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Fusion
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Rotation and Error Field influences on NTMs

Richard Buttery*,

with special thanks and considerable input from:

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C Holcomb, G Jackson, M Maraschek, H Reimerdes, M Schaffer.**

*EURATOM/UKAEA Fusion Association, Culham Science Centre, Abingdon, UK.

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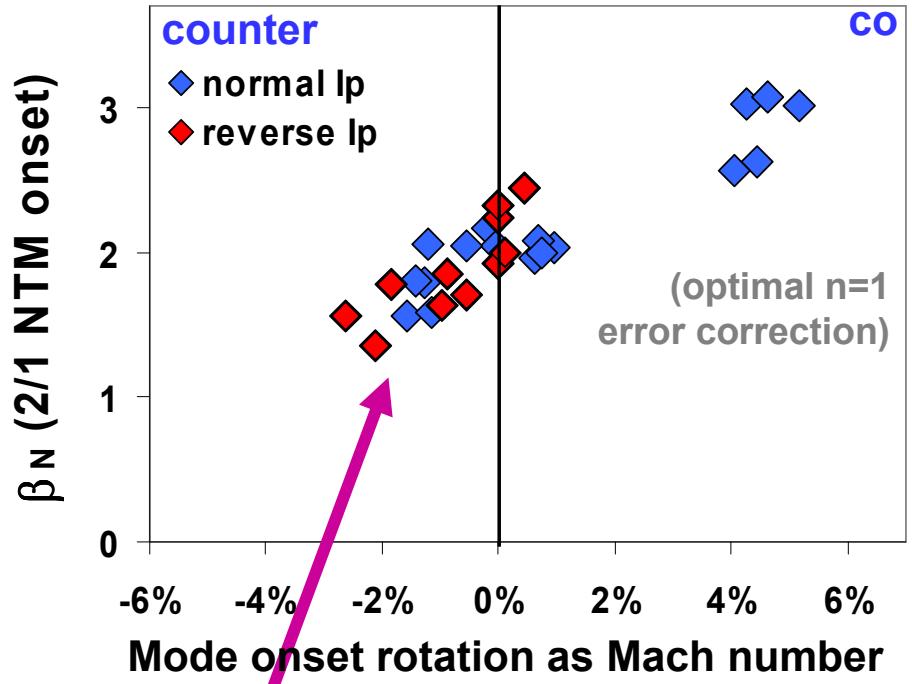
Three Questions

- 1. Is there an asymmetry in the influence of rotation on tearing stability?**
- 2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?**
- 3. Does proximity to intrinsic tearing instability lower error field thresholds?**



DIII-D normal & reverse I_p data shows strong rotation trend

- Clear β_N fall with increasing counter rotation



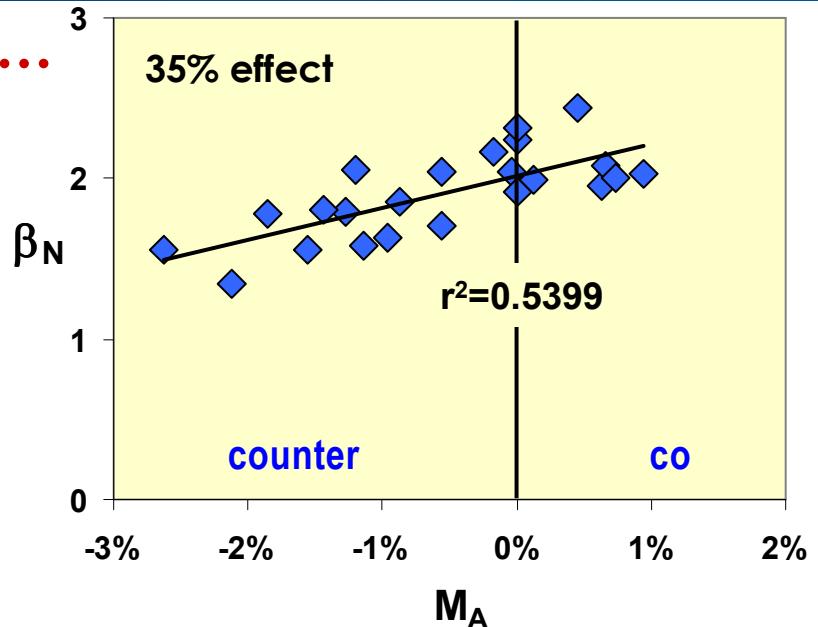
Is counter rotation trend a 'real' effect in underlying tearing physics?

– or just profile variation?

Fall in threshold with counter rotation is a real effect...

Consider only low rotation DIII-D data...

