



Integrated modeling of island growth, stabilization and mode locking

Consequences for NTM control on ITER

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What are the consequences of preventing mode locking for NTM control on ITER?

- Rotation of NTMs
- Generalized Rutherford Equation with ECCD stabilization
- Maximum allowed latency
- Effect of misalignment



NTM control on ITER

- ECCD on ITER
 - ◆ Four EC launchers spanning 100° toroidal angle
 - ◆ Total power 13.3 MW
 - ◆ Destabilizing current drive in X-point likely for locked modes
- Full suppression of islands
- No mode locking (rotation should remain finite)
- Latency and alignment requirements?



Rotation

- Rigid body rotation of the island
 - ◆ Speed up by viscous coupling with the bulk plasma
 - ◆ Slow down by wall interaction

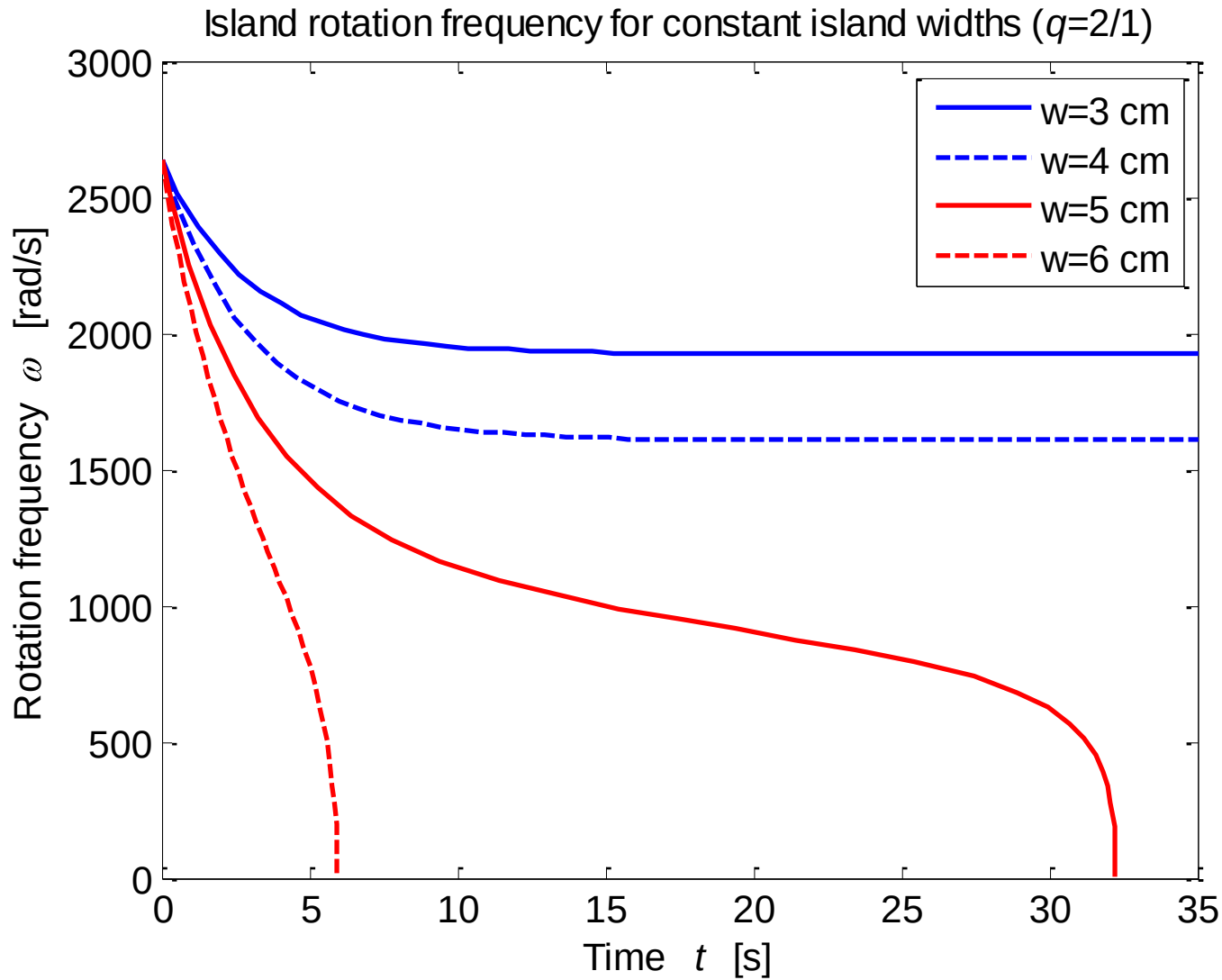
$$\frac{d\omega}{dt} = \left(\frac{\omega_0}{\tau_{M0}} - \frac{\omega}{\tau_M} \right) - \frac{1}{m\tau_{A0}^2 C_W \omega \tau_w} \left(\frac{w}{a} \right)^3$$

$$\tau_M = \frac{\tau_{M0}}{1 + C_M \frac{w}{a}}$$

- Islands equal to or larger than 5 cm lock

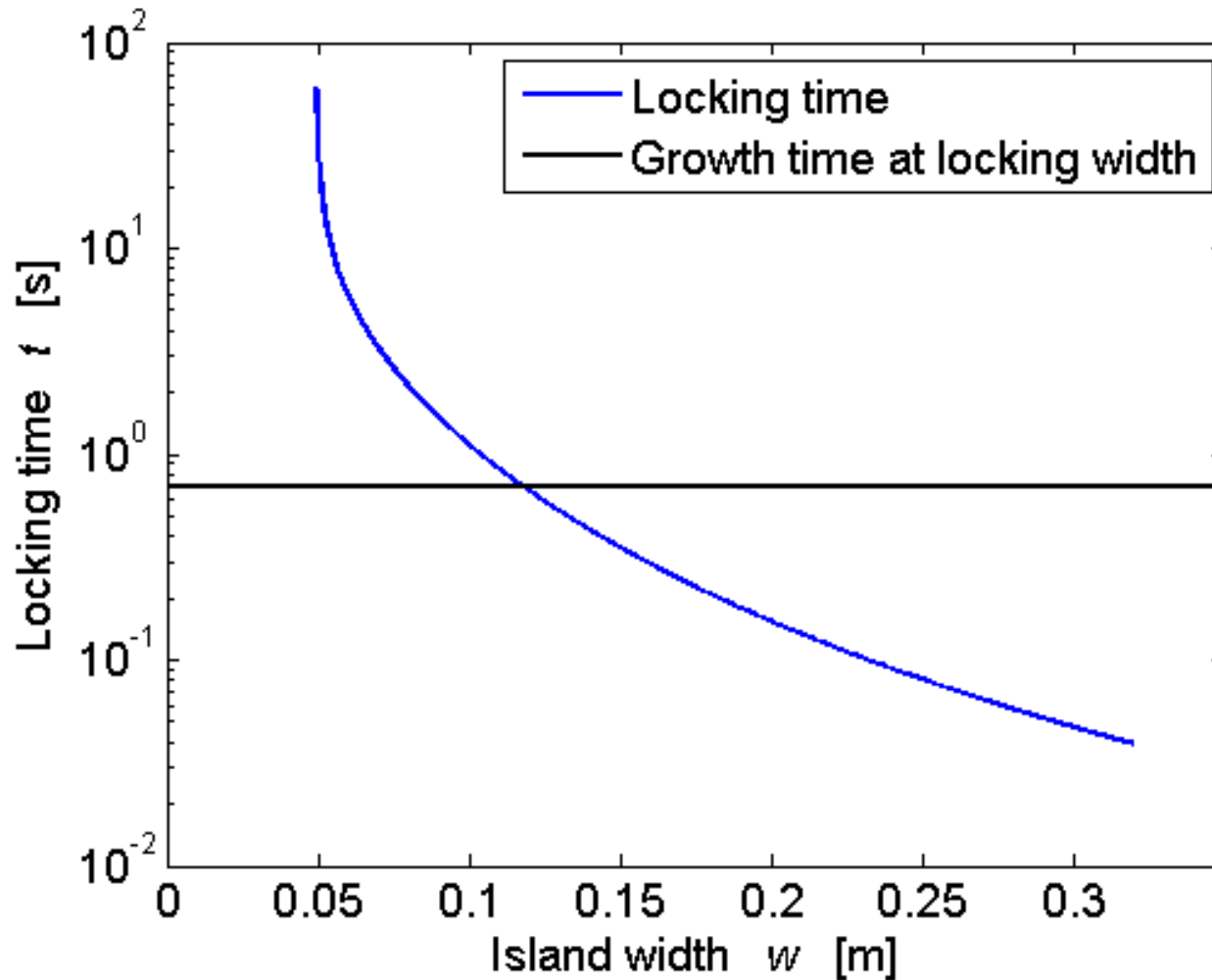


Locking of $q=2/1$ modes





Locking time comparable to growth time





Island growth

- Generalized Rutherford Equation
- Classical growth rate

$$\frac{\tau_r}{r_s} \frac{dw}{dt} = r_s \Delta'_0$$



Island growth

- Generalized Rutherford Equation
- Classical growth rate
- Neoclassical bootstrap growth rate
 - ◆ Flattening of pressure profile leading to a decreased bootstrap current

$$\frac{\tau_r}{r_s} \frac{dw}{dt} = r_s \Delta'_0 + \frac{16 \mu_0 L_q r_s j_{BS}}{B_p \pi} \frac{4}{3w} f\left(\frac{w}{w_{\text{marg}}}\right)$$



