

Equilibrium Reconstruction without Axisymmetry

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Equilibrium Reconstruction

- Find the MHD equilibrium that is most consistent with the experimental data

$$\chi^2(\mathbf{p}) \equiv \sum_i \left(\frac{S_i^{observed}(\mathbf{d}) - S_i^{model}(\mathbf{p})}{\sigma_i} \right)^2$$

- Reconstruction parameters \mathbf{p}
 - Signals S
 - Square root of the variance σ
- Minimize $\chi^2(\mathbf{p})$ by changing the parameters of the model (equilibrium)
- At minimizing parameter values, the model is a good representation of the experiment
- Axisymmetric Equilibrium Reconstruction
 - Equilibrium comes from a Grad-Shafranov solution
 - EFIT and other codes
- Non-axisymmetric Equilibrium Reconstruction
 - V3FIT code – This talk
 - STELLOPT code – Sam Lazerson's talk at this workshop

V3FIT Code

- Design Goal - Fast
 - Want reconstructions between shots
 - Design Choice: one reconstruction uses one CPU
 - Design Choice: single executable – to allow tighter coupling to equilibrium solver
- Design Goal - Flexible
 - Easy to understand, maintain, and modify
 - Written in Fortran 95
 - Clear and consistent data flow – modular coding
- Design Goal – Extensible
 - Initial equilibrium solver - VMEC
 - Localize VMEC code assumptions, so that could use a different equilibrium solver in the future
 - Signals – magnetic diagnostics (original), limiters, soft x-rays, Thomson scattering, combinations_of_other_signals (coosig).
- “V3FIT: a code for three-dimensional equilibrium reconstruction”
 - J D Hanson, S P Hirshman, S F Knowlton, L L Lao, E A Lazarus, and J M Shields
 - Nucl. Fusion **49**, 075031 (2009).

Current and Planned Usage

- CTH – Compact Toroidal Hybrid -Auburn University
 - Steve Knowlton's talk, this workshop
- HSX – Helically Symmetric Experiment – U. Wisconsin
 - Invited talk at 2011 APS-DPP, John Schmitt
- LHD – Large Helical Device – Japan
 - Aaron Sontag (ORNL)
- RFX – Reversed Field Pinch – Padova, Italy
 - David Terranova et al., EPS 2011
- Recent Discussions
 - MST – Madison Symmetric Torus– U. Wisconsin
 - Alcator C-Mod – MIT
 - DIII-D – General Atomics

V3FIT/VMEC Features

- VMEC – flexible and extensible mechanism for specifying profiles
- V3FIT – posterior parameter variance computation
- V3FIT – Signal Effectiveness computation
- V3FIT – New diagnostics - Soft x-ray, Thomson scattering
- V3FIT – flexible mechanism for model extension
- MAKEGRID – rotate and shift external coils

Pressure and Current Profiles in VMEC

- VMEC requires a pressure profile and either a current or iota profile
- Original specification – coefficients of power series

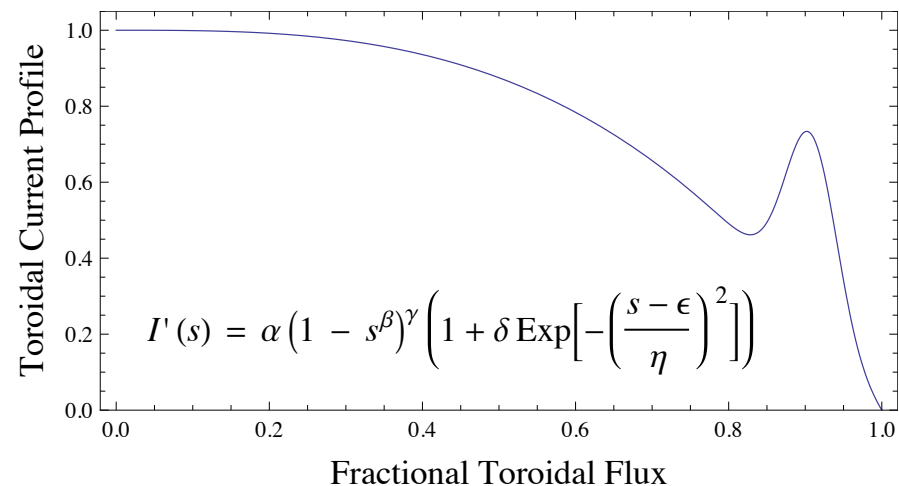
$$p(s) = a_0 + a_1 s + a_2 s^2 + \dots$$

– Radial coordinate s – fractional toroidal (poloidal) flux

- Now – also specify a parameterization type
- Different types cause reinterpretation of coefficient array

– `pmass_type = 'two_power'` $p(s) = a_0 \left(1 - s^{a_1}\right)^{a_2}$

- Simple code change to add new parameterization type
- Can also specify using spline positions and amplitudes



Probability and Inverse Problems

$$\begin{aligned}\chi^2 &= \sum_i \left(\frac{S_i^{model}(p_j) - S_i^{observe}}{\sigma_i} \right)^2 \\ &= \left(\vec{S}^{model}(\vec{p}) - \vec{S}^{observe} \right)^T \cdot \underline{\underline{C}}^{-1} \cdot \left(\vec{S}^{model}(\vec{p}) - \vec{S}^{observe} \right) \\ \underline{\underline{C}}^{-1} &= \begin{pmatrix} \sigma_1^{-2} & 0 & 0 \\ 0 & \sigma_2^{-2} & 0 \\ 0 & 0 & \dots \end{pmatrix} \quad (\underline{\underline{C}})_{ij} = \sigma_i \sigma_j \delta_{ij}\end{aligned}$$

- C – Covariance matrix of the signal noise
- Specifies a probability distribution on space of signals.
- Assumption that signal noise is uncorrelated \Leftrightarrow C diagonal

Jacobian and Posterior Parameter Variance

- The Jacobian relates small changes in reconstruction parameters to small changes in signals:

$$(\underline{J})_{ij} = \frac{\partial S_i^{\text{model}}(\vec{p})}{\partial p_j} \quad \delta \vec{S} = \underline{J} \cdot \delta \vec{p}$$

- V3FIT computes a finite-difference approximation to the Jacobian in the course of minimizing chi-squared
- The Jacobian propagates a (Gaussian) probability distribution from *signal* space to *parameter* space

$$\underline{\underline{C_p^{-1}}} = \underline{J}^T \cdot \underline{\underline{C^{-1}}} \cdot \underline{J}$$

- C_p is the posterior parameter covariance matrix.
- The diagonal elements of C_p are the posterior parameter variances.

$$\sigma_{pj} = \sqrt{\left(\underline{\underline{C_p}}\right)_{jj}}$$

- C_p need not be diagonal – the reconstructed parameters may be correlated.
- V3FIT computes and prints the posterior parameter variances.

Signal Effectiveness

- Proposed measure of the effectiveness of a signal:

$$R_{ji} = \frac{d \ln \sigma_{p,j}}{d \ln \sigma_i} = \frac{\sigma_i}{\sigma_{p,j}} \frac{d \sigma_{p,j}}{d \sigma_i}$$

- Logarithmic derivative of the j th posterior parameter σ_p with respect to the i th signal σ
- How much will the j th posterior σ_p improve if the noise level on the i th signal is reduced?
- Motivation – Signal Effectiveness can help answer important questions:
 - I wish to improve the measurement of the current profile. What diagnostics should I add?
 - Magnetic diagnostics break. For which magnetic diagnostics do I need a spare, ready and waiting to put on the machine?
 - I'm building a new stellarator. What diagnostics should I build?

