

# Observation and Analysis of MHD with the DIII-D Fast MSE System<sup>1</sup>

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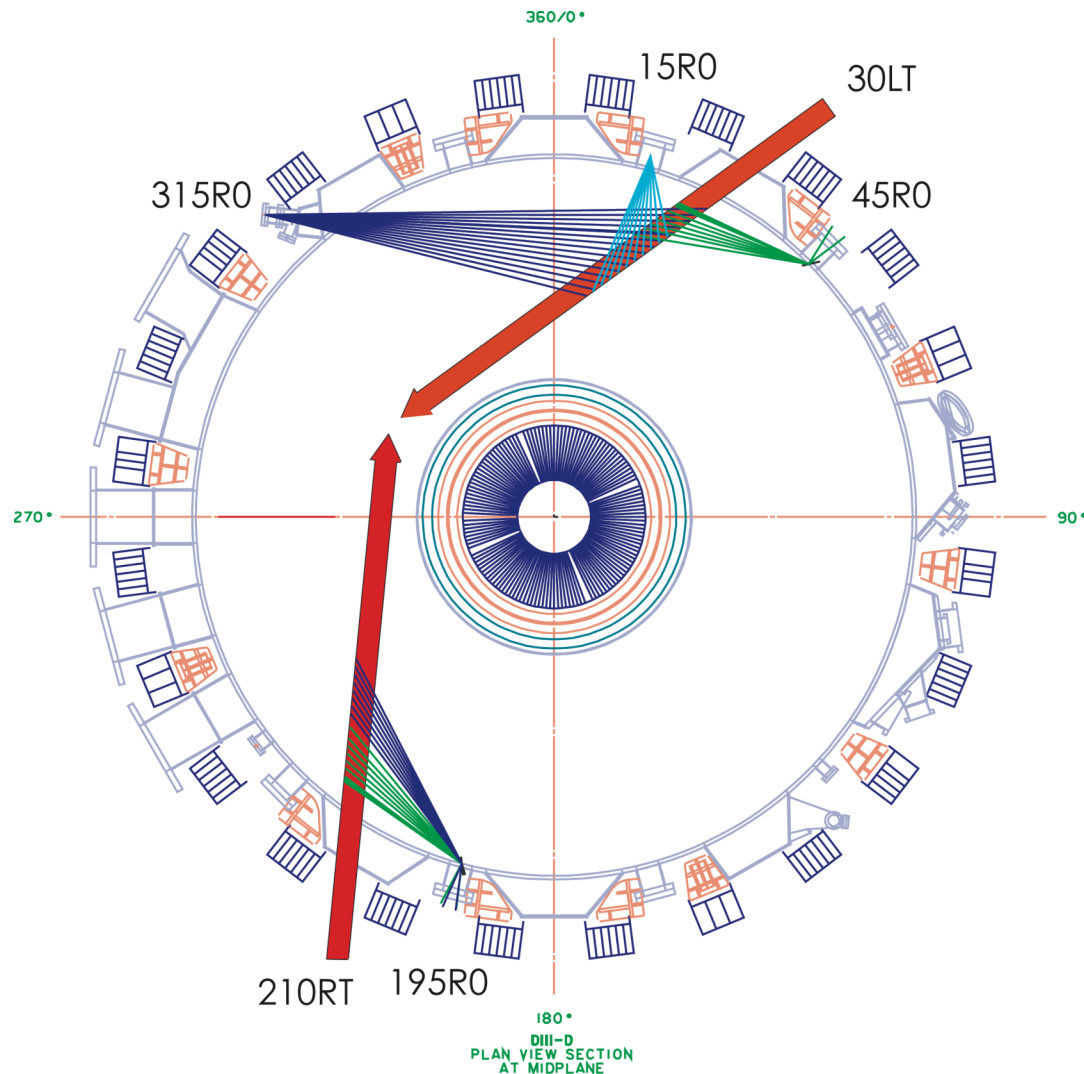


# MSE Measures the Local Plasma Pitch Angle

- The Motional Stark Effect (MSE) diagnostic measures the local value of the field line pitch angle
- Neutral beam particles experience a Lorentz ( $v_{\text{beam}} \times B$ ) electric field causing a Stark shift
- Collisionally excited particles emit linearly polarized light at a wavelength that depends on the beam energy and view angle (Doppler shift)
- The measured polarization is simply related to the local pitch angle by geometric constants
- Standard polarimetry techniques are used to determine the polarization