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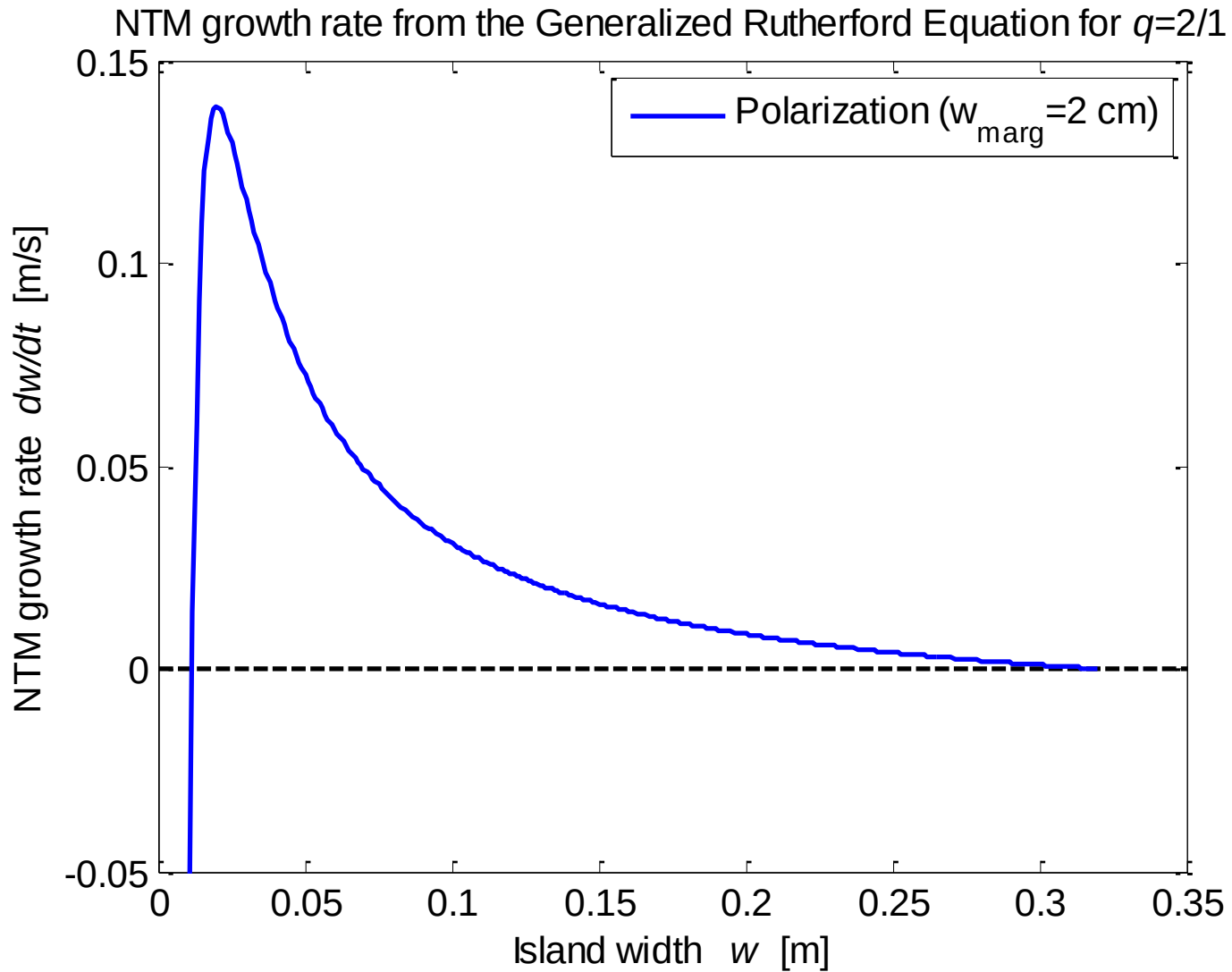
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- Classical growth rate found by relating it to the bootstrap term