Signal Effectiveness R_{ji}

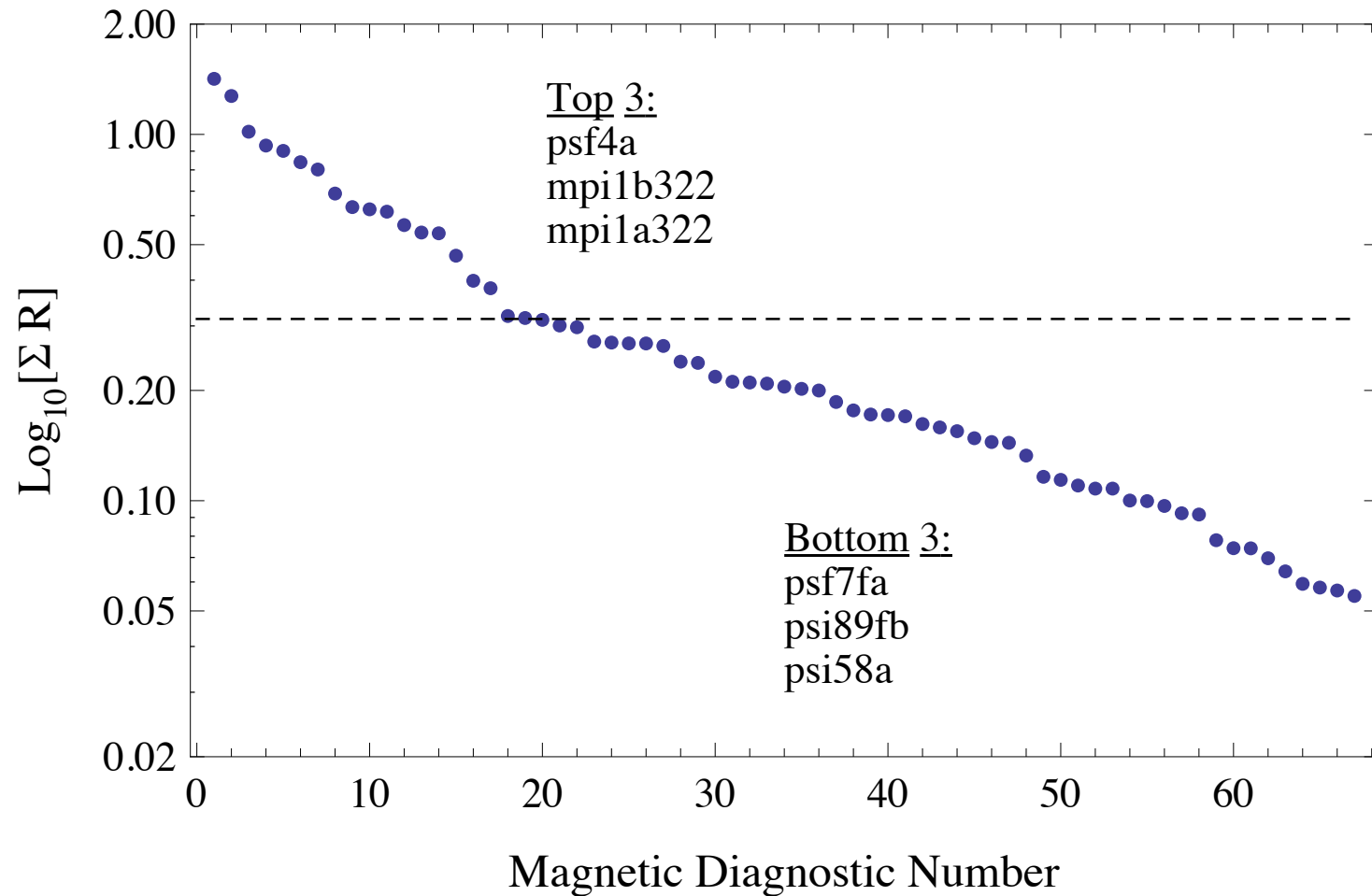
- With diagonal signal covariance C , the signal effectiveness R_{ji} is readily computable from the Jacobian $J_{ij} = \partial S_i^m / \partial p_j$.
- R_{ji} is dimensionless and non-negative.
- R_{ji} is normalized, $\sum_{i(\text{signals})} R_{ji} = 1$
- R_{ji} is *local*. It only contains information about what happens near a particular point in parameter space.
 - May want an appropriate average over parameter space.
- Signal Effectiveness depends on the whole set of diagnostics and choices of reconstruction parameters.
- V3FIT computes and prints the signal effectiveness matrix.
- CTH – have used signal effectiveness for planning of new diagnostics.
- HSX – Enrico Chlecowitz is using the signal effectiveness for planning new magnetic diagnostics.

Signal Effectiveness Example from DIII-D

- Reconstruction detailed in Nucl. Fusion 2009 paper
- Signals – magnetic diagnostics – 67 signals
 - 31 partial Rogowski coils
 - 36 flux loops
- Reconstruction Parameters – 21 parameters
 - 18 F-coil currents
 - Total plasma current
 - Pressure scale
 - One current profile shape parameter
- For each diagnostic, sum the Signal Effectiveness over all 21 reconstruction parameters
- Max - Average - Min SumSE is 1.42 – 0.313 – 0.055
- Factor of 25 between least and most effective diagnostic

DIII-D

Signal Effectiveness, Summed over 21 Reconstruction Parameters



Soft X-rays

$$S = \int \varepsilon_{sxr}(\underline{x}') d\ell = \int \left[\int A(E) \tau(E) \frac{n_e^2(x')}{\sqrt{T_e(x')}} \exp\left(-\frac{E}{T_e(x')}\right) \right] d\ell$$

- Line integral is straight path through plasma region
- Soft X-ray emissivity ε_{sxr} is *assumed* to be constant on a flux surface
- The model signal depends on *more* than just the MHD equilibrium
 - Radial profile of the emissivity
 - Radial profiles of the electron density and electron temperature

Thomson Scattering

$$S = T_e(\underline{x}_{diagnostic})$$

- Position of the temperature measurement is known
- To tie this in to the equilibrium *assume* that the electron temperature is constant on a flux surface.
- The model signal depends on *more* than just the MHD equilibrium
 - Radial profile of the electron temperature

Plasma Model and Radial Profiles

- For magnetic diagnostics, the only plasma information needed comes from the MHD equilibrium
- For other diagnostics, we need to *augment* the MHD equilibrium.
- The V3FIT model of the plasma now consists of the MHD equilibrium, and *parameterized-profiles* of
 - Soft x-ray emissivity
 - Electron density
 - Electron temperature
- Other *parameterized-profiles* can easily be added (n_i, T_i, p_{hot}).
- *Parameterized-profiles* have a type specification (“two-power”, “truncated-Gaussian”, “spline”) that determines the meaning of the parameterized-profile parameters.
- The parameters of a *parameterized-profile* can be used as reconstruction parameters.

