

Snowmass Preview

Edge Stability/Pedestal Constraints

Preliminary Results

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Pedestal Height and ELM behavior are key issues for Next Step

- Core transport modeling indicates profiles are quite stiff, $P_{\text{fus}} \sim \square_{\text{ped}}^{1.8}$, pedestal conditions essentially determine performance [Kinsey, Waltz]
- Large ELMs pose risk of severe divertor erosion
- Begin Uniform Technical Assessment of pedestal constraints due to MHD stability, and predictions of ELM behavior for ITER-FEAT, FIRE, Ignitor
 - “Uniform” is a challenge as Ignitor plans to operate in L-mode. For now, ignore this and calculate constraints that would exist if it did have an H-mode-like pedestal.
- Uncertainty in pedestal transport, particularly in physics setting the pedestal width, leaves gaps in our predictive capability
- Suggestions for how to proceed welcomed

ELITE is a highly efficient 2D MHD code for $n \gg 5$

Expect that most unstable mode will often be coupled peeling-ballooning mode at intermediate wavelength ($5 < n < 50$)

Need to scan real equilibria in several parameters simultaneously and explore stability constraints over a wide range of $n \rightarrow$ Need a fast code

ELITE is a 2D eigenvalue code, based on ideal MHD (amenable to extensions, includes simple model of diamagnetic stabilization):

Generalization of ballooning theory to incorporate surface terms which drive peeling modes, and retain first two orders in $1/n$ (treats intermediate $n \gg 5$)

Plasma displacement, X , expanded in poloidal Fourier harmonics:

$$X = \sum_{m=m_{\min}}^{m=m_{\max}} u_m(x) e^{im\varphi}$$

Makes use of fact that each $u_m(x)$ is localized about its own mode rational surface where $m=nq \Rightarrow$ *fast and efficient code*

Study coupled peeling/ballooning modes and quantitative constraints on edge gradients and pedestal height. Growth rates and mode structures generated.

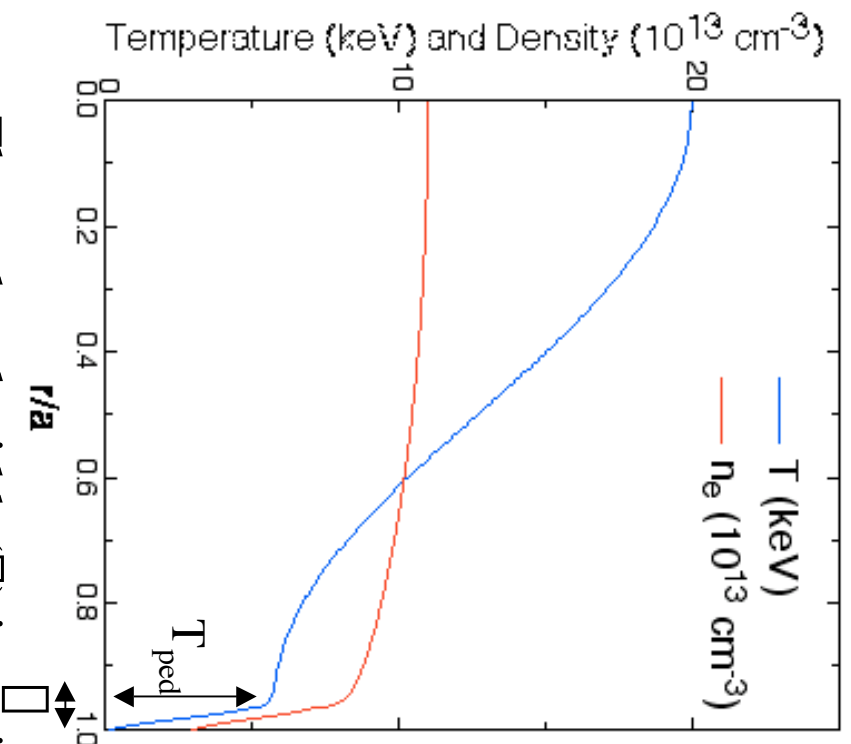
Successfully benchmarked against GATO and MISHKA

[P.B. Snyder, H.R. Wilson et al Phys Plas 9 2037 (2002); H.R. Wilson, P.B. Snyder et al Phys Plas 9 1277 (2002)]