$$\Delta'_0 = -\Delta'_{BS} (w = w_{\text{sat}})$$

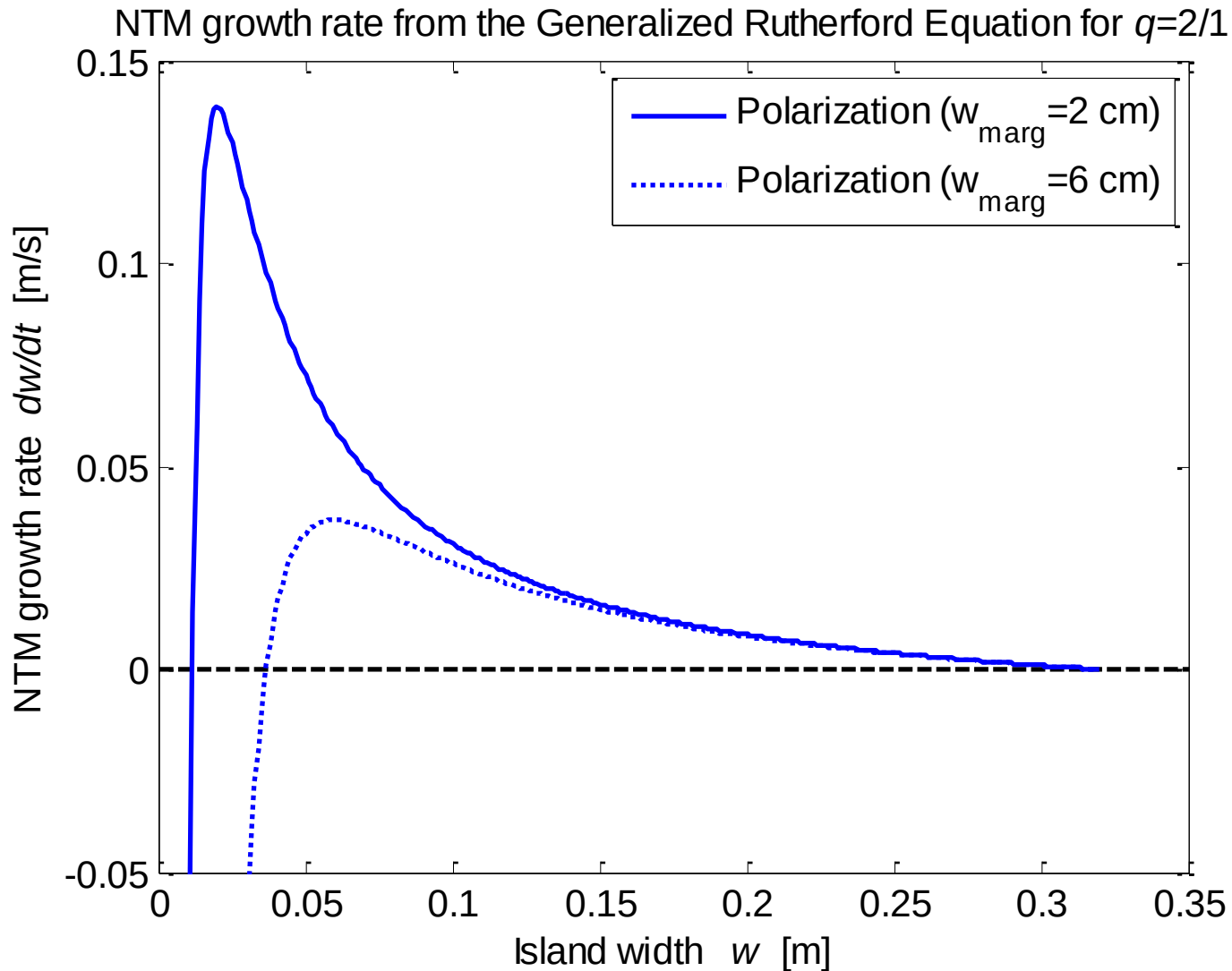


Bootstrap term models



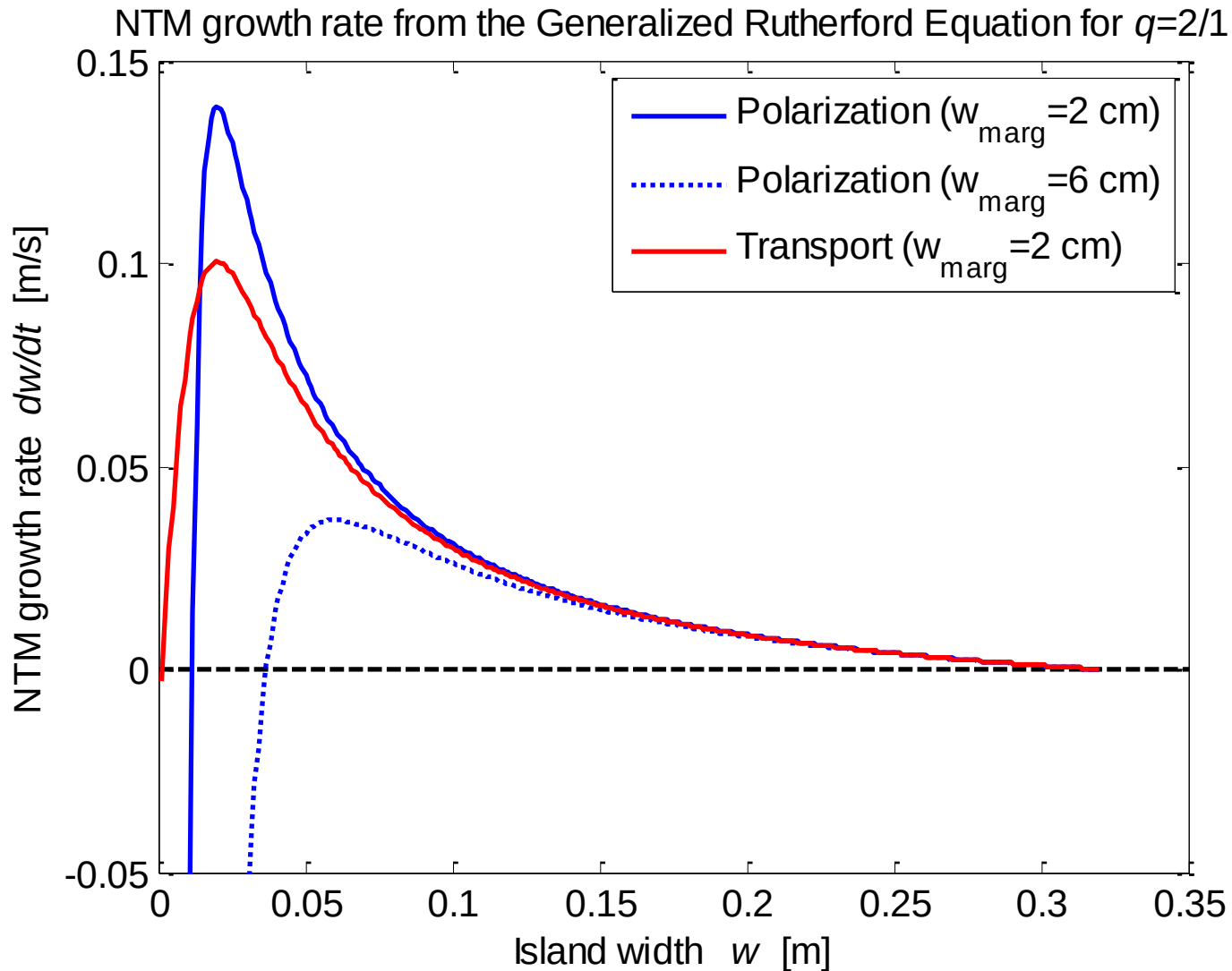


Bootstrap term models



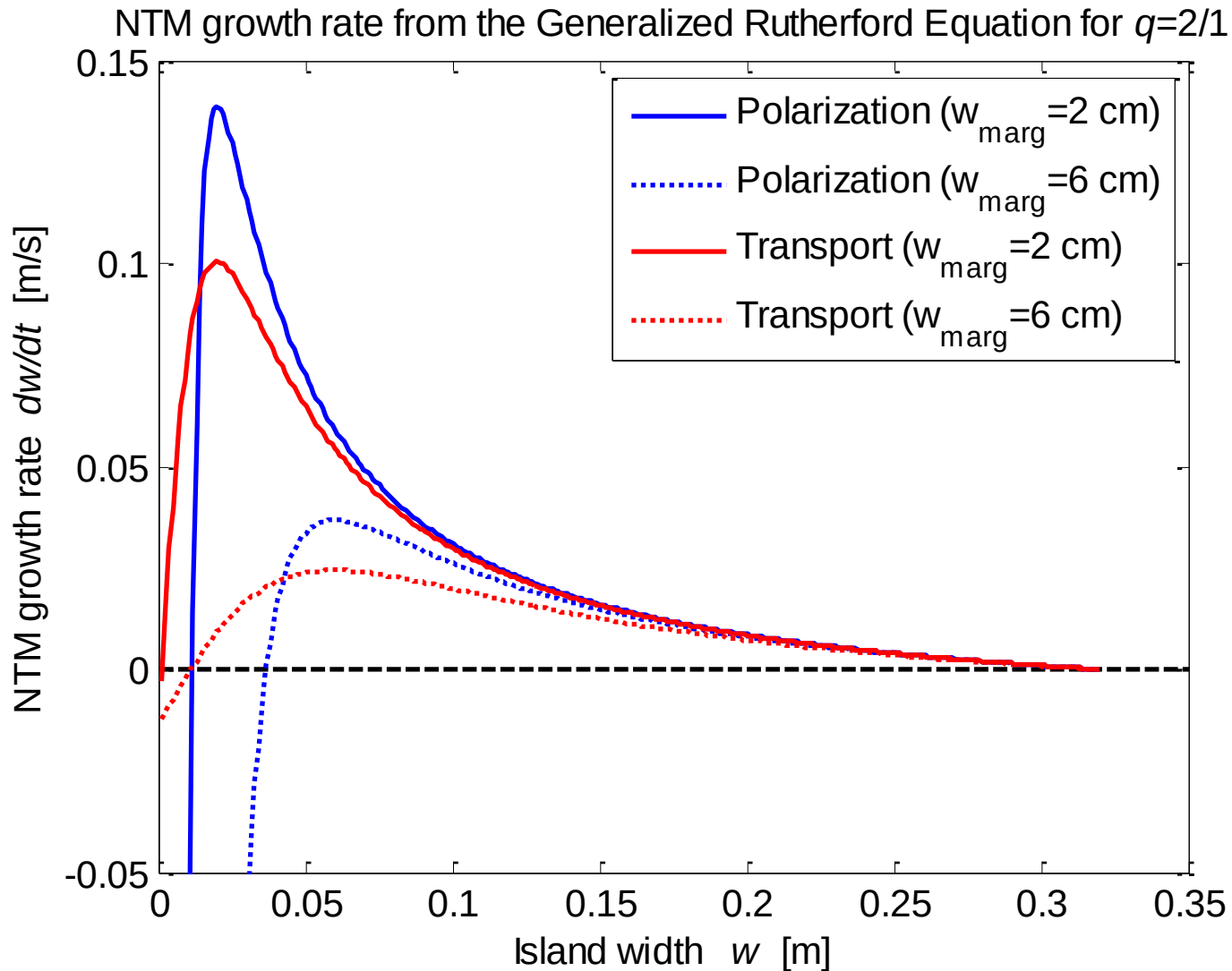


Bootstrap term models



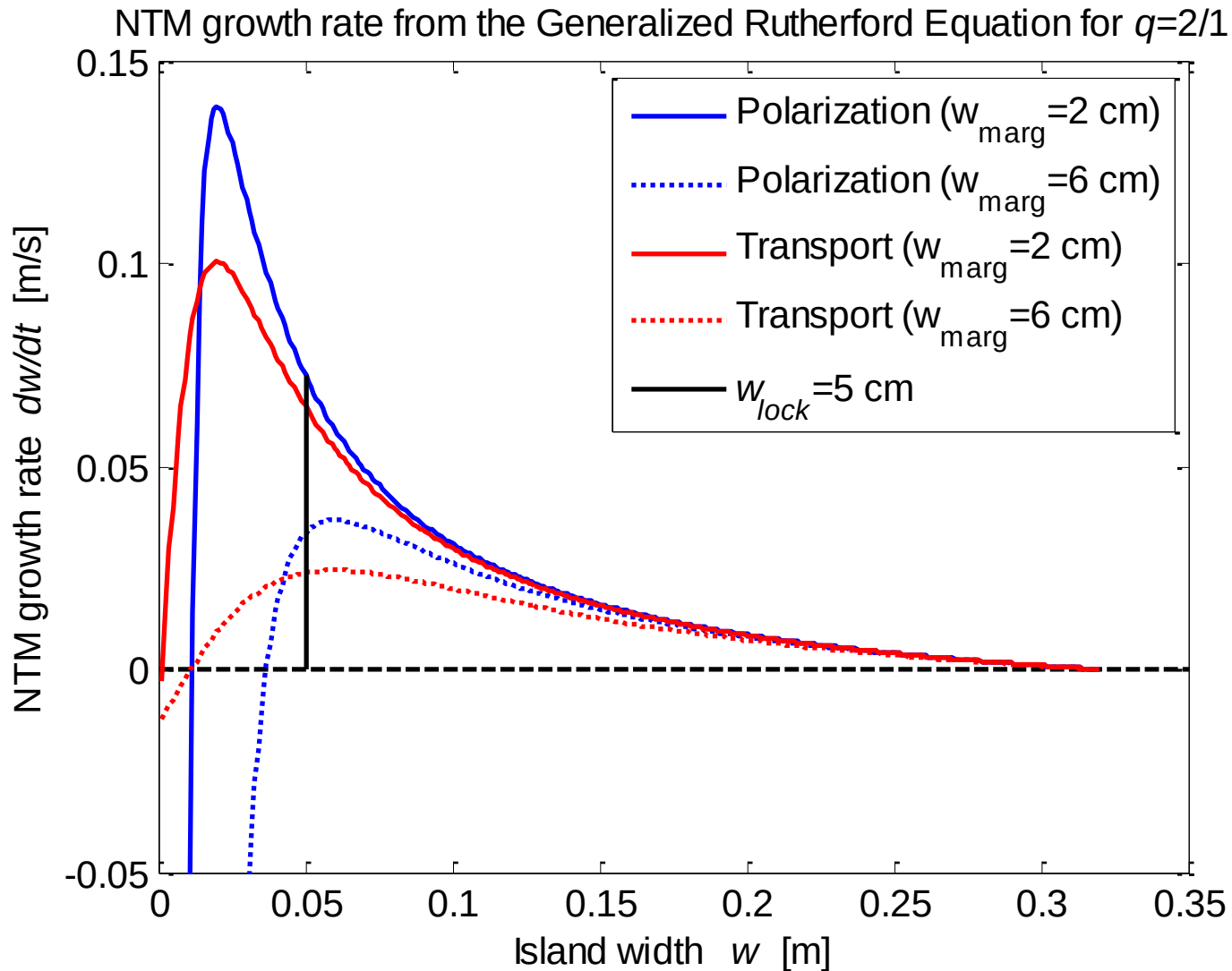


Bootstrap term models





Bootstrap term models