Choices are Explicit in V3FIT

- Soft X-rays

- model_sxrem_type = 'pp_sxrem'

Parameterized profile of the soft x-ray emissivity

$$S = \int \varepsilon_{sxr}(\underline{x}') d\ell$$

- model_sxrem_type = 'pp_ne_vmec_p'

Parameterized profile of the electron density, use the MHD pressure

$$\varepsilon_{sxr} = \alpha n_e^2 \sqrt{T_e} \quad n_e T_e = f_e p_{VMEC}$$

- Thomson Scattering

- Model_te_type = 'pp_te'

Parameterized profile of the electron temperature

- model_te_type = 'pp_ne_vmec_p'

Parameterized profile of the electron density, use the MHD pressure

$$n_e T_e = f_e p_{VMEC}$$

External Magnetic Fields

- Free Boundary equilibrium in VMEC – Need External B
 1. Geometric model of the external coils
 2. Rotate and shift coils from their nominal positions
 3. Biot-Savart to compute B on a grid, B from each coil separately
 4. VMEC reads B information from file, uses linear combination of B fields

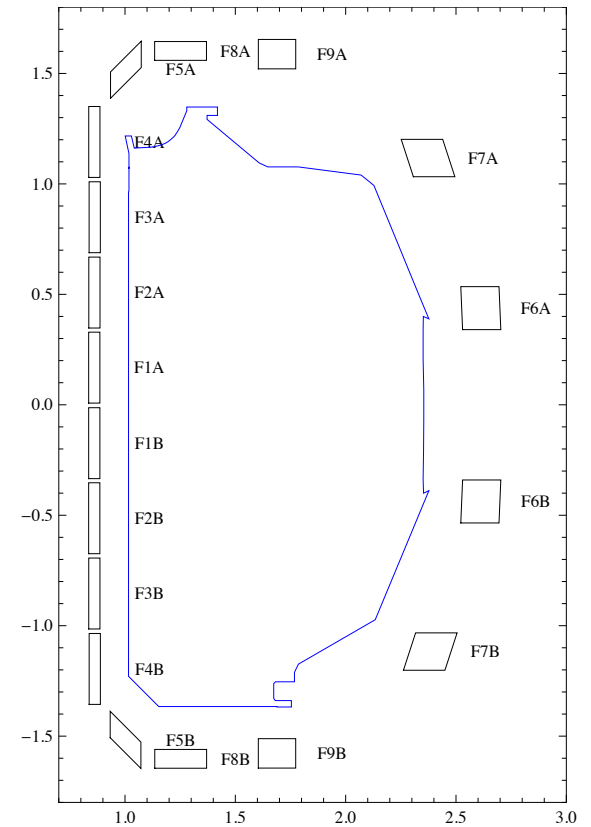
$$\vec{B}(R, \phi, Z) = \sum_i I_{extcur}^i \vec{B}_i(R, \phi, Z)$$

- Step 2 – added recently
- Shifts and rotations for DIII-D:
 - “Anomalies in the applied magnetic fields in DIII-D and their implications for the understanding of stability experiments” J.L. Luxon, M.J. Schaffer, G.L. Jackson et al., Nuclear Fusion **43** 1183 (2003).

Shift-Rotate Data for DIII-D

| Coil | d (mm) | Angle (°) | Tilt (°) | Angle (°) |
|-----------|--------|-----------|----------|-----------|
| F1A | 1.46 | 348.1 | 0.112 | 177.7 |
| F2A | 2.36 | 336.9 | 0.121 | 113.4 |
| F3A | 3.15 | 0.8 | 0.051 | 148.2 |
| F4A | 2.49 | 2.6 | 0.138 | 185.5 |
| F5A | 4.11 | 290.6 | 0.194 | 102.2 |
| F8A | 4.96 | 277.7 | 0.241 | 98.5 |
| F9A | 4.19 | 271.4 | 0.125 | 126.6 |
| F7A | 12.33 | 257.9 | 0.100 | 103.5 |
| F6A | 5.86 | 216.2 | 0.086 | 119.3 |
| F6B | 7.24 | 243.2 | 0.074 | 123.0 |
| F7B | 7.59 | 219.2 | 0.013 | 177.5 |
| F9B | 3.76 | 231.9 | 0.090 | 39.4 |
| F8B | 6.27 | 183.8 | 0.125 | 21.3 |
| F5B | 1.69 | 265.9 | 0.074 | 76.8 |
| F4B | 0.57 | 303.0 | 0.136 | 168.9 |
| F3B | 1.15 | 286.8 | 0.048 | 253.9 |
| F2B | 2.38 | 311.3 | 0.192 | 182.6 |
| F1B | 2.02 | 277.0 | 0.157 | 146.6 |
| Apparatus | 4.64 | 267.8 | 0.058 | 114.1 |

Table 2. The poloidal field coil positions measured from the toroidal coil axis. Right-handed coordinates measured from DIII-D zero.



- Reconstruction with shifted-tilted coils gives VMEC $n = \pm 1$ R and Z expansion coefficients on the order of 0.1 to 0.8 mm.

Conclusions and Future Prospects

- V3FIT is an effective tool for equilibrium reconstruction of highly non-axisymmetric plasmas
 - Stellarators
 - RFP Quasi-Helical States,
- V3FIT's flexibility and feature set may prove useful for nearly-axisymmetric equilibrium reconstruction
- New diagnostics for reconstruction are under development:
 - Microwave interferometry and polarimetry
 - Motional Stark Effect
- Future development of V3FIT will be driven by the code users

Acknowledgements

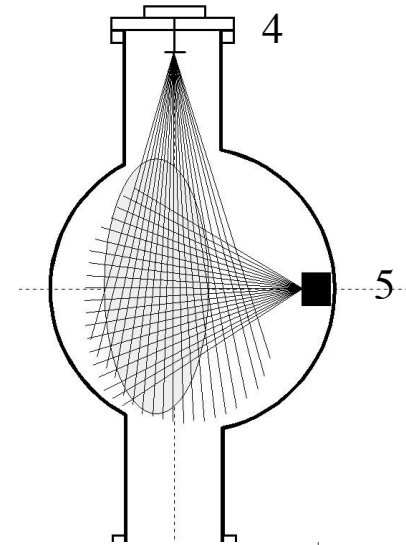
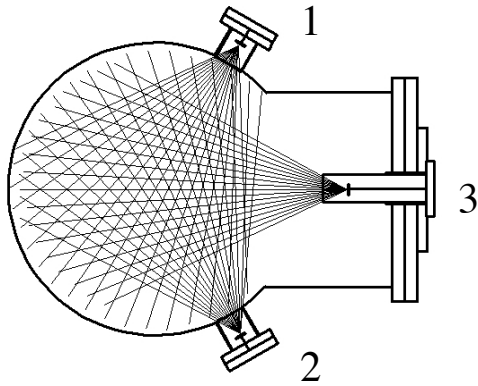
- **Auburn University**
 - Steve Knowlton
 - Greg Hartwell
 - Adam Stevenson
 - Mark Cianciosa
 - Jonathan Hebert
 - John Shields
- **Oak Ridge National Laboratory**
 - Steve Hirshman
 - Ed Lazarus (at GA)
 - Aaron Sontag
 - Jeff Harris
- **General Atomics**
 - Lang Lao
- **University of Wisconsin**
 - John Schmitt
 - Enrico Chlechowicz
- **Consorzio RFX, Padova**
 - David Terranova
- **Max-Planck-Institute, Greifswald**
 - Joachim Geiger
- **Los Alamos National Laboratory**
 - John Finn
 - Chris Jones
- **Princeton Plasma Physics Laboratory**
 - Sam Lazerson
 - David Gates
 - Ali Zolfaghari
- **College of William and Mary**
 - Gene Tracy
- **Tech-X Corporation**
- **Monetary Support - USDOE**