# Two Beam MSE System on DIII-D



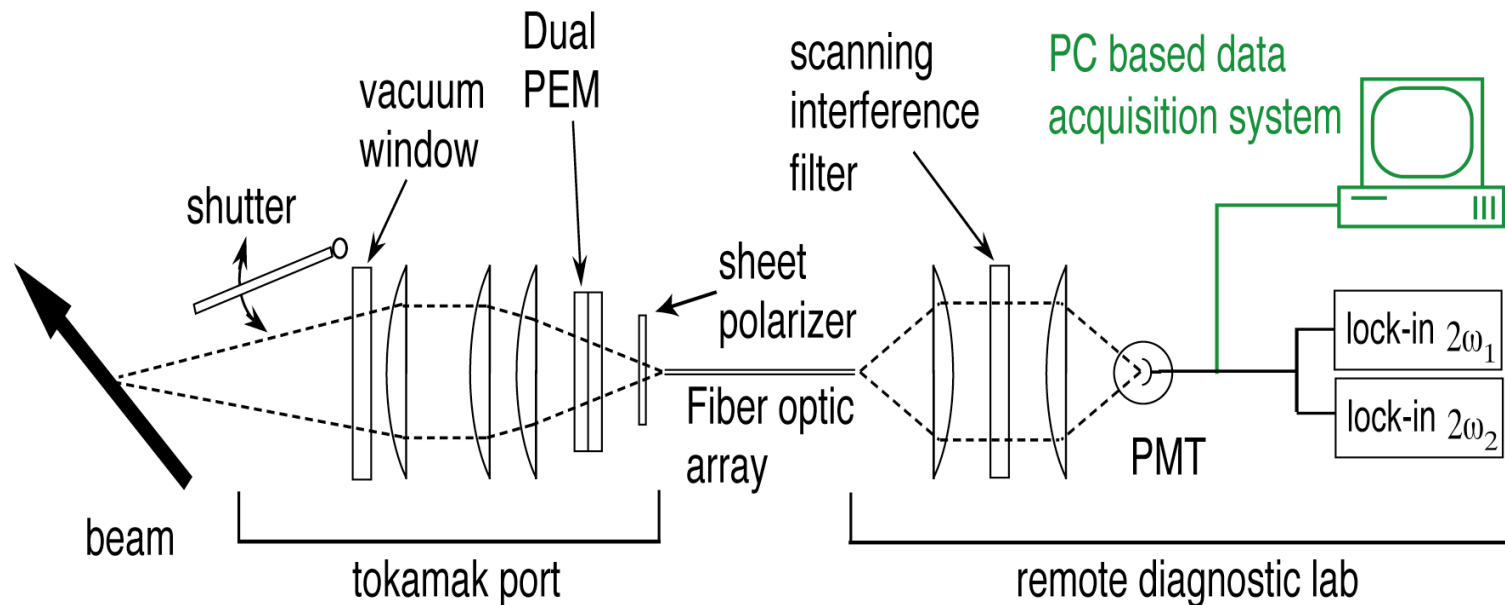
- Currently we have 5 arrays viewing the 30LT and 210RT beams
- An analog system measures the pitch angle on a slow time scale,  $\sim 1$  kHz
- Views of counter propagating neutral beams give maximum sensitivity in the determination of the electric field

# MHD Activity has been Observed with the Fast MSE System

- A prototype PC based digital data acquisition system has been developed for the DIII-D MSE diagnostic
- The signals are captured at the output of the PMTs and digitized at rates up to 1 MHz with 12 bit resolution
- MHD phenomena have been observed on the fast system and a method has been developed to interpret the signals
- The analysis tools that have been developed can be applied to a wider range of problems