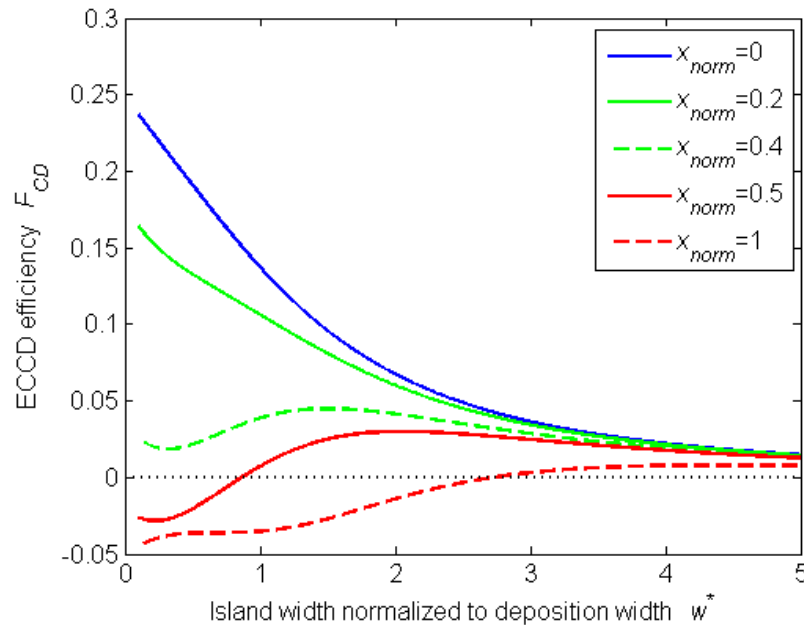




Electron Cyclotron Current Drive

$$\frac{\tau_r}{r_s} \frac{dw}{dt} = r_s \Delta'_0 + r_s \Delta'_{BS} + r_s \Delta'_{CD}$$

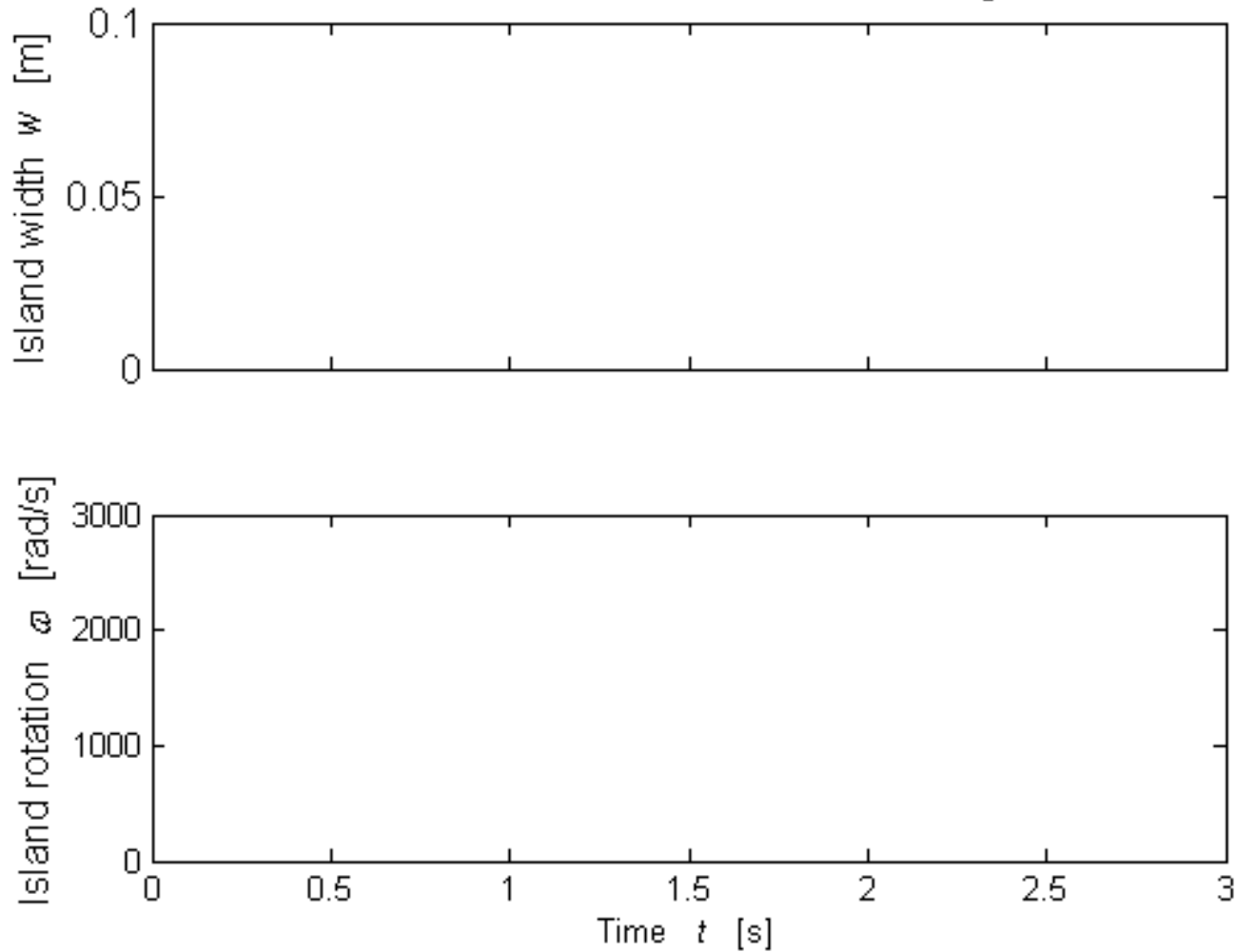
$$r_s \Delta'_{CD} = -K_{CD} P_{EC} F_{CD} \left(w^* = \frac{w}{w_{dep}}, x_{norm} = \frac{x_{dep}}{\max(w, w_{dep})} \right)$$