Extra Slides follow

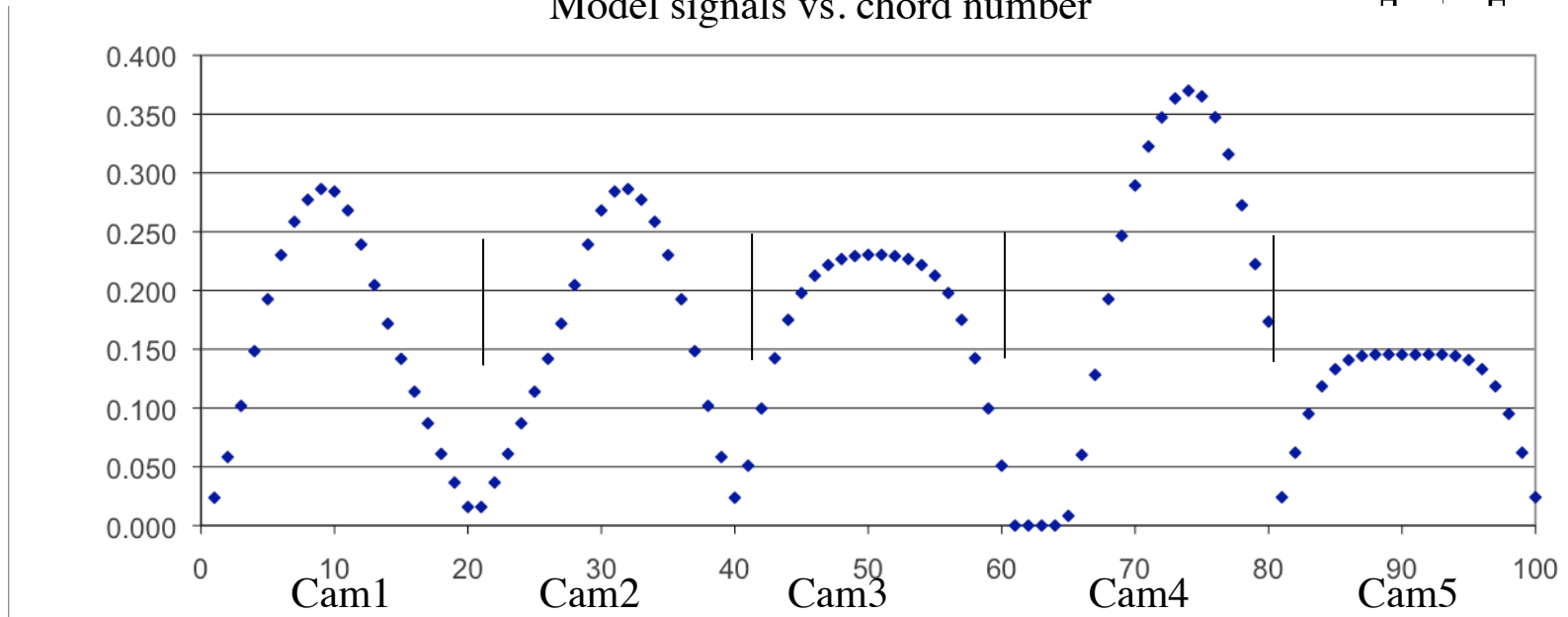
V3FIT History

- ~ 2001, NCSX (National Compact Stellarator eXperiment) on the horizon
 - Steve Hirshman, Steve Knowlton, Ed Lazarus, Lang Lao
 - Discussions about stellarator equilibrium reconstruction
- January 2002
 - First technical discussion
 - Jim Hanson joins the discussions
- “Magnetic diagnostic responses for compact stellarators”,
 - S P Hirshman, E A Lazarus, J D Hanson, S F Knowlton, and L L Lao
 - Phys. Plasmas, **11**, 595 (2004)
- “V3FIT: a code for three-dimensional equilibrium reconstruction”
 - J D Hanson, S P Hirshman, S F Knowlton, L L Lao, E A Lazarus, and J M Shields
 - Nucl. Fusion **49**, 075031 (2009).
- “Equilibrium and Stability of Current-Carrying Discharges in the Non-Axisymmetric CTH Experiment”
 - J D Hanson, S F Knowlton, B A Stevenson, and G J Hartwell
 - Contrib. Plasma Phys. **50**, 724 (2010)