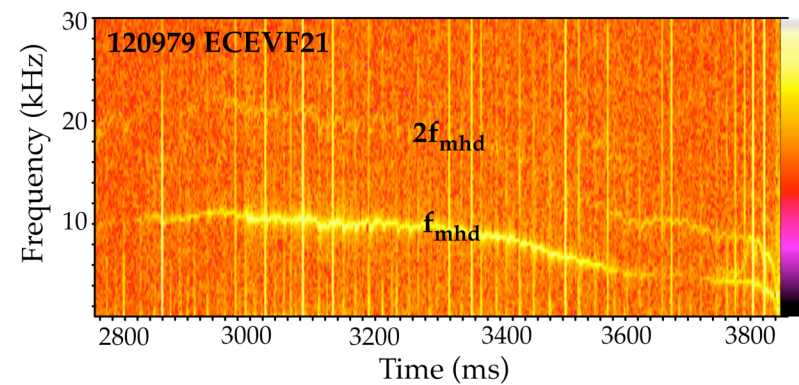
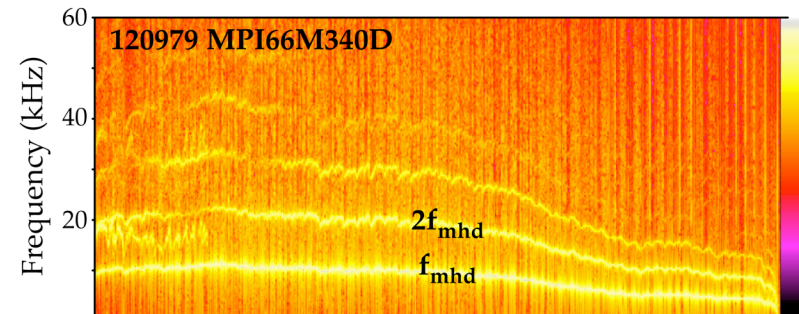
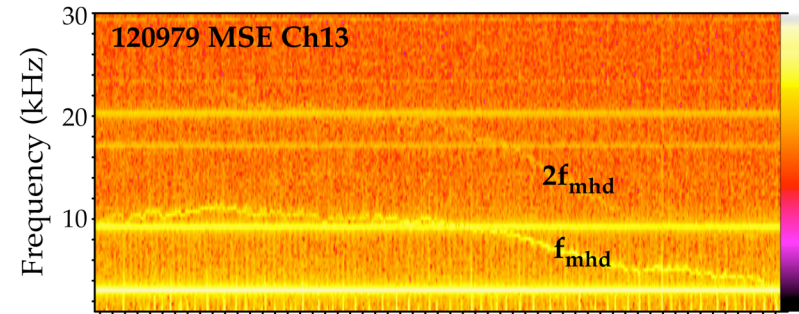
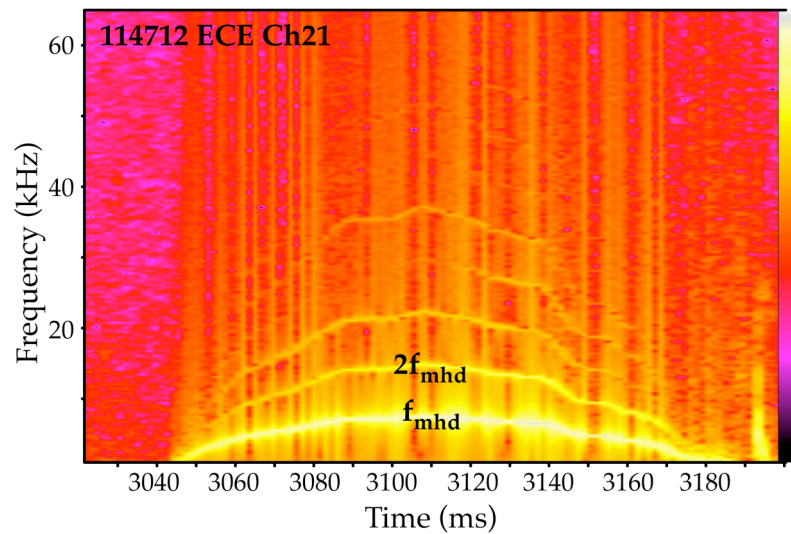
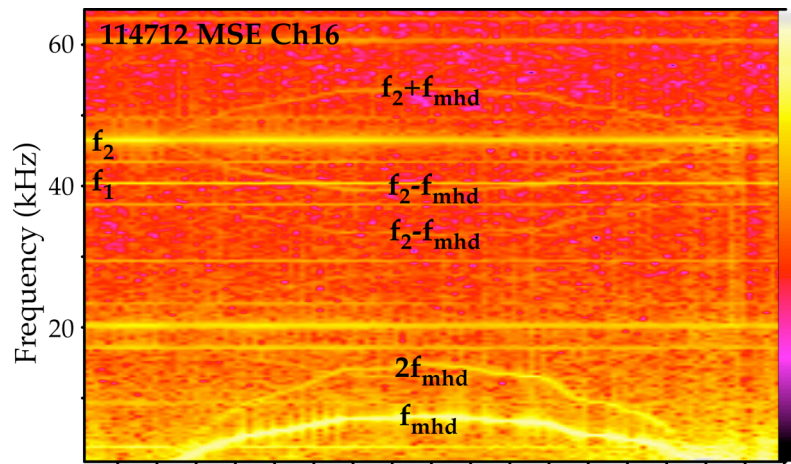