Simulation example

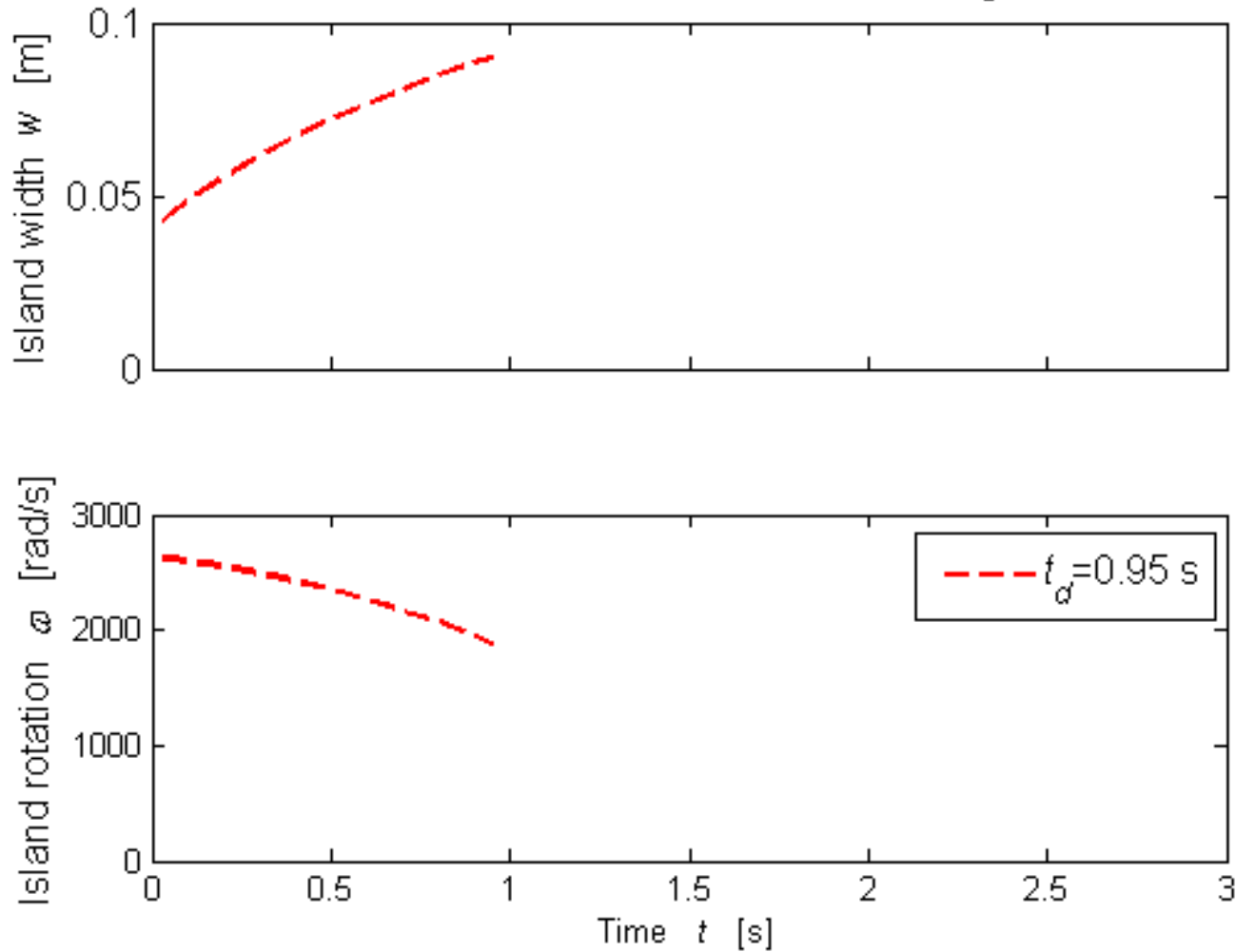
$q=2/1$ $w_{seed}=4$ cm (polarization model $w_{marg}=2$ cm)





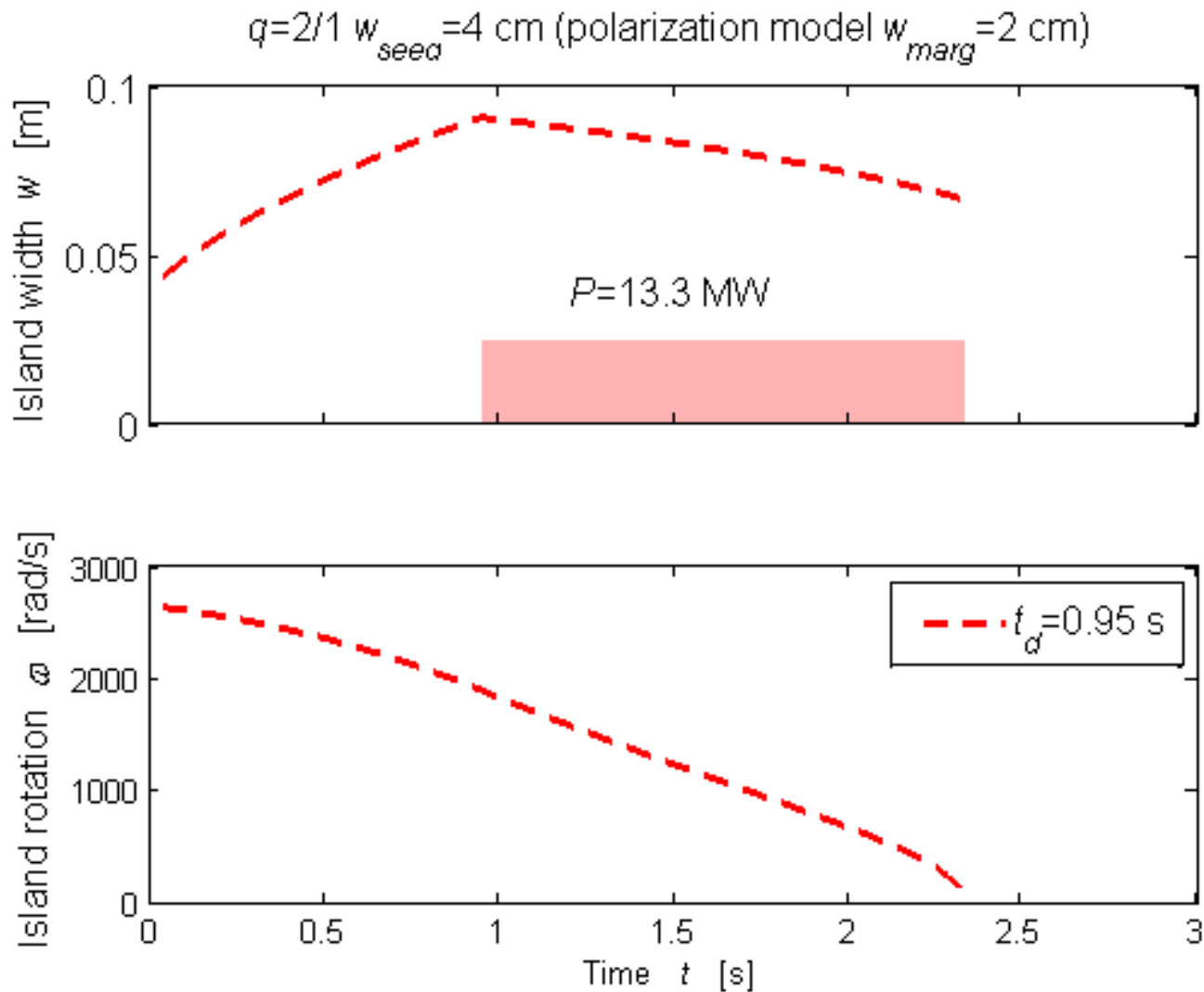
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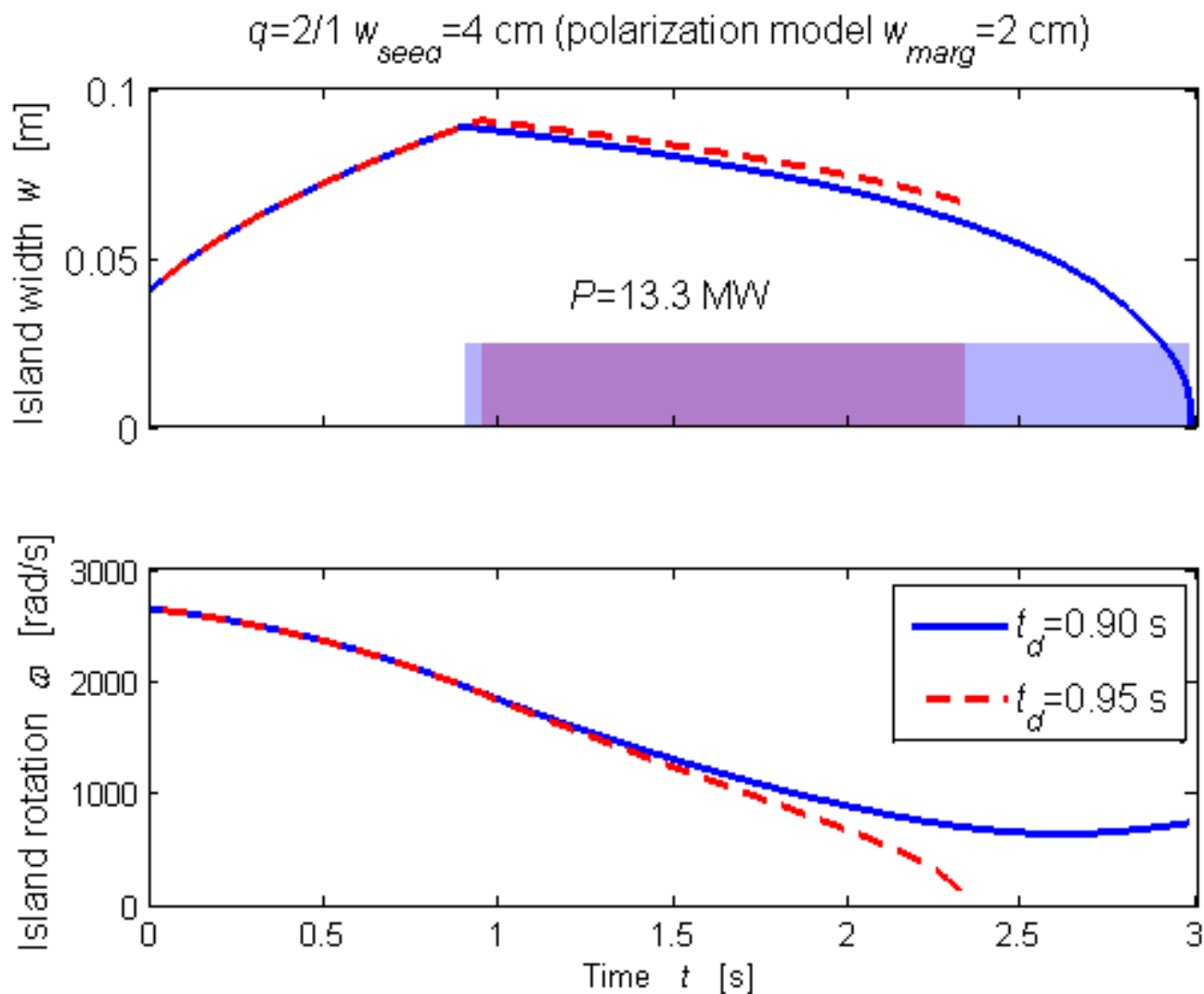