Soft X-ray Chords Model Signals

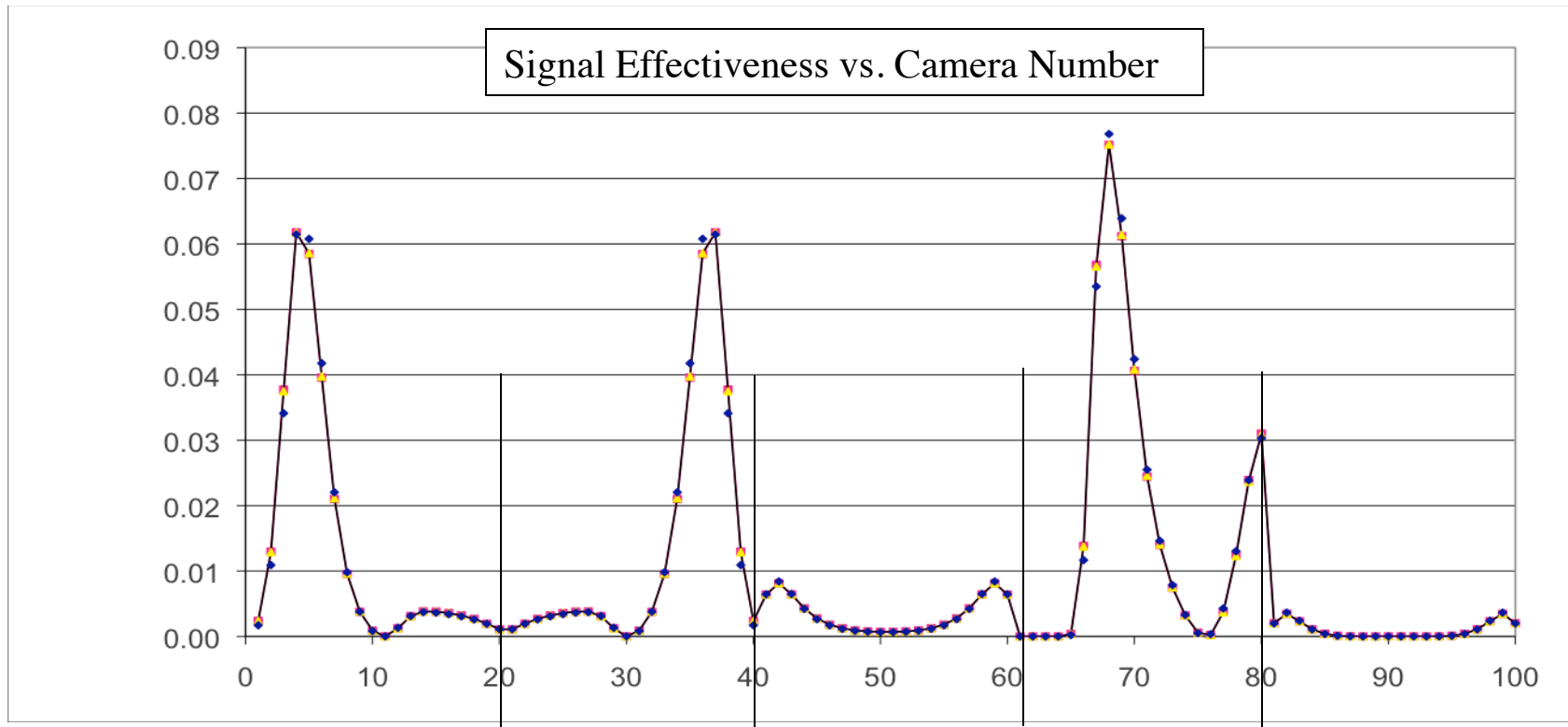


Model signals vs. chord number



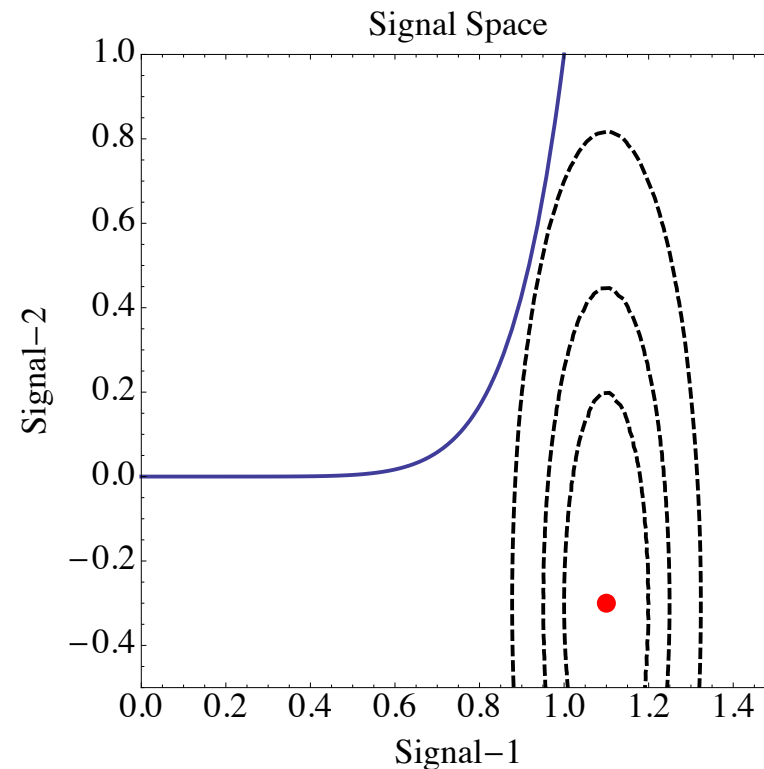
Signal Effectiveness - Soft X-Ray

- Signal Effectiveness shown is for measuring the Trim Vertical Field reconstruction parameter.
- Effect of Trim Vertical Field is mainly to move the plasma radially outward.



Signal Space

- The model function $\vec{S}^{\text{model}}(\vec{p})$ takes a point in parameter space to a point in signal space.
- Usually, the signal space has much higher dimensionality than the parameter space.
- Solid curve – Image of a one-dimensional parameter space, $\vec{S}^{\text{model}}(p)$
- Red dot – observed signals \vec{S}^{observe}
- Dashed lines – probability distribution of observations



VMEC

- Three-dimensional MHD equilibrium, *assumes* closed, nested flux surfaces
 - Can *not* resolve islands and chaotic regions
 - Uses inverse-coordinate representation
 - Spectral representation for angle coordinates
 - Grid representation for radial coordinate
 - Variational principle – minimizes radial forces on flux surfaces
 - Both free-boundary and fixed-boundary equilibria
- Fast, robust, widely used throughout the world.
 - S. P. Hirshman and J. C. Whitson, *Physics of Fluids* **26**, 3553 (1983).
- VMEC parameters to use for reconstruction:
 - Current and pressure profile parameters am(i), ac(i)
 - Pressure scale factor pres_scale
 - Total toroidal current curtor
 - External currents extcur(i)
 - Total toroidal flux within last closed flux surface phiedge

Algorithm

- Minimize deviation between observed and model signals

$$\chi^2(\mathbf{p}) \equiv \sum_i \left(\frac{S_i^o(\mathbf{d}, \mathbf{p}) - S_i^m(\mathbf{p})}{\sigma_i} \right)^2$$

- Minimize $\chi^2(\mathbf{p})$. Parameters \mathbf{p} , Observed signals $S_i^o(\mathbf{d}, \mathbf{p})$.
 - Model-computed signals $S_i^m(\mathbf{p})$, uncertainties in signals σ_i .
- V3FIT uses Newton algorithm for new parameters

$$\mathbf{A}^T \cdot \mathbf{A} \cdot \delta \mathbf{a} = \mathbf{A}^T \cdot \mathbf{e}$$

- Jacobian (normalized) $A_{ij} = \frac{\pi_j}{\sigma_i} \left(\frac{\partial S_i^m}{\partial p_j} - \frac{\partial S_i^o}{\partial p_j} \right)$

- Error vector $e_i = (S_i^o(\mathbf{d}, \mathbf{p}) - S_i^m(\mathbf{p})) / \sigma_i$

- Normalized Parameters $a_j = p_j / \pi_j$

$$\chi^2(\mathbf{p}) = \mathbf{e} \cdot \mathbf{e}$$

$$\mathbf{A} = -\nabla_{\mathbf{a}} \mathbf{e}$$

Algorithm (2)

- Jacobian Calculation

- Finite difference approximation, $J_{ij} \approx \Delta S_i / \Delta p_j$
- Small Δp in parameter space – VMEC converges rapidly
- Need moderate accuracy in S_i^m
- Needs well-converged VMEC
- Does *not* need high radial resolution – improves speed
- Use SVD on Jacobian to help avoid large steps in parameter space

- Posterior Sigmas – Confidence Limits on Parameters

- Assume uncorrelated signals – diagonal signal covariance matrix
- Parameter covariance matrix (also called posterior covariance)

$$\mathbf{C}_p = (\mathbf{J}^T \cdot \mathbf{C}^{-1} \cdot \mathbf{J})^{-1}$$

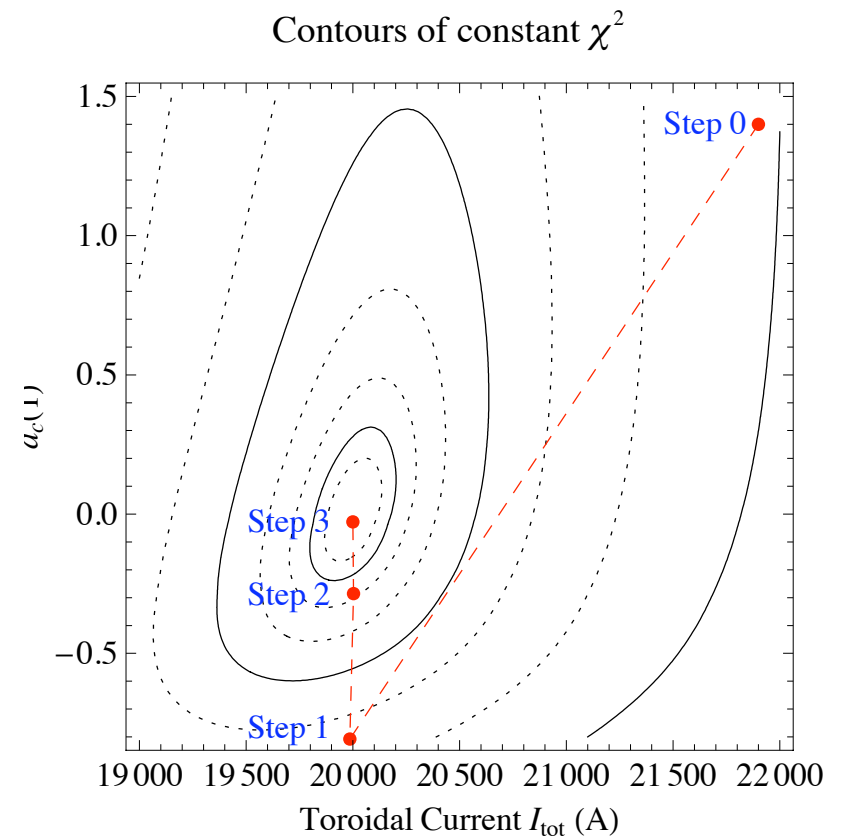
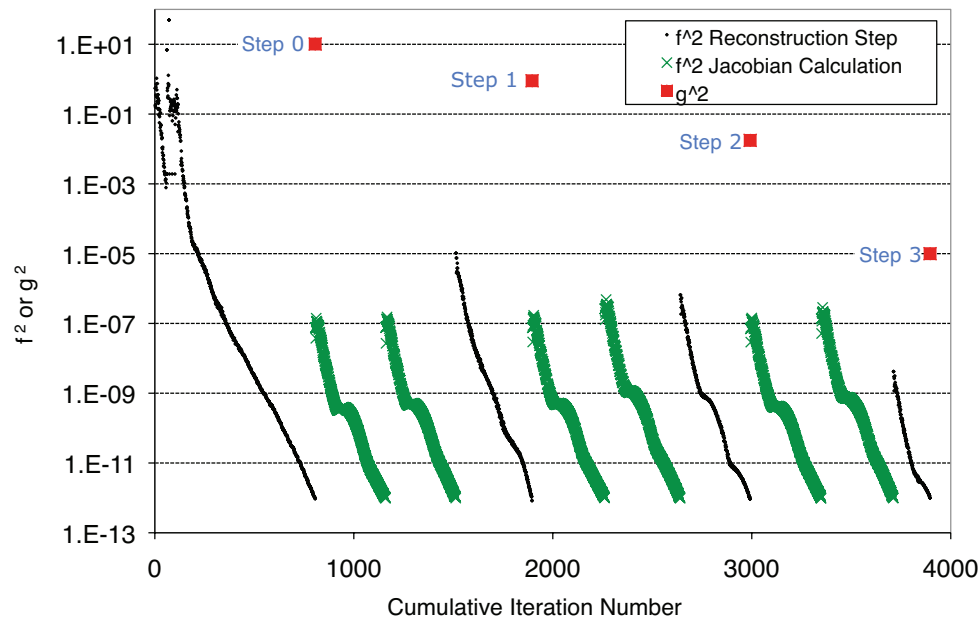
$$C_{ij} = \sigma_i^2 \delta_{ij}$$