# Prototype Fast MSE System has a Flexible Configuration



- Fast MSE system acquires a maximum of 12 channels
- Acquired channels can be selected from any of the 36 channels comprising the  $315^\circ$  and  $45^\circ$  arrays
- Data is stored in a local MDSPlus server

# Spectrum of Fast MSE Signal Shows the Same MHD Signal as other Diagnostics





# Interpretation of the Signal is Complicated by Associated Density Fluctuations

- Signatures of MHD activity that are well correlated with other diagnostics are observed on fast MSE data
- Such observations are indicative of *local pitch angle fluctuations* due to the presence of the MHD mode
- Interpretation of the raw signal is complicated as it depends on the total intensity (proportional to  $n_e n_{\text{beam}}$ )
- Therefore, the observed fluctuation is dependent on changes in both the density and pitch angle.
- In a quiescent discharge, the ratio of two signals is used to remove the density dependence and derive the static (equilibrium) pitch angle
- A more elaborate analysis technique is needed to determine the contribution due to the pitch angle fluctuation alone



# Mueller Matrix Model Forms Basis of Analysis

- The optical system is modeled by a cascade of Mueller matrices which operate on the Stokes vector corresponding to the polarization of the incident light
- Perturbations are taken as

$$\gamma + \tilde{\gamma} \cos(\omega_{mhd} t + \varphi_g)$$
$$n_0 [1 + \tilde{n} \cos(\omega_{mhd} t + \varphi_n)]$$

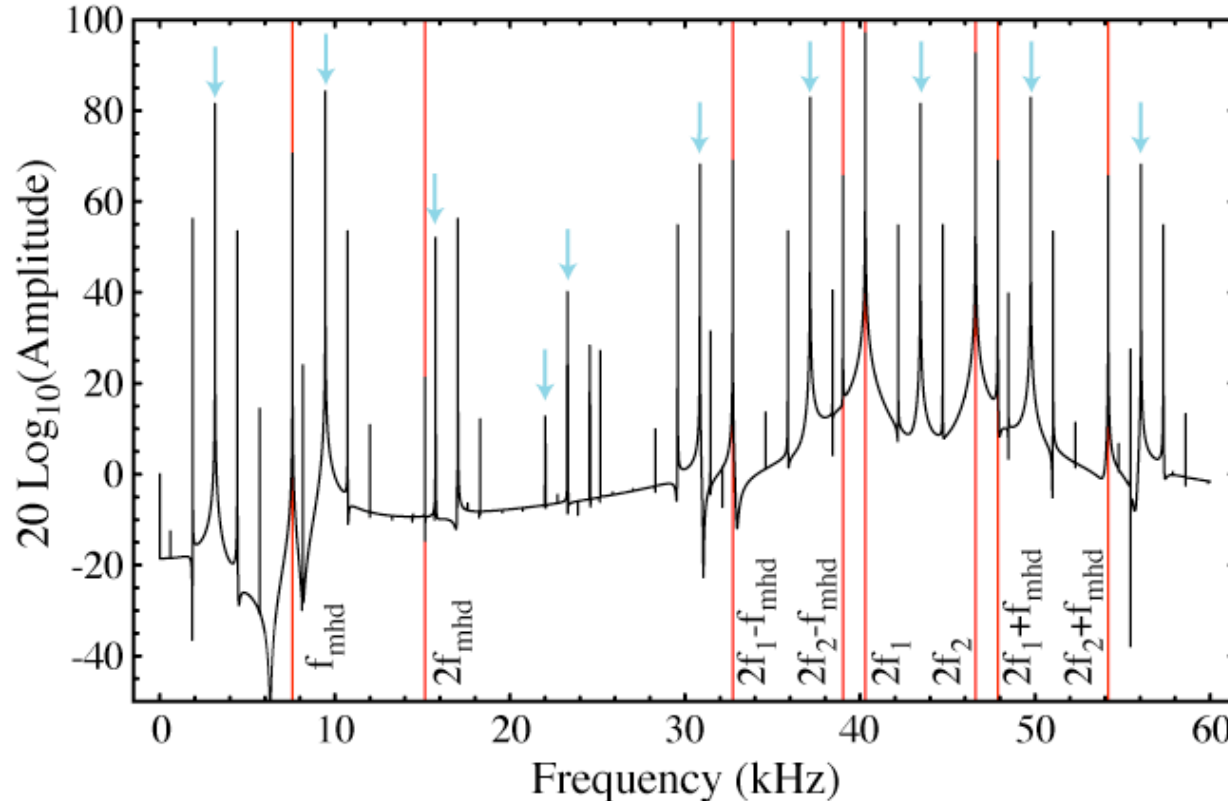
- Photoelastic modulators (PEMs) in the optical system modulate the polarization of the incident light and mix non-linearly with the MHD oscillation to produce a complex spectrum
- The primary challenge in the analysis is to simultaneously determine the phase and amplitude of the density and pitch angle contributions