Simulation example



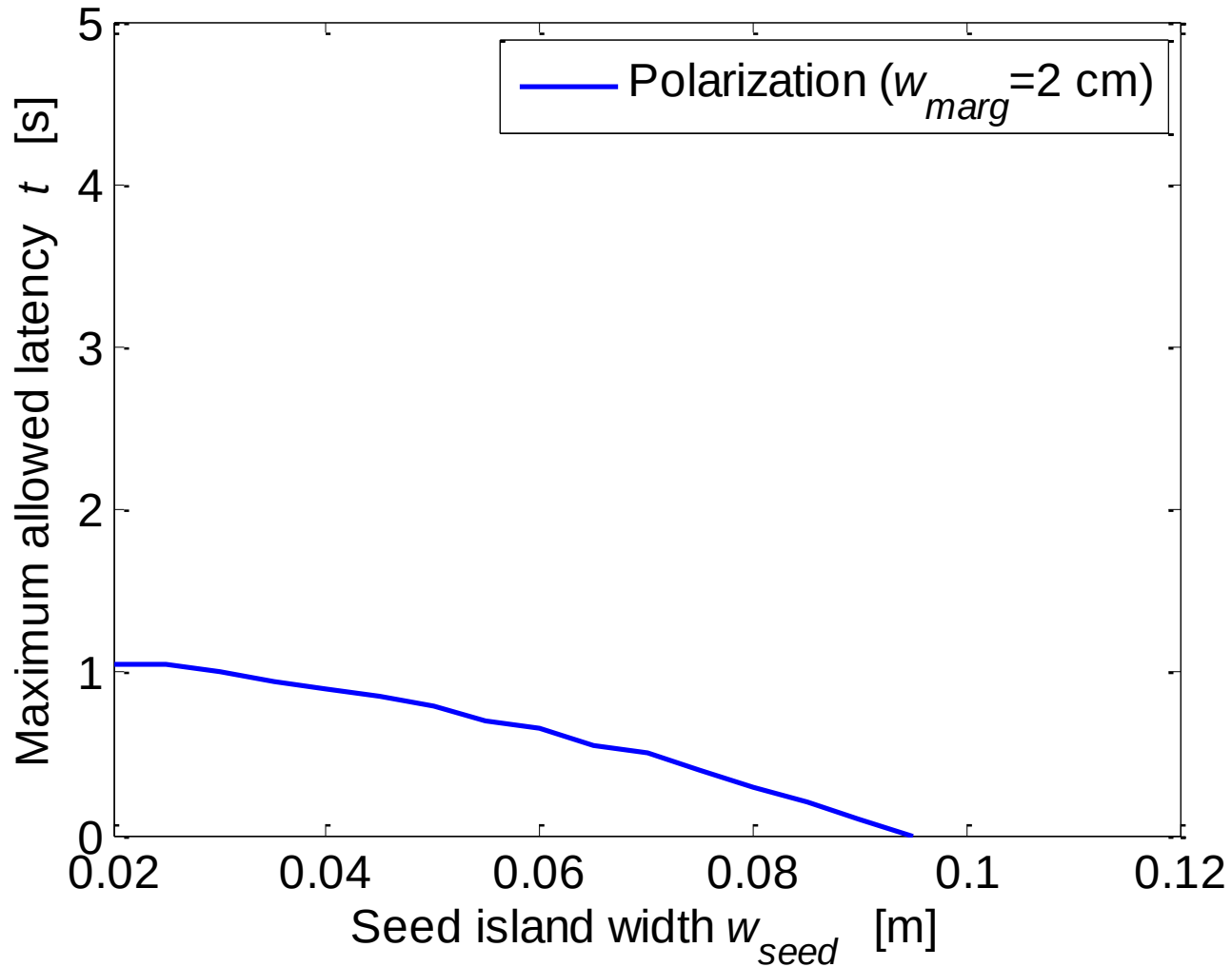


Simulation example



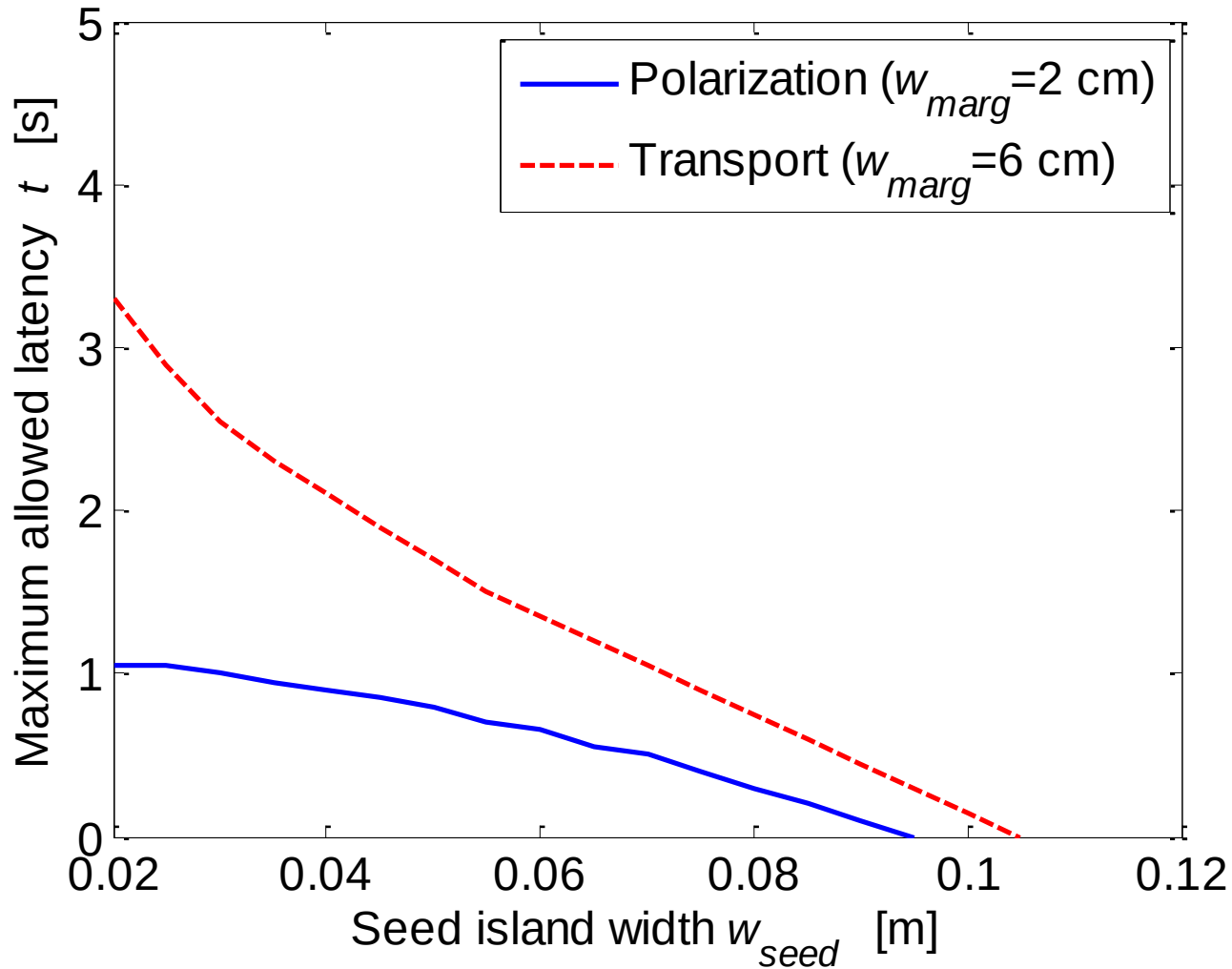


Maximum allowed latency



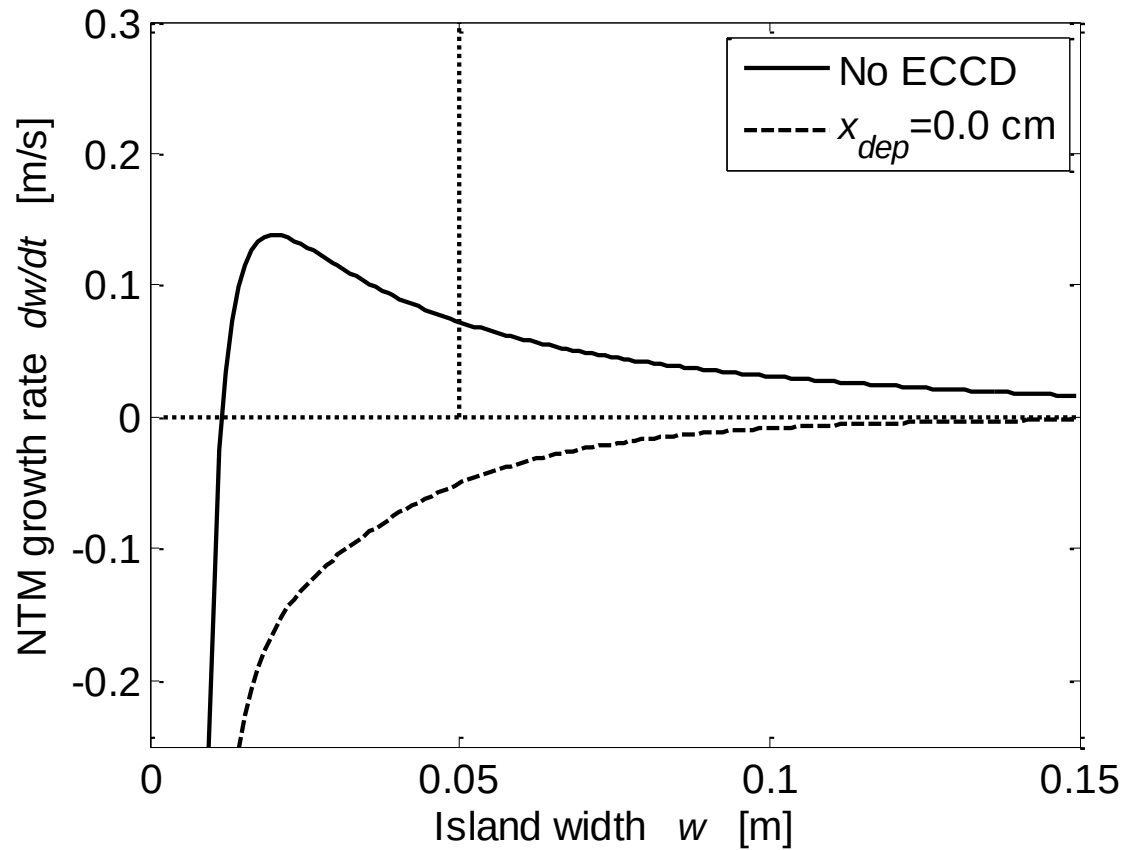


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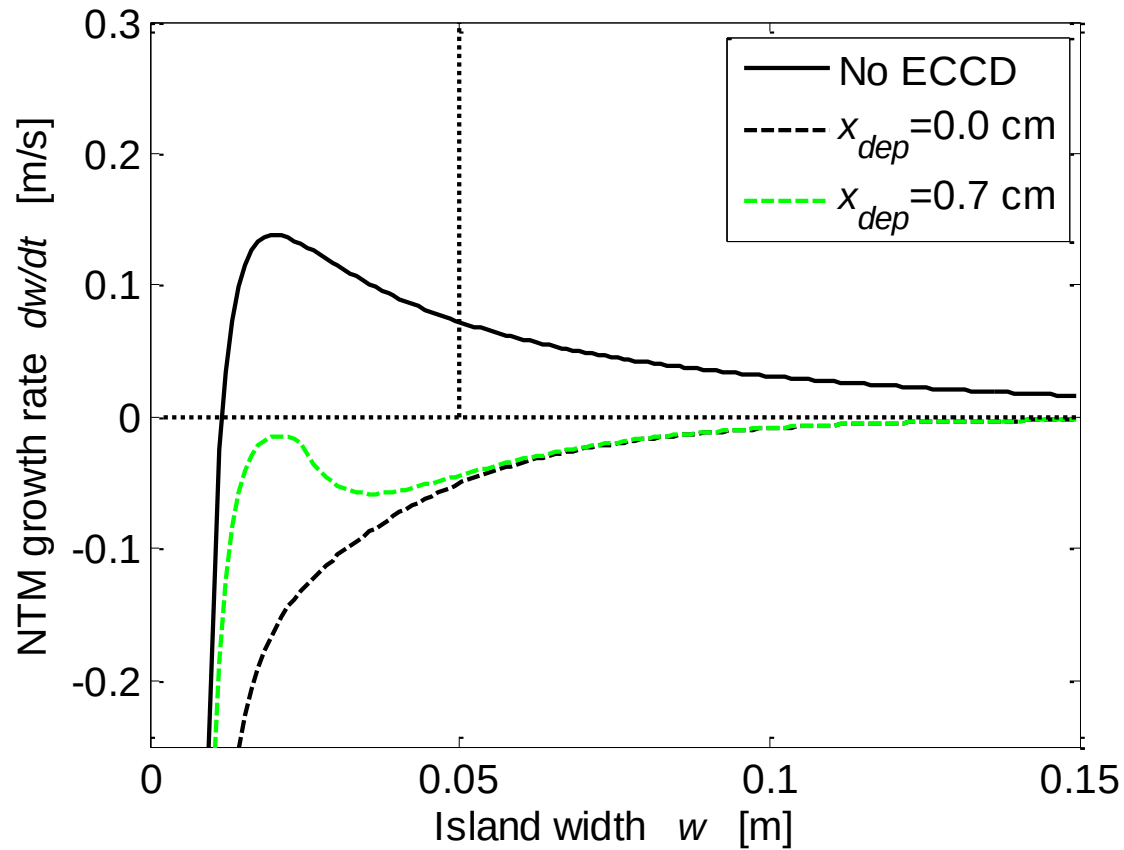


Effect of misalignment on island growth



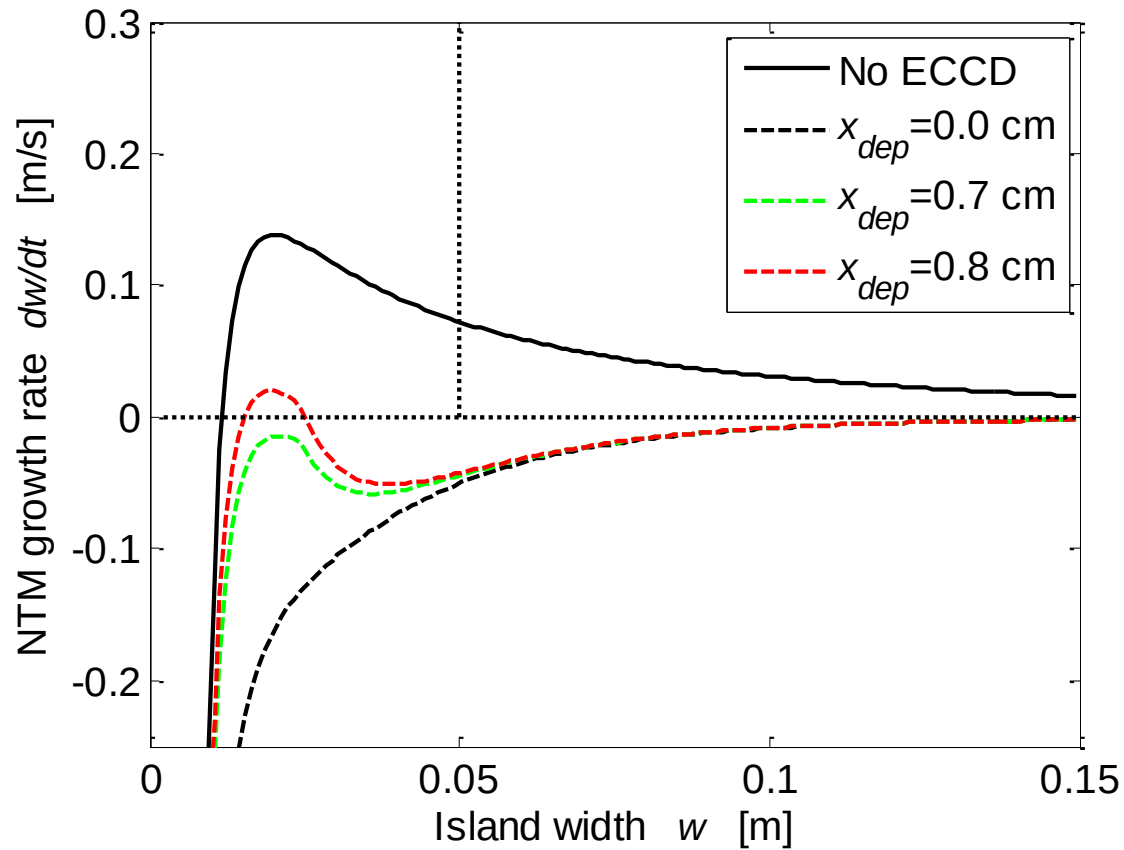


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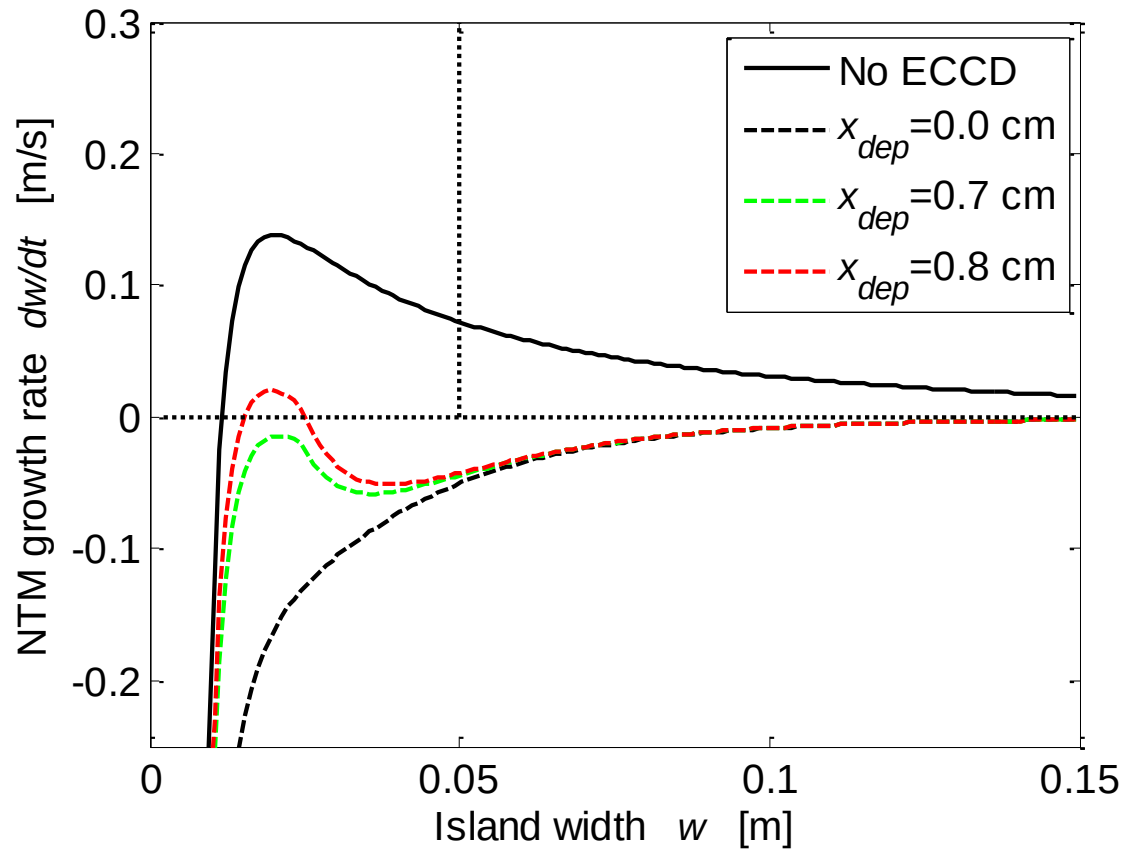