- Confidence limit on parameter value - Measures how accurately these signals determine the j th reconstruction parameter.

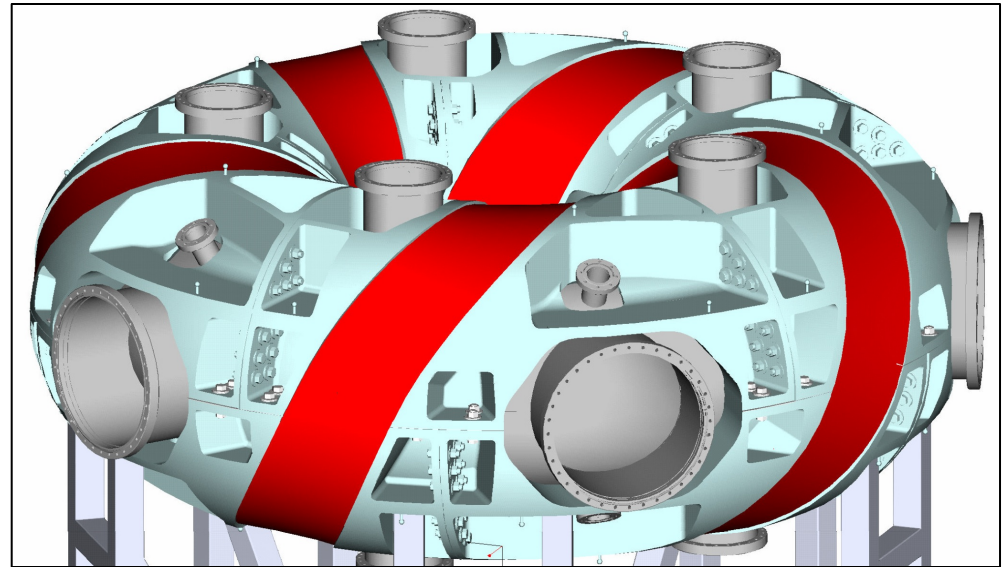
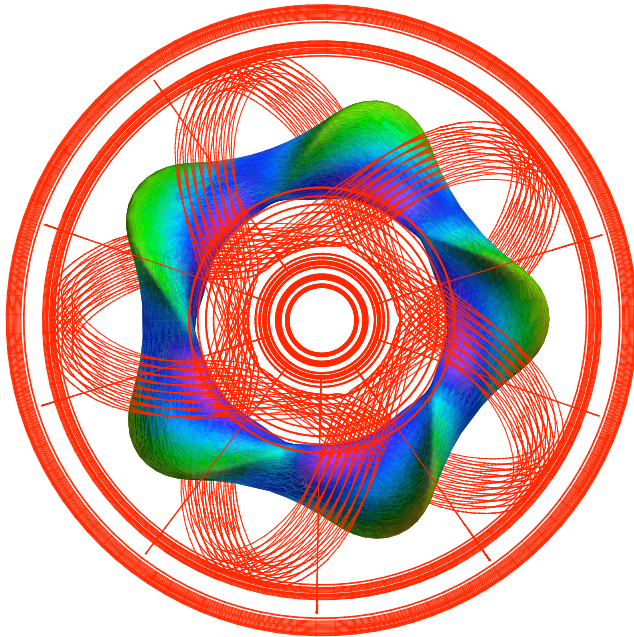
$$\sigma_{p\ j} = \sqrt{(\mathbf{C}_p)_{jj}}$$

Reconstruction Illustration

- CTH Equilibrium, Simulated observations
- 2 Parameters
 - Total toroidal plasma current I_{tot} [curtor]
 - Toroidal current profile shape $a_c(1)$
- 12 Magnetic Diagnostic signals
 - Rogowski, 8-part Rogowski
 - Two flux loops, one magnetic probe