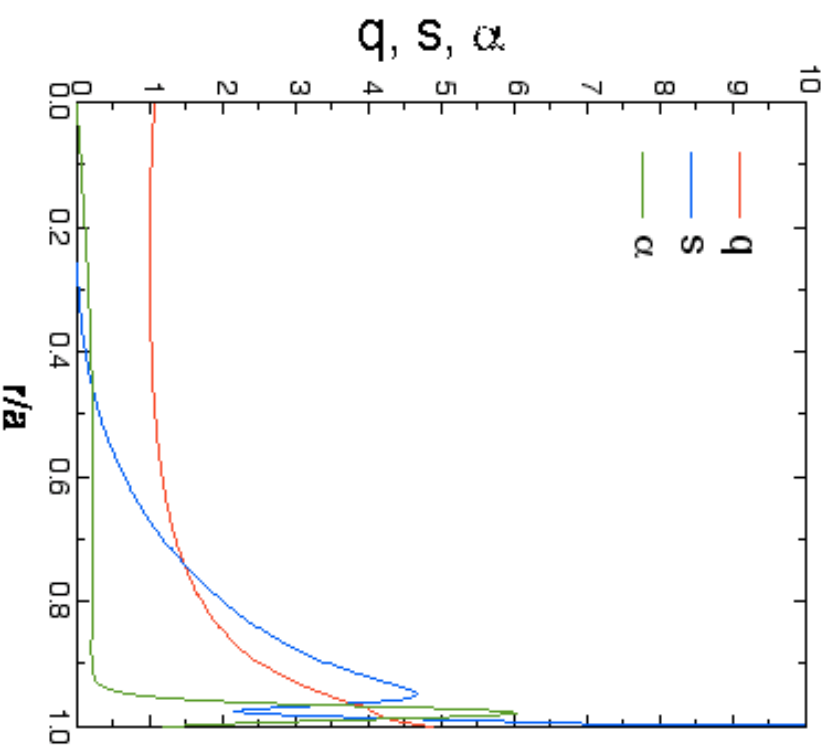
Sample Model Equilibrium Profiles

ITER-FEAT model profiles for $\Delta/a \sim 0.03$, $T_{ped} \sim 5\text{keV}$ case

Sample ITER-FEAT profiles

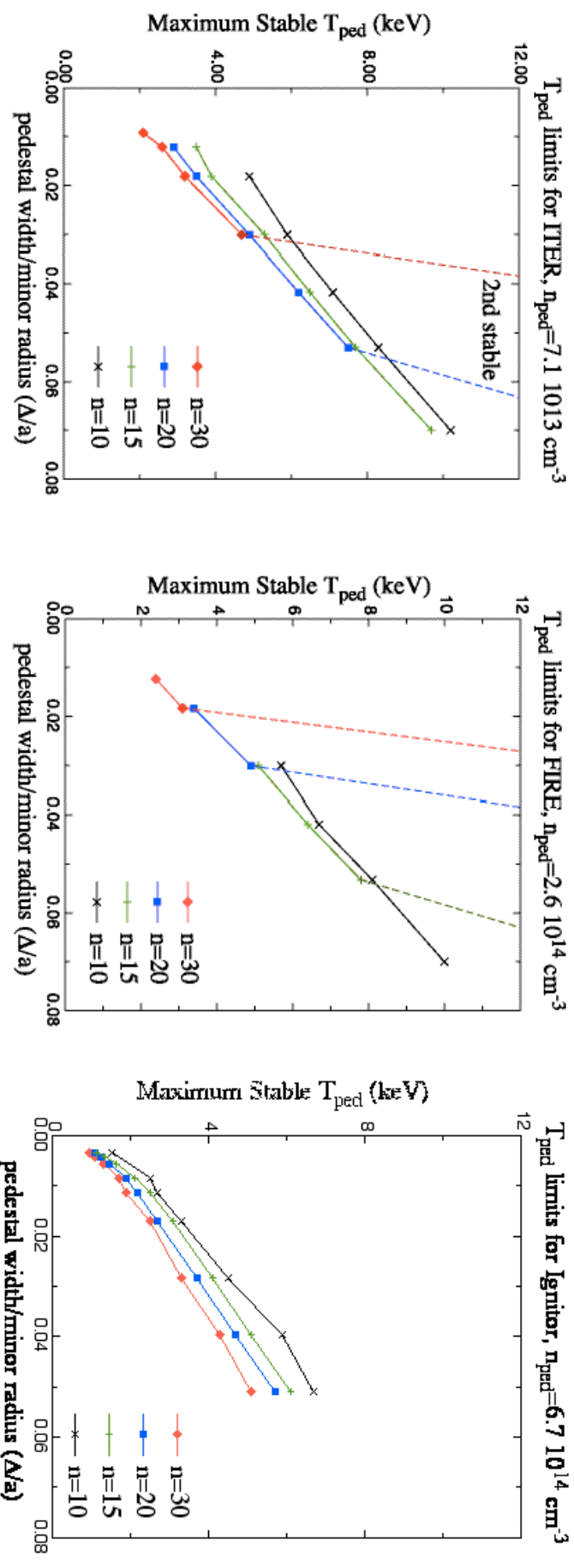


Sample ITER-FEAT profiles



- The pedestal width (Δ) is varied from $\sim 1\%$ to 12% of the poloidal flux ($\Delta/a \sim 0.005-0.07$)
- At each value of Δ , T_{ped} is increased (with J_{bs} calculated consistently) until instabilities are triggered