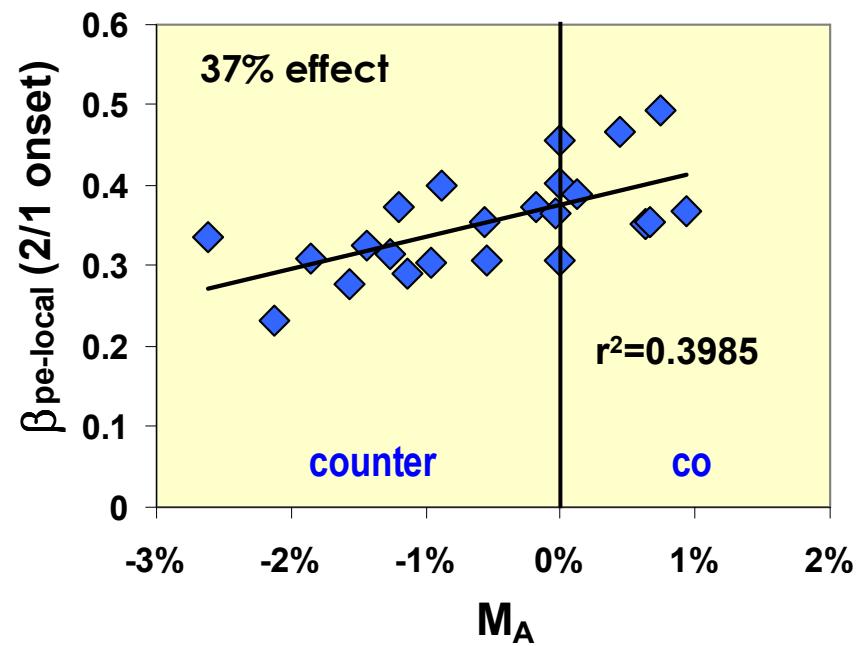
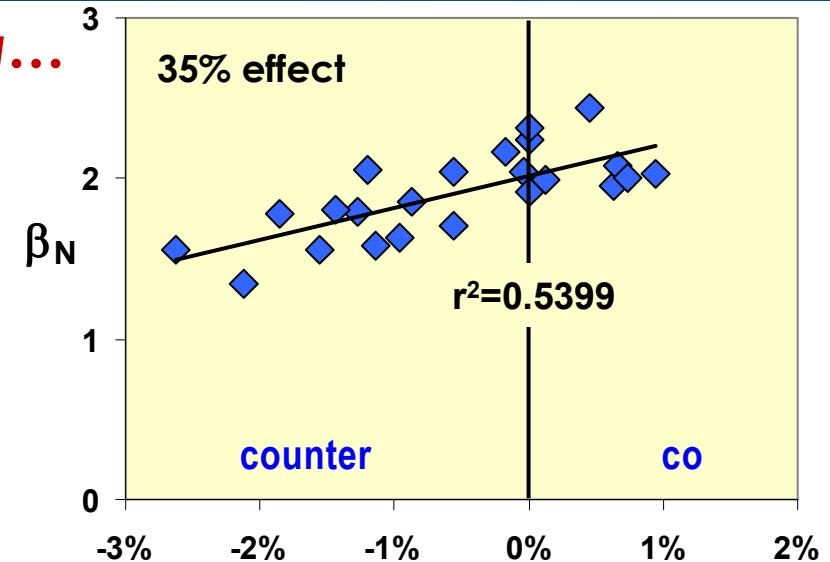
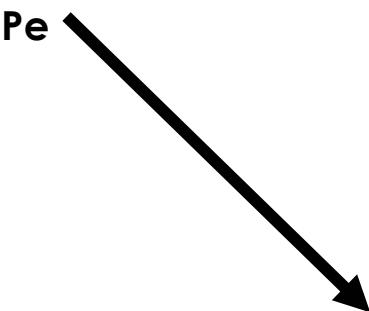
- Clear trend in β_N 



Fall in threshold with counter rotation is a real effect...

Consider only low rotation DIII-D data...