# Spectrum of Mixed MSE and MHD Signals is Rich

## Simulated MSE Spectrum

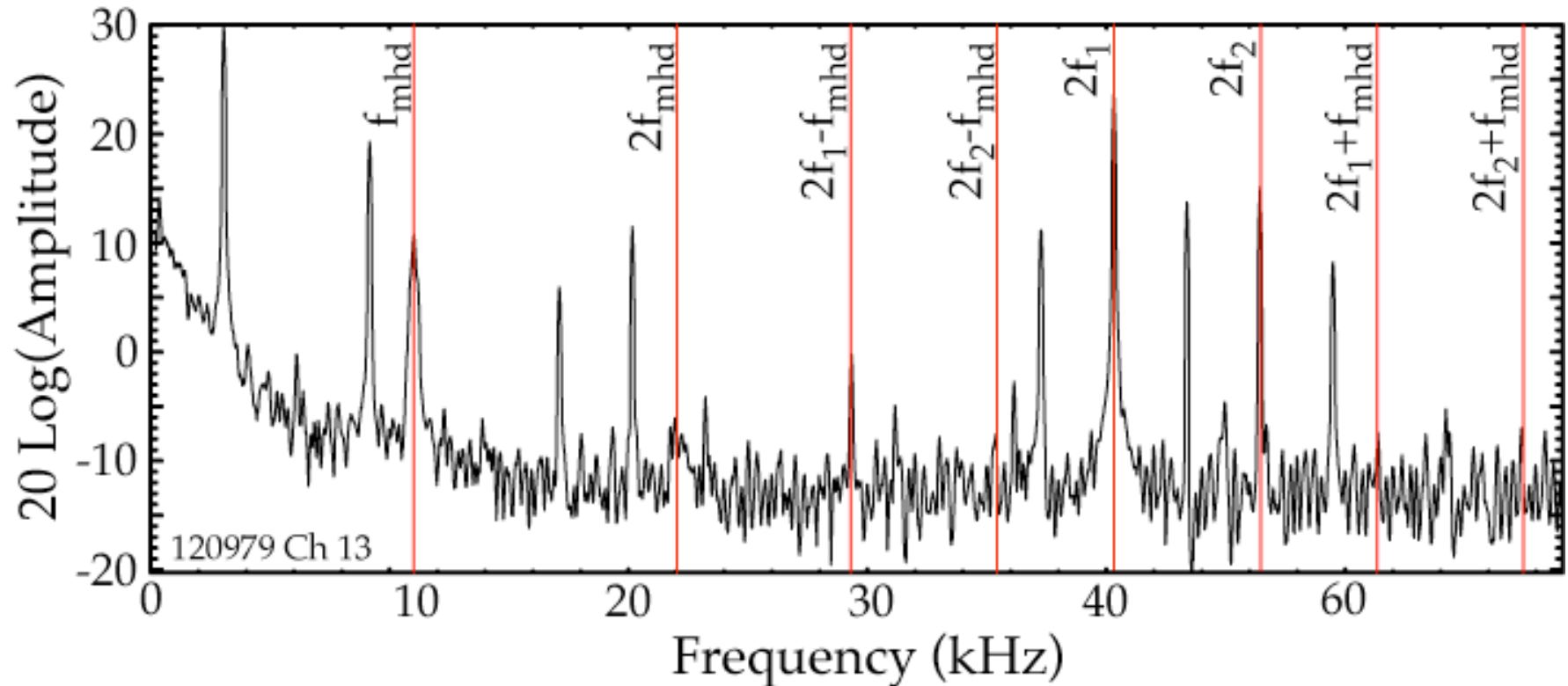


- Blue arrows indicate peaks present in an MHD-free case
- Red lines indicate frequencies normally observed when MHD is present