Pedestal Stability Constraints on T_{ped}

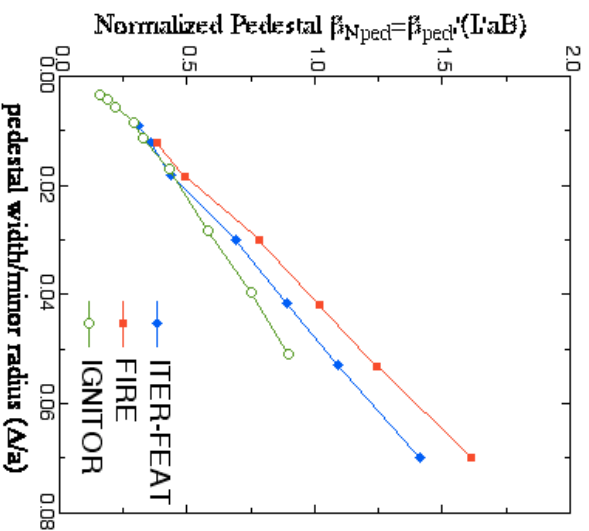


- T_{ped} limit is a strong function of pedestal width, but notably sub-linear, particularly at narrow width ($\sim \Delta/a^{2/3}$)
 - Intermediate to high- n peeling-ballooning modes are most unstable. ITER & FIRE show significant second stability to high- n modes at larger widths.
 - Useful metric for comparing machines is Δ/a_{ped} or Δ/a_{Nped} (see following)
 - $\Delta/a=0.03$ provides a useful reference point, similar to present observations. At this width or larger, T_{ped} is in range needed for good performance.
- [J. Kinsey transport talk Wednesday morning]

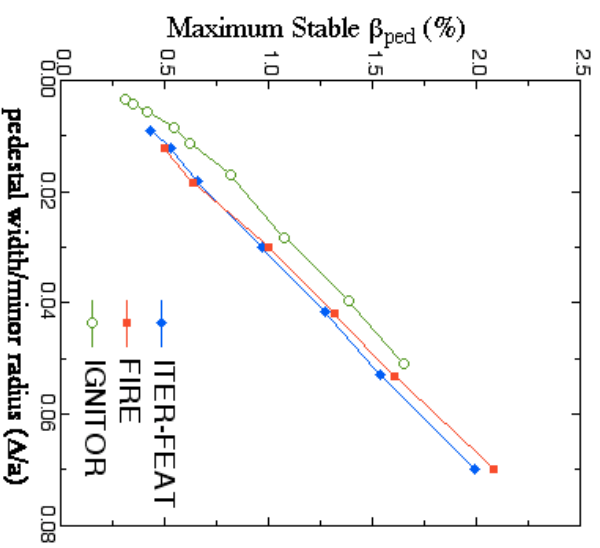


Stability constraints on β_{Nped} , β_{ped} , β_c

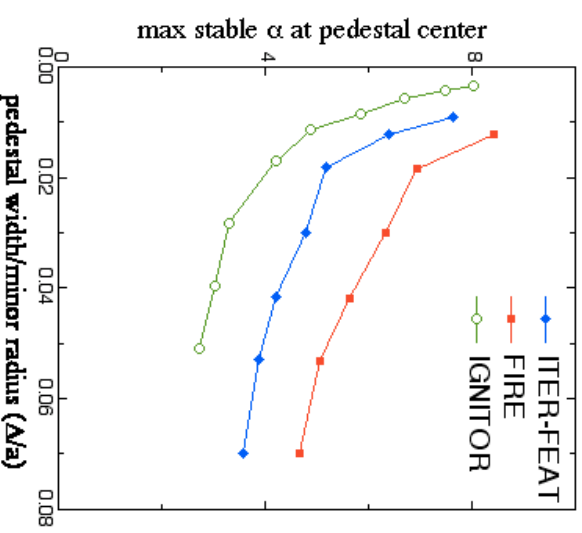
Comparison of Normalized Pedestal Stability Limits