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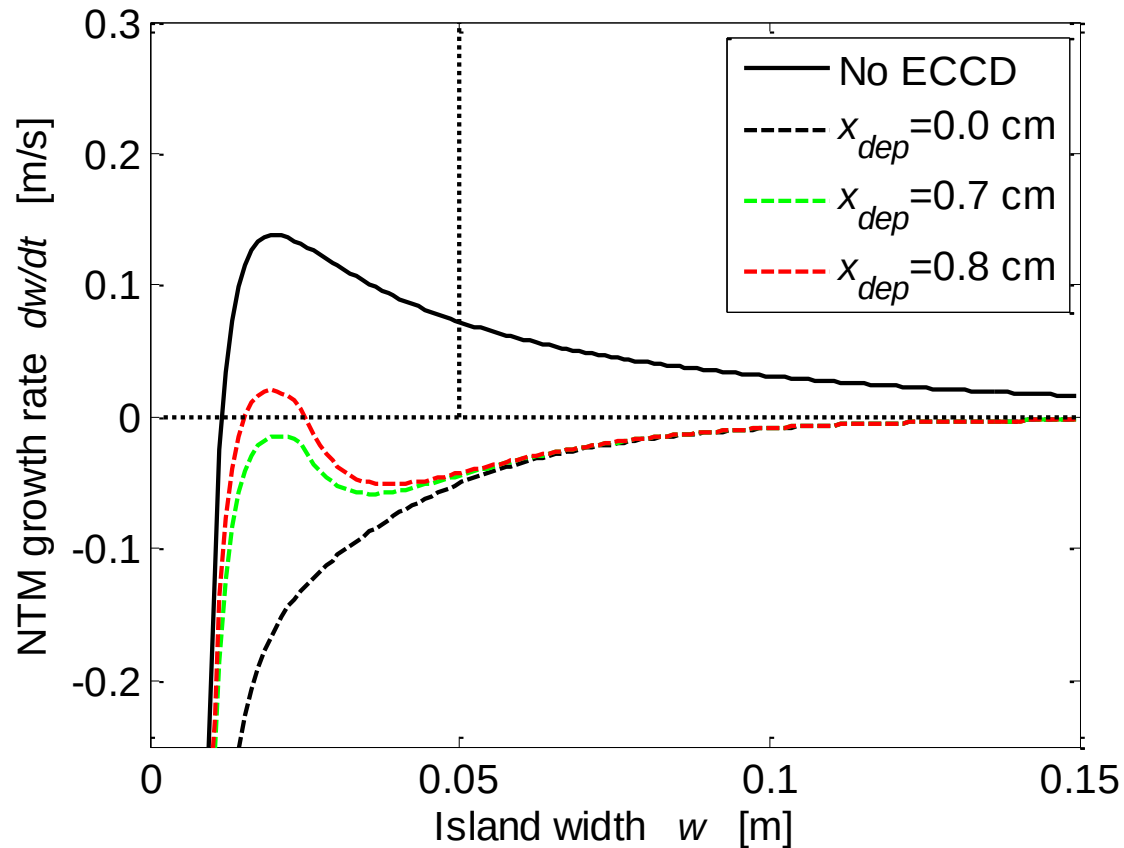
Effect of misalignment on island growth



- Maximum allowed deviation 0.7 cm to 1.0 cm



Effect of misalignment on island growth



- Maximum allowed deviation 0.7 cm to 1.0 cm
- No effect on latency



Conclusions

Due to limited actuator span, mode locking should be avoided

- Dependence of rotation on width requires combined model
- Maximum allowed latency in order of 1 second
- Maximum allowed deviation 0.7 cm to 1.0 cm from GRE
 - ◆ Misalignment does not affect latency
- Similar results for 3/2 NTM
- Results relevant for design of ITER NTM controller
 - Reported mirror settling time of 2.5 s is longer





Terminology

- Maximum allowed latency = the longest time between island seeding and start of ECCD deposition that results in full suppression of the island before mode-locking
- Mode-locking = stop of the island rotation, this means that the island locks to the error fields
- x_{dep} = radial misalignment related to the resonant surface position
- Island width = Average of island width on LFS and HFS in the equatorial plane
- Locking time = the time it takes for an island of constant width to stop rotating



Bootstrap models

$$\begin{aligned} f_{tra}(w, w_{marg}) &= \left(\frac{w^2}{w^2 + w_{marg}^2} \right) \\ f_{pol}(w, w_{marg}) &= \left(1 - \frac{w_{marg}^2}{3w^2} \right) \end{aligned}$$

Simulation parameters

	Constants and ITER parameters		
μ_0	$4\pi \cdot 10^{-7} \frac{\text{N}}{\text{A}^2}$		Permeability of free space ⁶⁸
R_0	6.2 m		Major radius ⁵⁷
a	2.0 m		Minor radius ⁵⁷
κ	1.7		Plasma elongation ⁵⁷
Z_{eff}	1.7		Effective charge ^{69,70,71,72}
	NTM parameters		
	$q = 2/1$	$q = 3/2$	
r_s	1.55 m	1.3 m	Position of the resonant surface ²²
$j_{BS}(r_s)$	$73 \frac{\text{kA}}{\text{m}^2}$	$94 \frac{\text{kA}}{\text{m}^2}$	Bootstrap current(cite Bertelli forthcoming) ⁶³
$T_e(r_s)$	5.6 keV	7.6 keV	Electron temperature ²²
$B_p(r_s)$	0.97 T	1.07 T	Poloidal magnetic field ²²
$L_q(r_s)$	0.87 m	0.88 m	Gradient length of the q-profile ²²
w_{marg}	2-6 cm	2-6 cm	Marginal island width ⁶ (cite Bertelli forthcoming)
w_{sat}	32 cm	25 cm	Saturated island width ⁶
w_{dep}^{LSM}	2.4 cm	3.7 cm	Deposition width at flux surface with LSM TORBEAM simulation by Bertelli et. al.
$j_{CD,W}^{LSM}$	$1.32 \cdot 10^{-2} \frac{\text{A}}{\text{m}^2\text{W}}$	$1.22 \cdot 10^{-2} \frac{\text{A}}{\text{m}^2\text{W}}$	Current drive density per watt with LSM TORBEAM simulation by Bertelli et. al.
w_{dep}^{USM}	3.9 cm	5.5 cm	Deposition width at flux surface with USM TORBEAM simulation by Bertelli et. al.
$j_{CD,W}^{USM}$	$9.62 \cdot 10^{-3} \frac{\text{A}}{\text{m}^2\text{W}}$	$1.07 \cdot 10^{-2} \frac{\text{A}}{\text{m}^2\text{W}}$	Current drive density per watt with USM TORBEAM simulation by Bertelli et. al.
$\epsilon = \frac{r_s}{R_0}$	0.25	0.21	Inverse aspect ratio
η_{NC}	$1.44 \cdot 10^{-8} \Omega\text{m}$	$7.73 \cdot 10^{-9} \Omega\text{m}$	Neoclassical conductivity (equation 2.4)
τ_r^*	293 s	383 s	Resistive time scale (equation 2.3)

	$q = 2/1$	$q = 3/2$	
ω_0	$420 \cdot 2\pi \text{ rad/s}$	$578 \cdot 2\pi \text{ rad/s}$	Result of ITER scenario 2 simulations
τ_{A0}	$3.0 \mu\text{s}$		Assumes toroidal rotation of the island
τ_{M0}	$\tau_E = 3.7 \text{ s}$		Equal to ITER energy confinement time
τ_w	0.188 s	0.125 s	Resistive wall simulations with VALEN
C_1	$\frac{1}{14}$	$\frac{1}{29}$	Obtained through fits on DIII-D shots
C_2	20	12	Obtained through fits on DIII-D shots

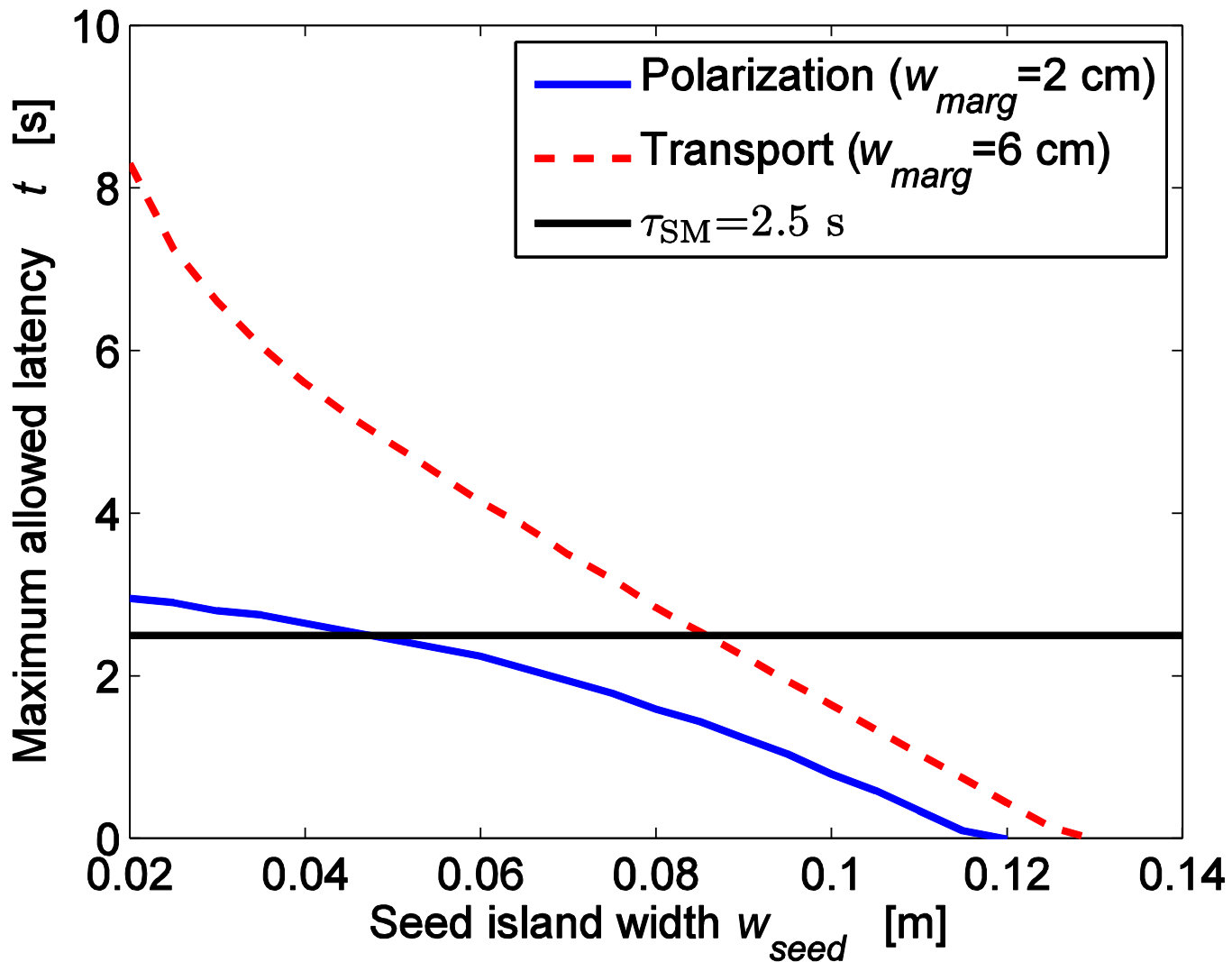


Simulation details

- Seed island size varied
- Delay between seeding and start of ECCD varied
- Largest delay that still results in full suppression before locking is the maximum allowed latency
- Simulation scenarios
 - ◆ Polarization 2 cm
 - ◆ Transport 6 cm
- Resolution: $dt=50$ ms and $dw_{\text{seed}}=0.5$ cm
- Implemented in MathWorks Simulink
 - ◆ Runga-Kutta 5th order with 4th order error estimate (var. step)
 - ◆ Rel error $1e-6$