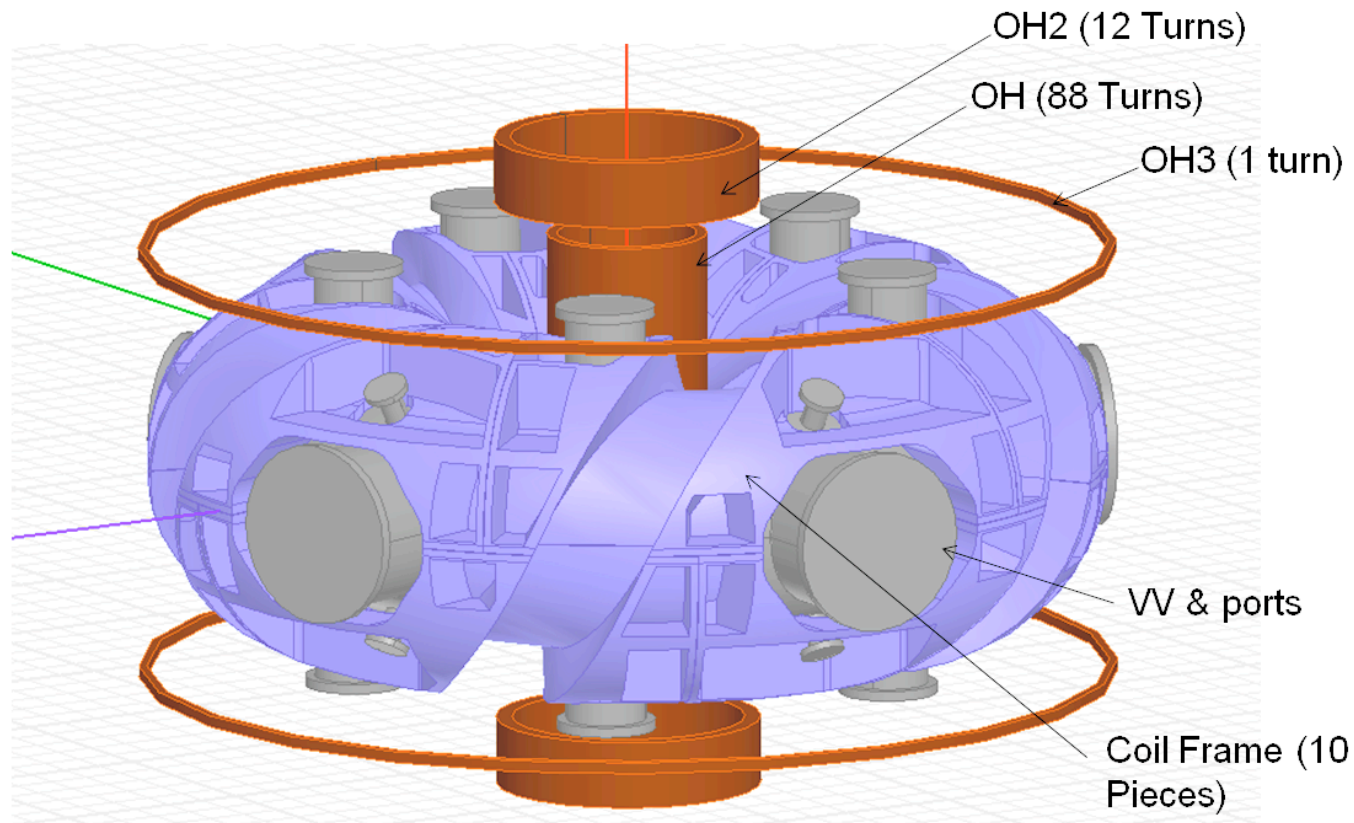


CTH – Compact Toroidal Hybrid



- Auburn University, Steve Knowlton – Principal Investigator
- Torsatron with Ohmic heating coils
- Major radius 0.75 m

CTH – Compact Toroidal Hybrid



Magnetic Diagnostics

$$\Phi_i = \sum_j M_{ij} I_j^{external} + \int_{plasma} \vec{J}(\vec{r}') \cdot \left(\frac{\mu_0}{4\pi} \oint \frac{d\vec{\ell}_i}{|\vec{\ell}_i - \vec{r}'|} \right) d\vec{r}'$$

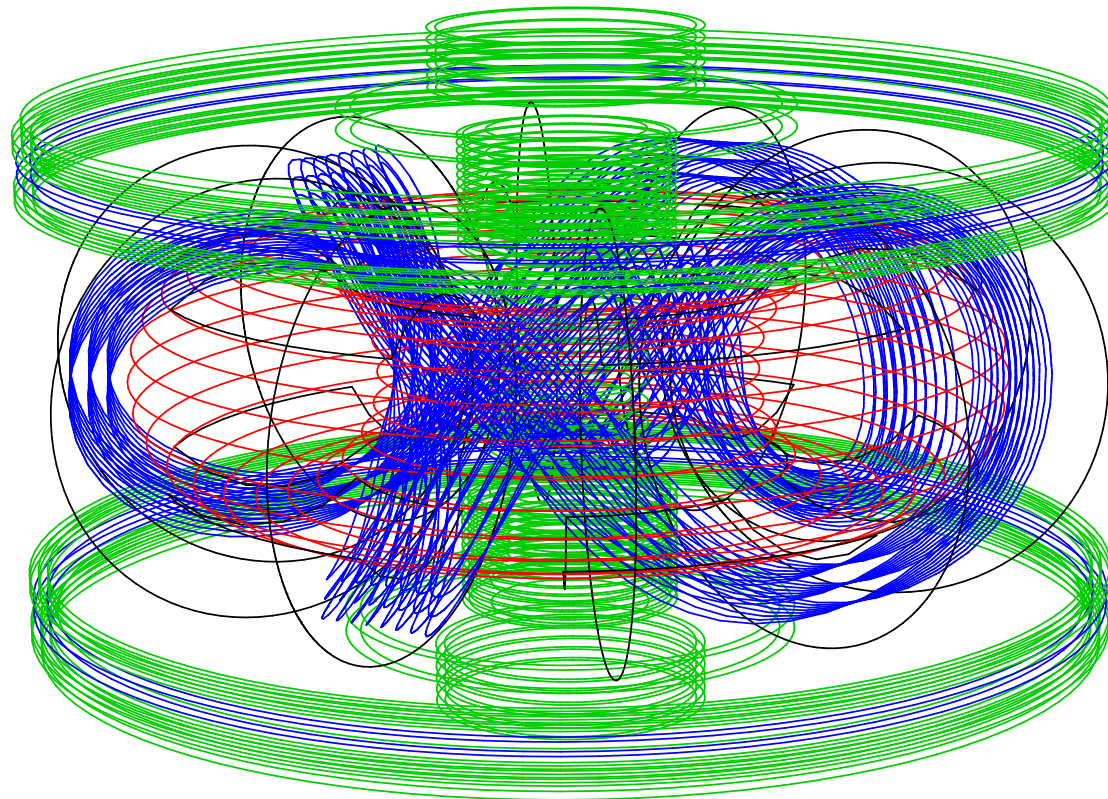
- Signal depends on details of external currents
 - Mutual inductance matrix M depends on geometry of both external coil and diagnostic coil
- Plasma contribution is a *volume* integral over the whole plasma
- The plasma contribution *only* depends on equilibrium quantities – no other plasma information is needed.

Details of implementation, see “*Magnetic diagnostic responses for compact stellarators*”, S. P Hirshman, E. A. Lazarus, J. D. Hanson, S. F. Knowlton, and L. L. Lao, Phys. Plasmas **11**, 595 (2004).