- $f_1$  and  $f_2$  are the (fundamental) PEM modulation frequencies
- $f_{\text{mhd}}$  is the frequency of the MHD oscillation

# Model Explains All Observed Peaks in the Spectrum

- The measured phases and amplitudes of various spectral peaks of the FFT can be related to the phase and amplitude of the density and pitch angle perturbations



# Fluctuation Parameters are Encoded in the Amplitude and Phase of the Main Spectral Peaks

$\omega$	Amplitude	Phase
$\omega_{mhd}$	$\frac{1}{4}(I_\pi + I_\sigma)\{\tilde{n}^2[1 - PJ_0(A_{12})\cos 2\gamma] + 4\tilde{\gamma}^2 P^2 J_0^2(A_{12})\sin^2 2\gamma + 4P\tilde{\gamma}\tilde{n}J_0(A_{12})\sin 2\gamma[1 - PJ_0(A_{12})\cos 2\gamma]\cos(\varphi_g - \varphi_n)\}^{1/2}$	$\tan^{-1}\left[\frac{[1 - PJ_0(A_{12})\cos 2\gamma]\sin \varphi_n + rPJ_0(A_{12})\sin 2\gamma \sin \varphi_g}{[1 - PJ_0(A_{12})\cos 2\gamma]\cos \varphi_n + rPJ_0(A_{12})\sin 2\gamma \cos \varphi_g}\right]$
$2\omega_1$	$\frac{1}{\sqrt{2}}(I_\pi - I_\sigma)J_2(A_1)\cos 2\gamma_1$	$2\varphi_1$
$2\omega_1 + \omega_{mhd}$	$\frac{1}{2\sqrt{2}}(I_\pi - I_\sigma)J_2(A_1)\{\tilde{n}^2 \cos^2 2\gamma_1 + 4\tilde{\gamma}^2 \sin^2 2\gamma_1 - 4\tilde{n}\tilde{\gamma}\cos 2\gamma_1 \sin 2\gamma_1 \cos(\varphi_g - \varphi_n)\}^{1/2}$	$\tan^{-1}\left[\frac{\sin(\varphi_n + 2\varphi_1) - r \tan 2\gamma_1 \sin(\varphi_g + 2\varphi_1)}{\cos(\varphi_n + 2\varphi_1) - r \tan 2\gamma_1 \cos(\varphi_g + 2\varphi_1)}\right]$
$2\omega_1 - \omega_{mhd}$	$\frac{1}{2\sqrt{2}}(I_\pi - I_\sigma)J_2(A_1)\{\tilde{n}^2 \cos^2 2\gamma_1 + 4\tilde{\gamma}^2 \sin^2 2\gamma_1 - 4\tilde{n}\tilde{\gamma}\cos 2\gamma_1 \sin 2\gamma_1 \cos(\varphi_g - \varphi_n)\}^{1/2}$	$-\tan^{-1}\left[\frac{\sin(\varphi_n - 2\varphi_1) - r \tan 2\gamma_1 \sin(\varphi_g - 2\varphi_1)}{\cos(\varphi_n - 2\varphi_1) - r \tan 2\gamma_1 \cos(\varphi_g - 2\varphi_1)}\right]$
$2\omega_2$	$\frac{1}{\sqrt{2}}(I_\pi - I_\sigma)J_2(A_2)\sin 2\gamma_1$	$2\varphi_2$
$2\omega_2 + \omega_{mhd}$	$\frac{1}{2\sqrt{2}}(I_\pi - I_\sigma)J_2(A_2)\{\tilde{n}^2 \sin^2 2\gamma_1 + 4\tilde{\gamma}^2 \cos^2 2\gamma_1 + 4\tilde{\gamma}\tilde{n}\cos 2\gamma_1 \sin 2\gamma_1 \cos(\varphi_g - \varphi_n)\}^{1/2}$	$\tan^{-1}\left[\frac{\sin(\varphi_n + 2\varphi_2)\tan 2\gamma_1 + r \sin(\varphi_g + 2\varphi_2)}{\cos(\varphi_n + 2\varphi_2)\tan 2\gamma_1 + r \cos(\varphi_g + 2\varphi_2)}\right]$
$2\omega_2 - \omega_{mhd}$	$\frac{1}{2\sqrt{2}}(I_\pi - I_\sigma)J_2(A_2)\{\tilde{n}^2 \sin^2 2\gamma_1 + 4\tilde{\gamma}^2 \cos^2 2\gamma_1 + 4\tilde{\gamma}\tilde{n}\cos 2\gamma_1 \sin 2\gamma_1 \cos(\varphi_g - \varphi_n)\}^{1/2}$	$-\tan^{-1}\left[\frac{\sin(\varphi_n - 2\varphi_2)\tan 2\gamma_1 + r \sin(\varphi_g - 2\varphi_2)}{\cos(\varphi_n - 2\varphi_2)\tan 2\gamma_1 + r \cos(\varphi_g - 2\varphi_2)}\right]$