Comparison of MHD Pedestal Stability Limits



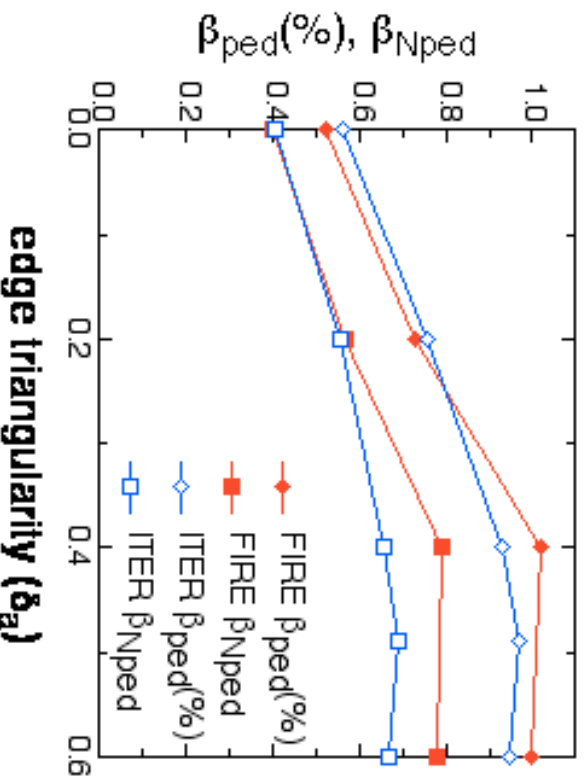
Max Stable α vs Pedestal Width



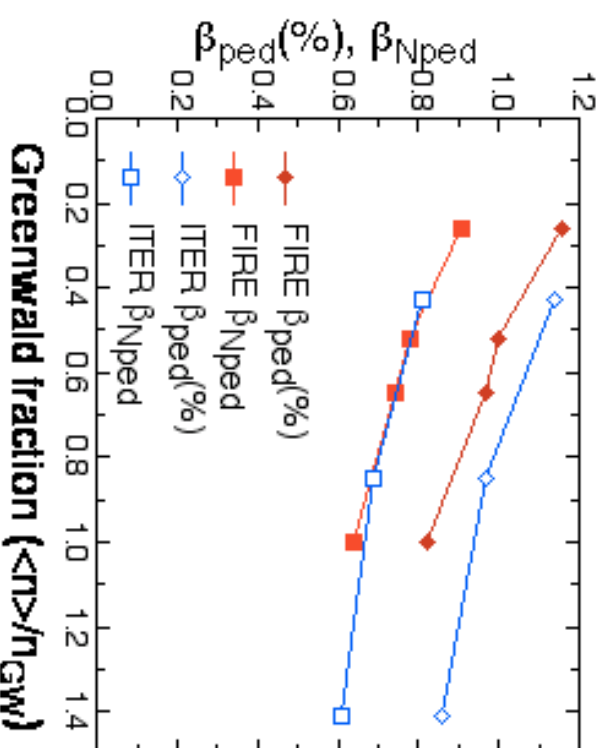
- β_{Nped} provides a useful figure of merit for inter-machine comparisons
 - Stronger shaping \Rightarrow higher β_{Nped} & β_{cped}
 - Ignitor has largest $I/aB=1.86$, ITER=1.42, FIRE=1.29
 - Maximum stable β_{ped} important for core transport, remarkably similar between machines
 - β_{crit} decreases strongly with width
- [note: these figures contain the same data as the previous page, selecting the most unstable n and re-plotting the stability threshold in terms of other vars]

Variation with triangularity and density

Variation in Stability Limits with Triangularity

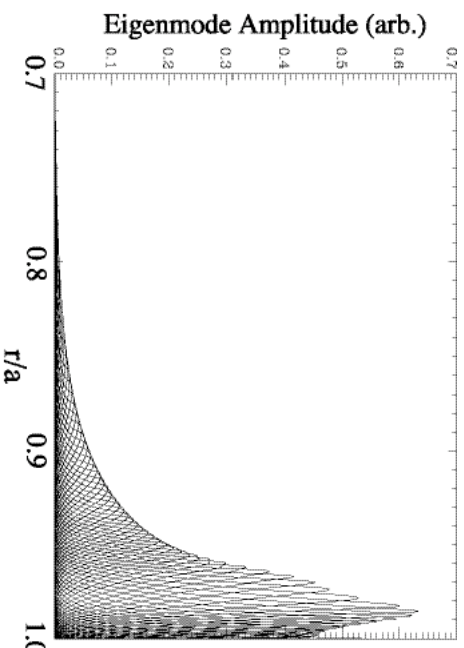
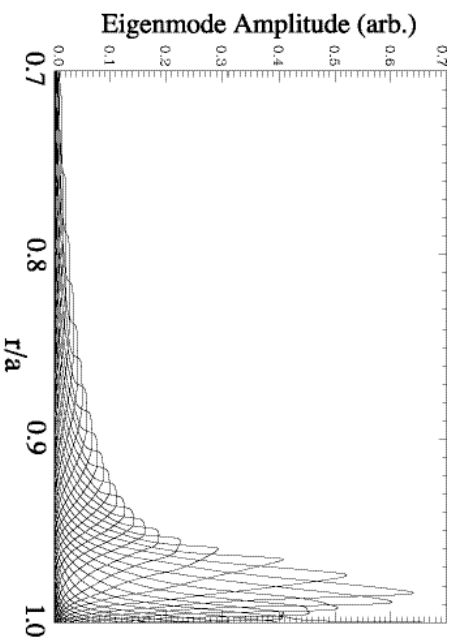