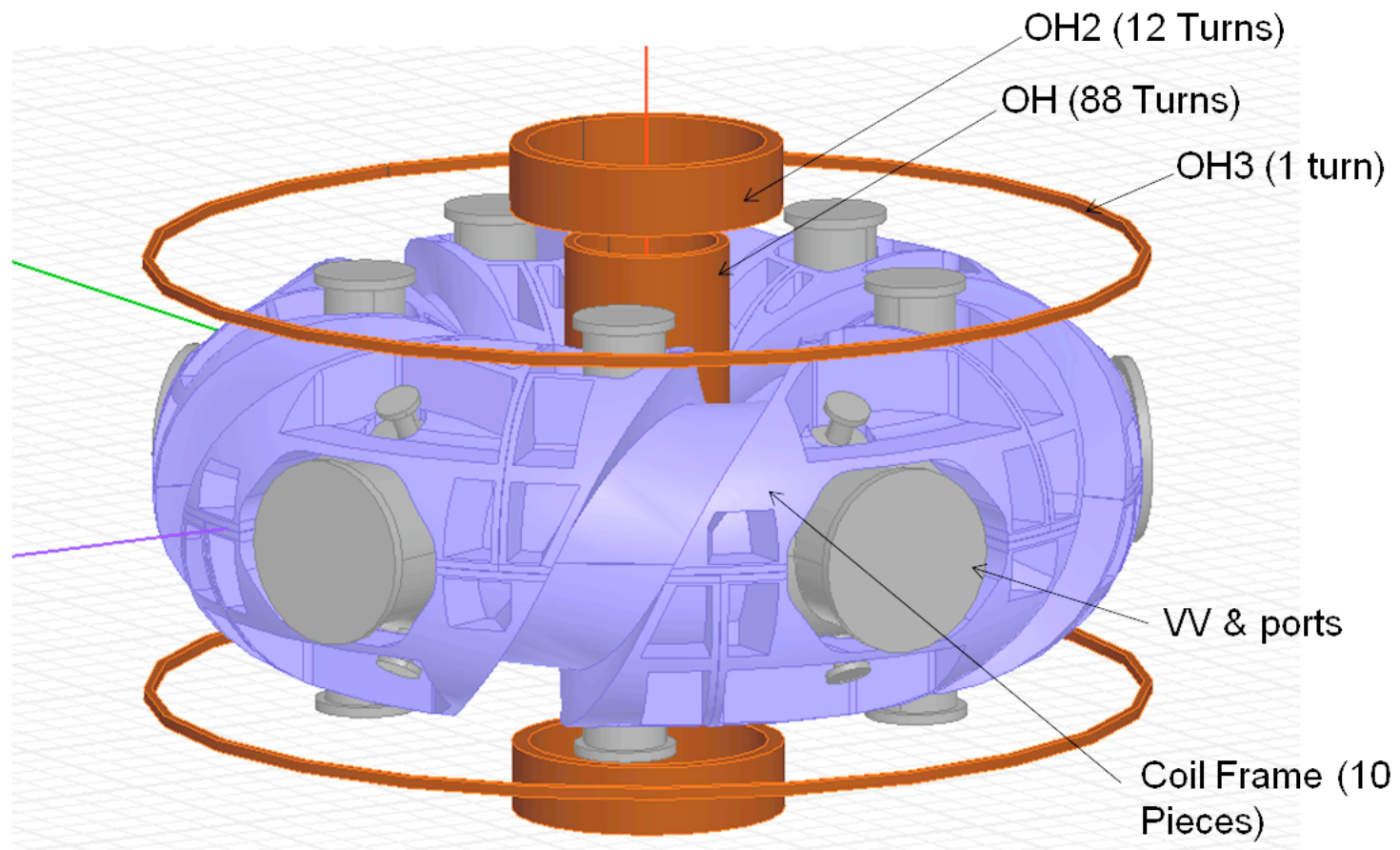
Eddy Current Modeling

- Eddy currents in the CTH coil frame and vacuum vessel can be included in the MHD equilibrium as external magnetic fields – included in the coils_dot file
- Measured currents in these structures are significant, induced by the ohmic loop voltage (and other time-changing magnetic fields)
- Auburn University requested assistance from Princeton Plasma Physics Laboratory “Offsite University Research Program” for help modeling the eddy currents in these complicated structures.
- Ali Zolfaghari and Dave Gates from PPPL.
- CAD models of structures -> eddy current modeling code SPARK.
- Translate results in format appropriate for VMEC input.

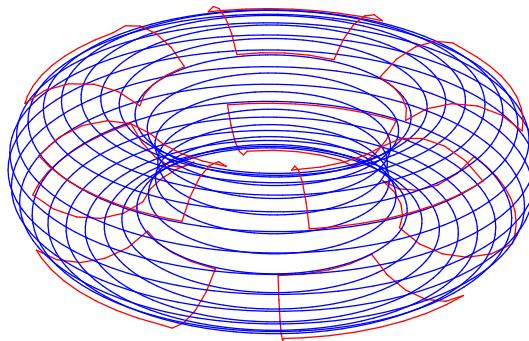
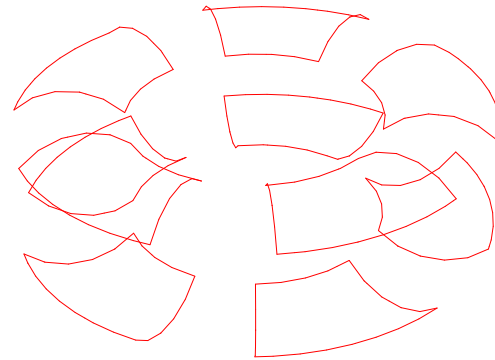
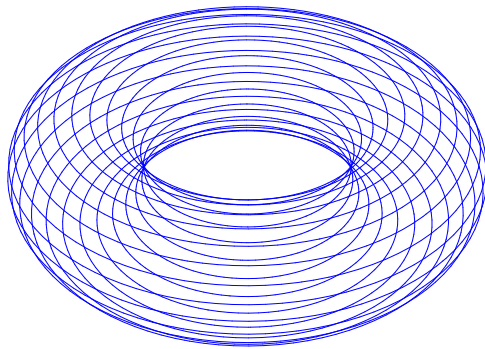
CTH External Coils



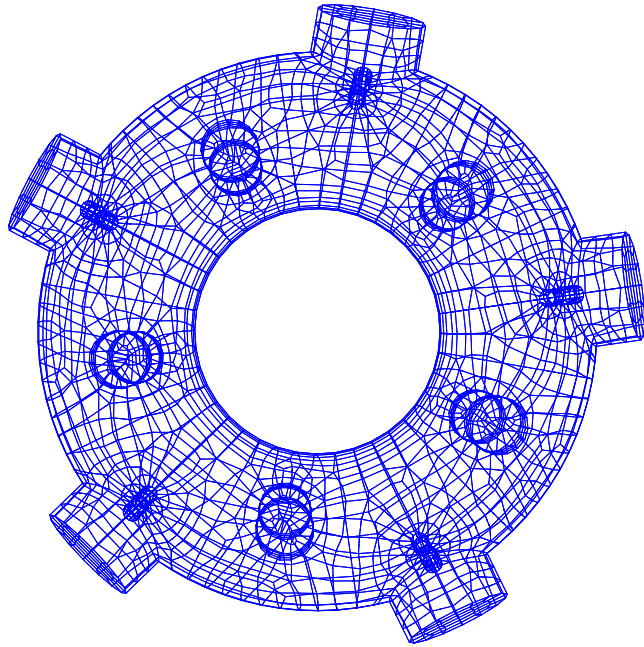
CTH



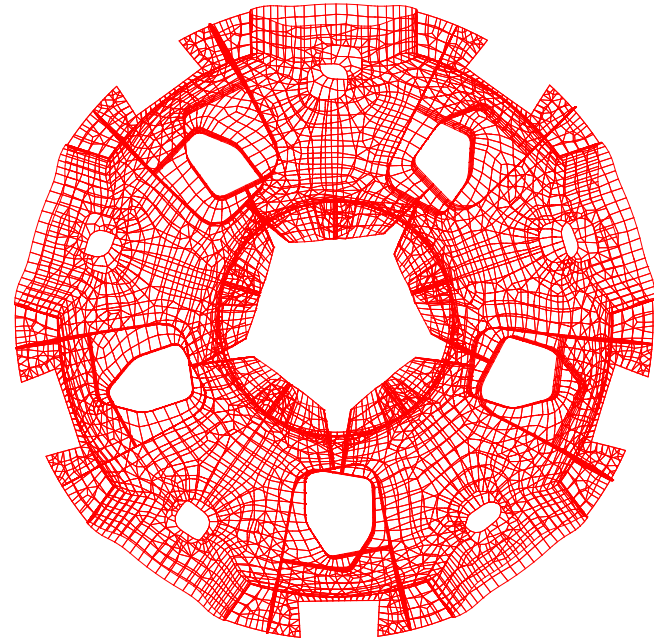
Vaccum Vessel and Coil Frame



PPPL Results Translated to VMEC Format



Vacuum Vessel



Coil Frame

- Status – Checking results from PPPL
- Expect V3FIT reconstruction comparisons soon.
- See 3D versions on iPad