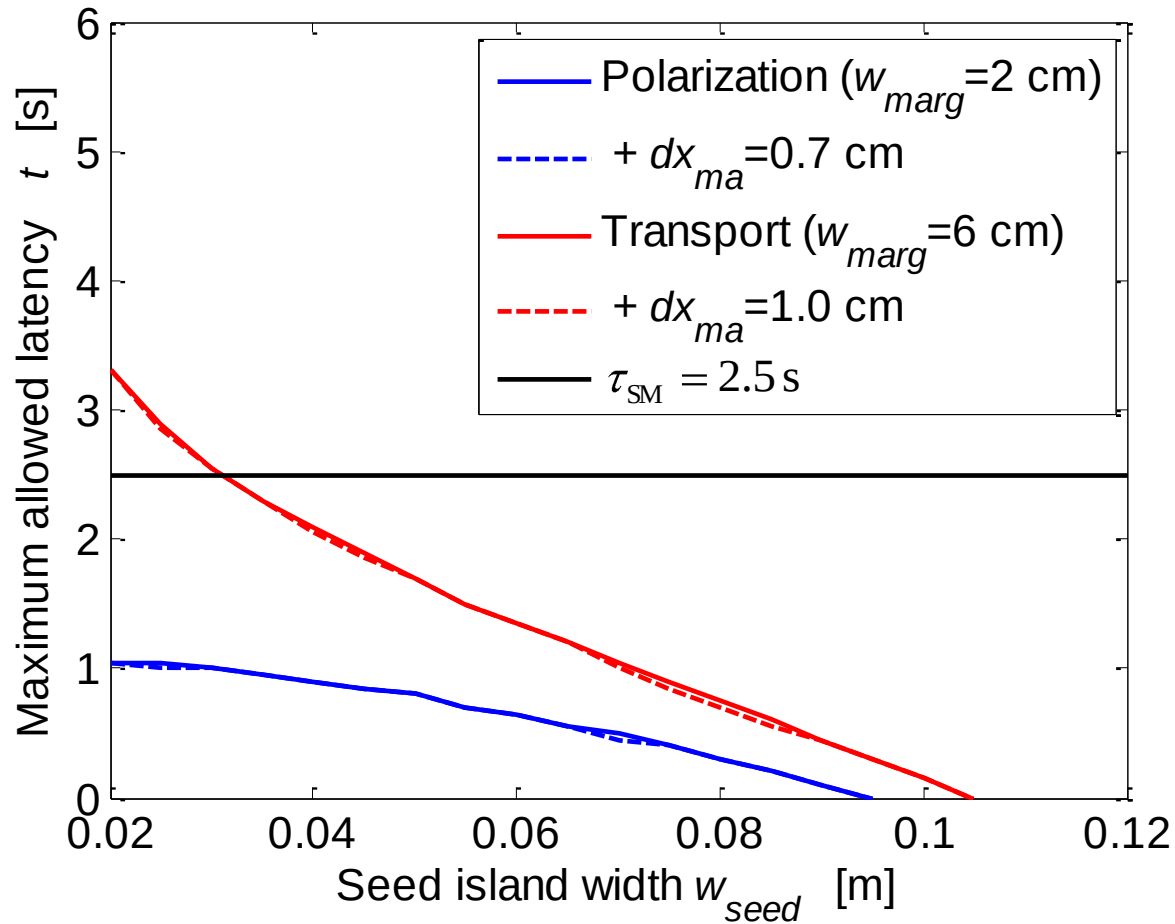
$q=3/2$ latency





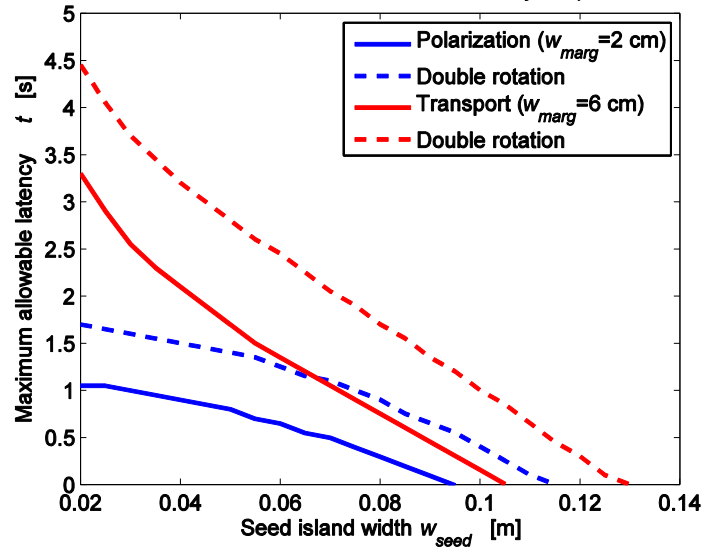
Effect of misalignment on latency

- No effect

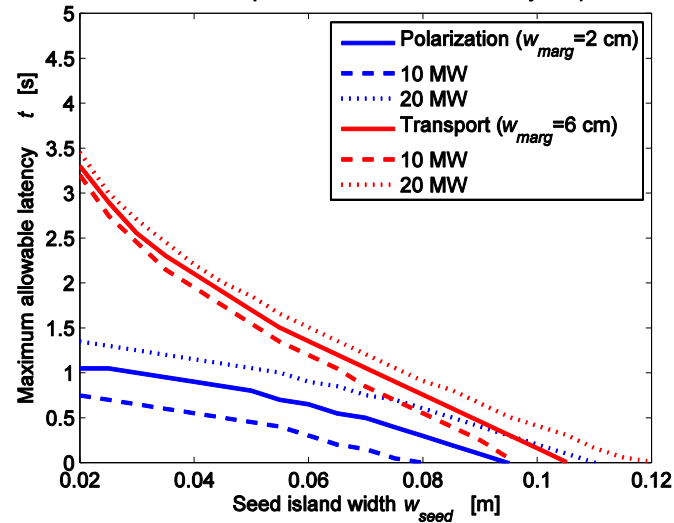


Extra simulations

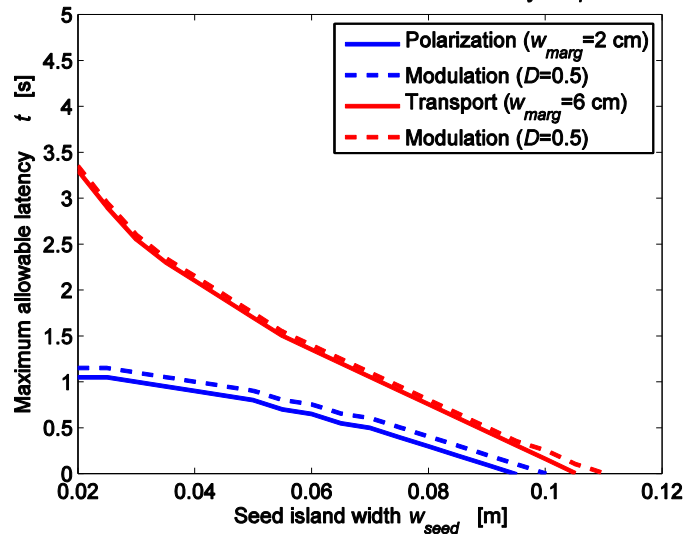
Effect of rotation on the allowable latency for $q=2/1$



Effect of ECCD power on the allowable latency for $q=2/1$



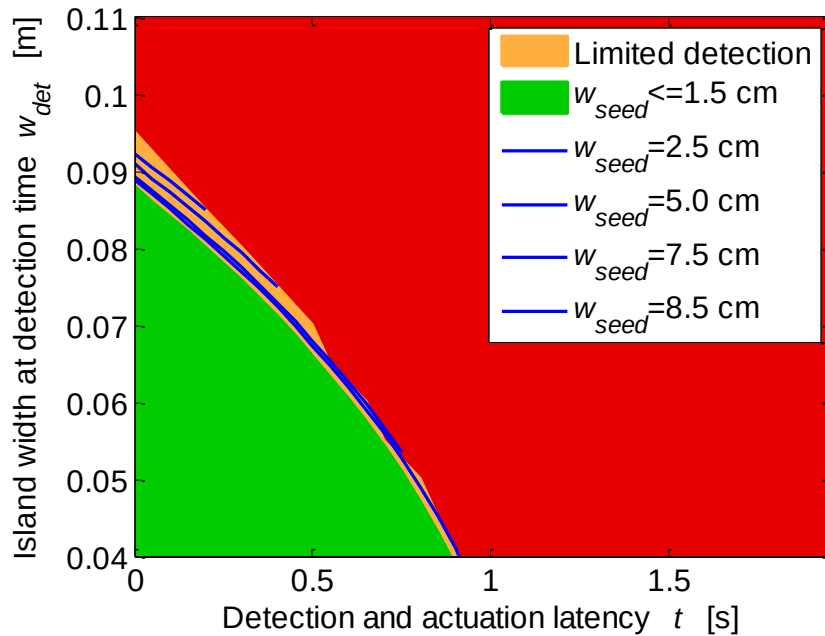
Effect of modulation on the allowable latency for $q=2/1$



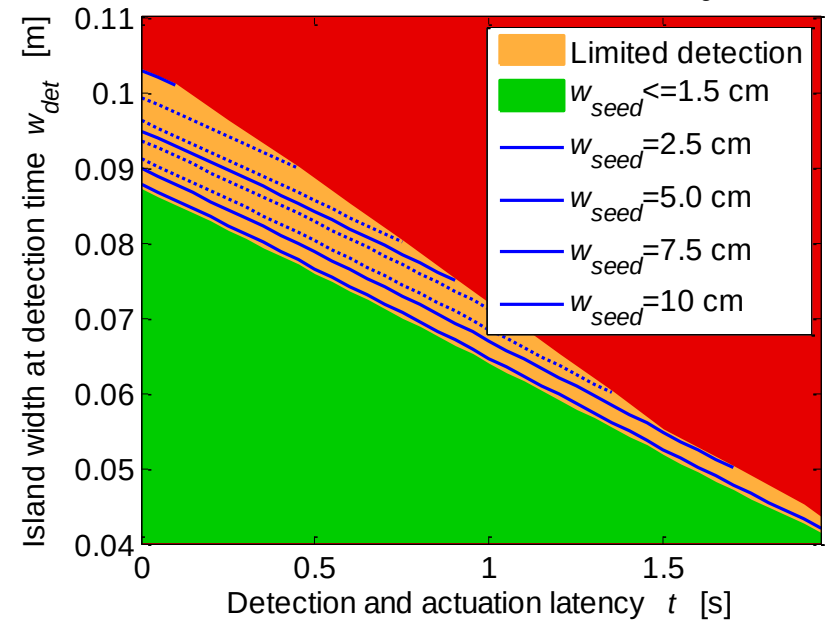


Stabilization maps $q=2/1$

Detection limits for $q=2/1$ polarization $w_{\text{marg}}=2 \text{ cm}$



Detection limits for $q=2/1$ transport $w_{\text{marg}}=6 \text{ cm}$





Tearing modes

- Flux surfaces characterized by safety factor

$$q = \frac{m}{n}$$

- Reconnection of magnetic field lines

- Rational values of q

- $q=2/1$ (and $q=3/2$)

- Affected by non-inductive current