Variation in Stability Limits with Density

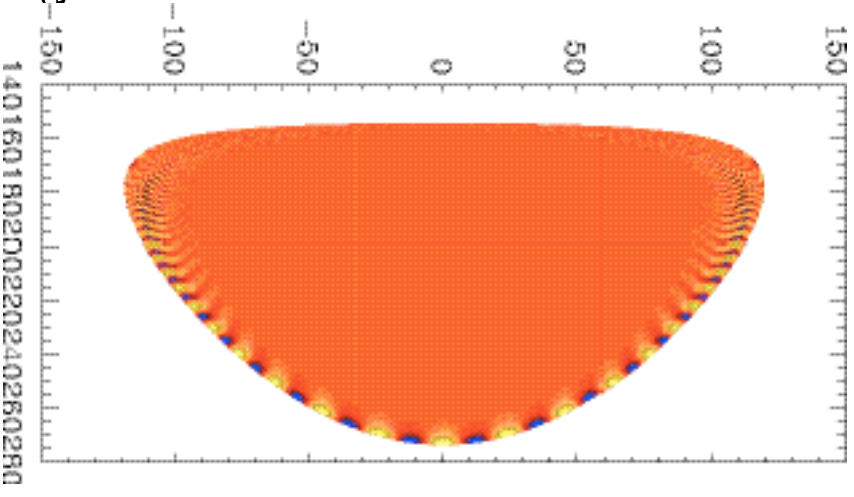


- Calculated at fixed width $\square/a \sim 0.03$ (5% of flux) and reference parameters except the one varied
- Increasing triangularity (\square_a) is stabilizing, levels off around $\square_a \sim 0.5$
- Increasing density lowers edge bootstrap current, restricts 2nd stability access. Appears possible to increase performance by operating at lower density; tradeoffs with divertor, ELM size?

Unstable Mode Structure and ELM size



Comparison of radial eigenmode structures for $n=8$ & 20 in ITTER-FEAT model equilibrium with $\beta/a=0.03$, $T_{ped}=6.2\text{keV}$. Lower n modes are slightly more extended



- ELM size expected to be related to unstable mode width, but details of this relationship are complex and uncertain.
- Calculated mode structures extend beyond pedestal. Some dependence on n .
- ITTER & FIRE appear able to access 2nd stable edge regime and explore tradeoffs between higher pedestal and possible larger ELMs due to lower n instabilities.

Summary/Plans

- MHD stability imposes constraints on pedestal height, which are strong functions of pedestal width (but *not* linear with width) and plasma shape. Constraints are \sim similar between machines.
- Limiting instability is intermediate to high- n peeling-ballooning mode. Strong shaping opens 2nd stability, and leads to lower n for limiting mode. Mode width extends somewhat beyond the pedestal.
- Uncertainty about the pedestal width makes precise prediction difficult. Observed correlations ($\beta_p \sim \beta_p^{-1/2}$, $\beta_p \sim \beta_p^x$) are \sim expected from the stability constraints and may provide limited information on physics setting the width. Finite- n stability constrains the width as well as the gradient, but understanding of transport likely needed as well to accurately predict width. (power dependence of width is a key question)
- For β_p/a in observed range, constraints allow β_{ped} in vicinity of what's predicted to be needed for good performance (GLF23 Kinsey, Waltz). Optimizing shaping & density may increase it further.
- These are preliminary results with ideal MHD. Non-ideal effects such as diamagnetic stabilization will be considered - expected to increase stability threshold somewhat and move most unstable mode toward lower n
- Plan to parameterize stability constraints, and try to use better understanding of pedestal stability to “back out” behavior of width from the database