r)-grid.

If we multiply n x 10 and ρ s x 1/10, r -> 0.49 to 0.51 and eddies will scale down in size by 1/10, but χ normed to gyroBohm will be unchanged.

• Annulus contour plot of physical $\Phi(r, \theta)$ shows dominance of zonal flows over ballooning modes.







GYRO : right or wrong ? code checks and comparisons in progress

- Linear stability of ballooning modes checked with GKS and spot checked with GS2
- Quasilinear flux / $|\phi| \text{ rms}^2$ with GS2 std case (except a/L_n=1.5) kyps = 0.3

GYRO / GS2	ions	electrons
energy	0.39 / 0.39	0.14 / 0.15
plasma	0.012 / 0.015	0.012 / 0.015

• Nonlinear ky-pump mode test : $\gamma_{NL}(kx) = ky\rho_s \cdot kx\rho_s \cdot (e\varphi(ky)/T_e) / (\rho_s/a) c_s/a \pm 7\%$

- Nonlinear ITG same grid resolution std case GYRO / GS2

• For some collisionless cases, running beyond t=500 $a/c_s(1500 LT/cs)$, and particulary at low q (1.4) we find the longest wave length zonal flow (n=0, lowest k_x) builds up to a large stationary value, causing the diffusion to collapse to nearly 0. Other codes do not see this.

The CYCLONE case at R/LT=9 is a good example. r/a=0.5, a/LT=3 \Rightarrow 3.29, a/Ln=1 \Rightarrow 0.8, R/a=3 \Rightarrow 2.77, s=1.0 \Rightarrow 0.78, q=2 \Rightarrow 1.4 (This is far beyond Dimit's shift region R/LT= 4 to 6)

With small level of ii-collisions GYRO has $\chi = 2.72$ (dt =0.025) compared to Dimit's 4.0 (-32% po



Progress and Conclusions

- We have how obtained good linear EM agreement with Kotschenreuther's GKS code
- We have found efficient MPI parallelization methods with better than linear scaling to 512ps.
- The use of banding and real space nonlinear 2 and 3-pt derivative allows Nr scaling.
- n=0 modes have excellent linear agreement with Rosenbluth-Hinton residules.
- Stable implicit linear methods well in hand
- Have EM real geometry linear runs on the 16ps GA LINUX Beowulf LUNA and moderate phase space resolution nonlinear runs ES adiabatic-e ITG and nonadiabatic-e runs on 45ps GA Stella LINUX cluster, and NERSC 512ps GSeaborg IBM-SP

• Immediate goals:

_Finish flux tube run benchmark with Dorland-Kotschenreuther GS2 code.

_Move to radial annulus operation with non-cyclic radial boundary conditions and profiles



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