# Definitions

$I_\pi, I_\sigma$  = Intensity of the  $\pi$  and  $\sigma$  lines

$$P = \frac{I_\pi - I_\sigma}{I_\pi + I_\sigma} = \text{Polarization ratio}$$

$J_0, J_2$  = Bessel functions of first kind of order 0 and 2

$A_1, A_2$  = Amplitudes of the PEM modulation

$A_{12}$  = Common PEM modulation amplitude (assumes  $A_1 = A_2$ )

$r = 2\tilde{\gamma}/\tilde{n}$  = ratio of fluctuation amplitudes

$\tilde{\gamma}, \tilde{n}$  = pitch angle and density perturbation amplitudes

$\varphi_g, \varphi_n$  = phases of the pitch angle and density perturbations

$\varphi_1, \varphi_2$  = phases of the PEM modulations

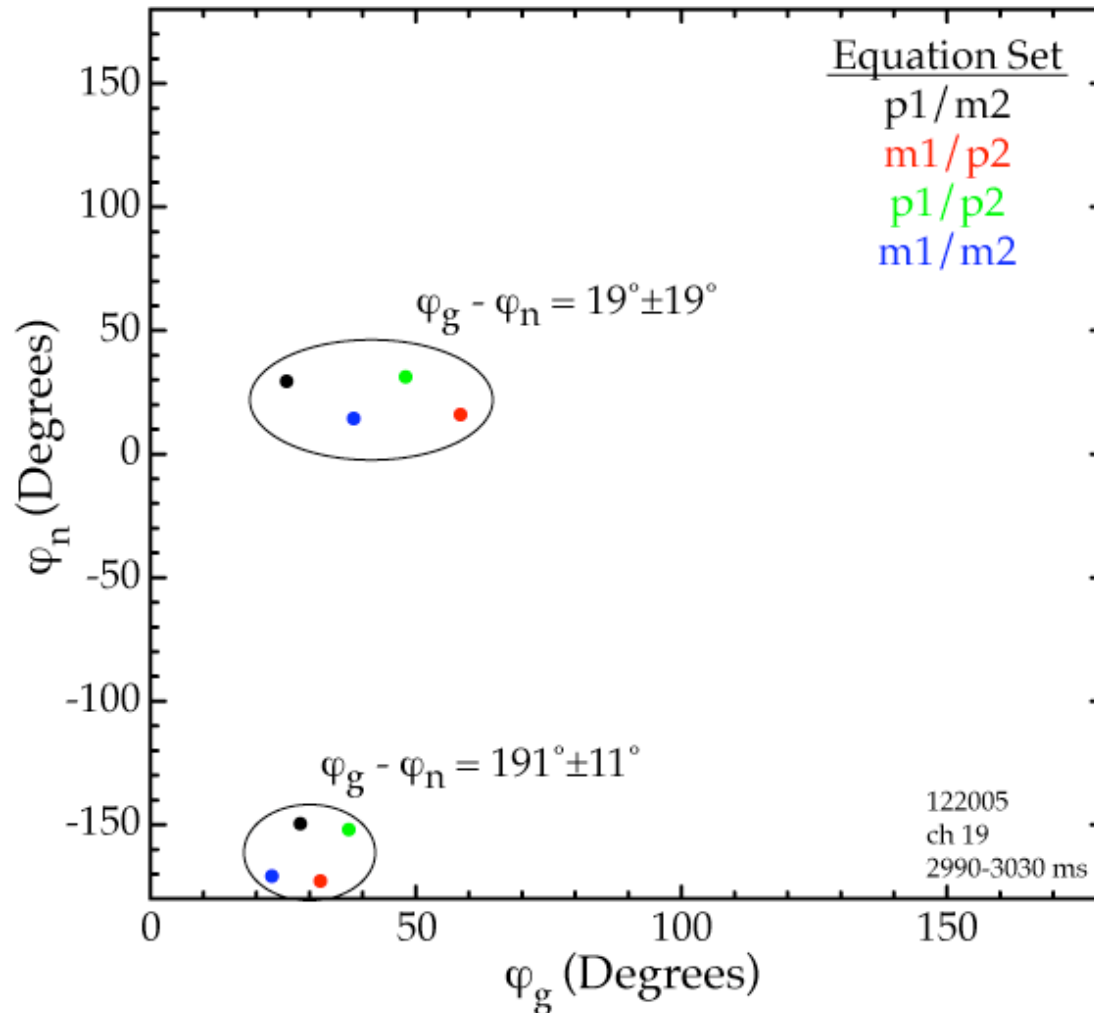
$\gamma = \gamma_1 - \pi/8$  = magnetic pitch angle at the measurement location

# There is Sufficient Information in the Spectrum to Solve for the Unknown Parameters

- Main peaks are at  $2f_1 \pm f_{\text{mhd}}$  and  $2f_2 \pm f_{\text{mhd}}$  with amplitude and phase information at each
- The  $f_{\text{mhd}}$  peak cannot be used in the initial solution because it contains an additional unknown,  $P$ , the polarization fraction
- Relating the measured phases and ratios of amplitudes to the expressions in the table leads to multiple sets of coupled transcendental equations for the unknown phases  $(\varphi_g, \varphi_n)$  and perturbation amplitudes  $(\tilde{n}$  and  $\tilde{\gamma})$
- Solutions to these equations can be found relatively easily
- Moreover, solutions from different equation sets are consistent with one another
- The  $f_{\text{mhd}}$  peak may then be used to determine  $P$ , a quantity that we cannot otherwise measure experimentally



# Multiple Roots are Often Found



- Relative phase between the density and pitch angle fluctuation ( $\varphi_g - \varphi_n$ ) is the quantity of physical interest
- Since the equations are transcendental, multiple roots are often found
- Have yet to find a way to distinguish the roots physically

# Inferred Quantities

- Solution yields the following quantities

$$\begin{aligned}\tilde{\gamma} &= 0.024 & \tilde{B}_z &= 360 \text{ G} \\ \tilde{n} &= 0.15 & I_s / I_p &= 1.9\end{aligned}$$

- Mode amplitude is very large,  $\tilde{B}_z \sim 10\times$  magnetic probe value
- Attribute this to non-ideal effects not initially modeled due to retardance in a mirror in the optical train of the edge channels
- When a correction is applied for the mirror retardance the following solution is obtained:

$$\begin{aligned}\tilde{\gamma}_{\min} &= 0.0008 & \tilde{B}_{z,\min} &= 12 \text{ G} & \varphi_g - \varphi_n &= \begin{cases} 9^\circ \pm 9^\circ \\ 201^\circ \pm 21^\circ \end{cases} \\ \tilde{n} &= 0.14 & I_s / I_p &= 1.7\end{aligned}$$

- Exact values depend on the mirror retardance (being assessed)
- Solution method validated by simulations



# Measurement Issues

- Detectible mode frequency is limited to  $\sim 40$  kHz -- not enough photons in a period to detect
- Due to “busy” spectrum, there are MHD frequencies which can be masked by PEM peaks
- Minimum detectible mode amplitude is estimated to be  $\sim 10$ - $20$  G. This is possibly limited by the current 12 bit digitizers. Hope to get 16 bit digitizers in the near future
- Other complications
  - Large amplitude (observable) modes don't linger, so the time the mode is stationary is generally short, typically  $< 50$  ms, making measurements noisy due to short integration time
  - ELMs also contribute considerably to the background noise



## Toroidal Correlations in the Magnetic Pitch Angle Fluctuations could be Studied with a Second Fast MSE System

- Two toroidally separated fast MSE systems would allow the study of toroidal correlations in the pitch angle fluctuations
- Applicable to both
  - NTMs
  - Edge phenomena (EHO, ELMs, Stochasticized SOL, ...)
- Plan to migrate entire MSE data acquisition system (64 channels) to a 16 bit fast (500 kHz) system (eliminate all CAMAC and analog components)

# Summary

- MHD oscillations have been observed on the MSE diagnostic using a fast data acquisition system
- The diagnostic is sensitive to density as well as pitch angle fluctuations preventing direct interpretation of the data
- An analysis technique has been developed to interpret the data and has been applied to it with some success - further work is needed here
- This allows the local values of the phase and amplitude of magnetic fluctuations to be determined
- We are currently limited by the sensitivity of the diagnostic, but plan to improve this in the near future