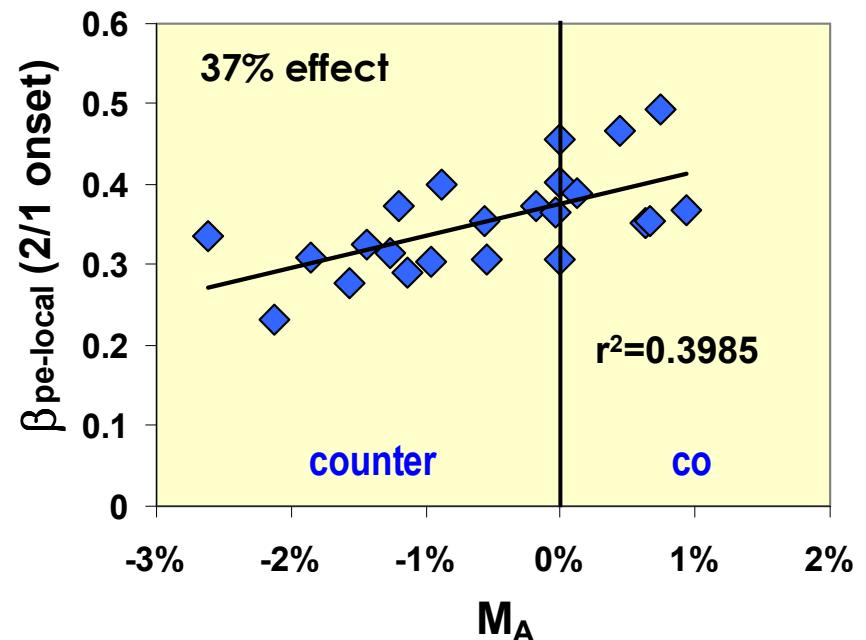
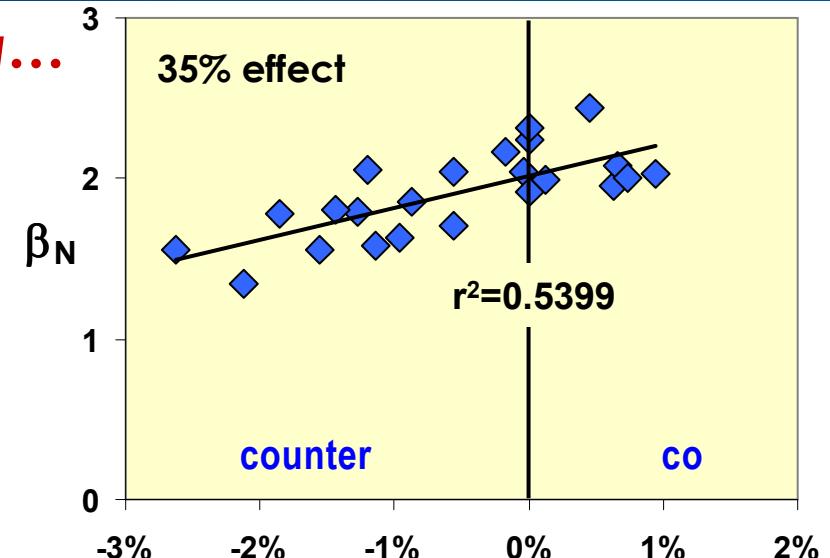
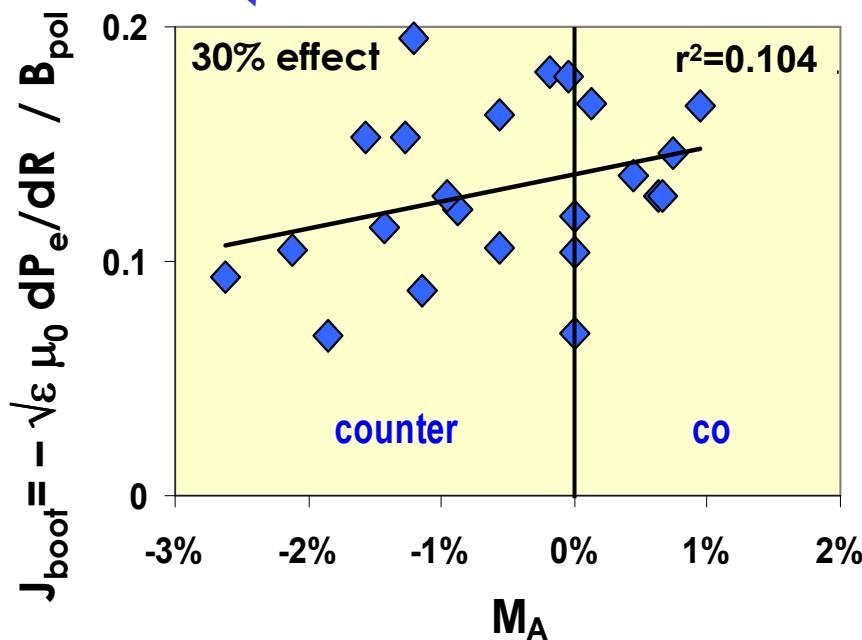
- Clear trend in β_N
- Similar trend in local β_{Pe}



Fall in threshold with counter rotation is a real effect

Consider only low rotation DIII-D data...

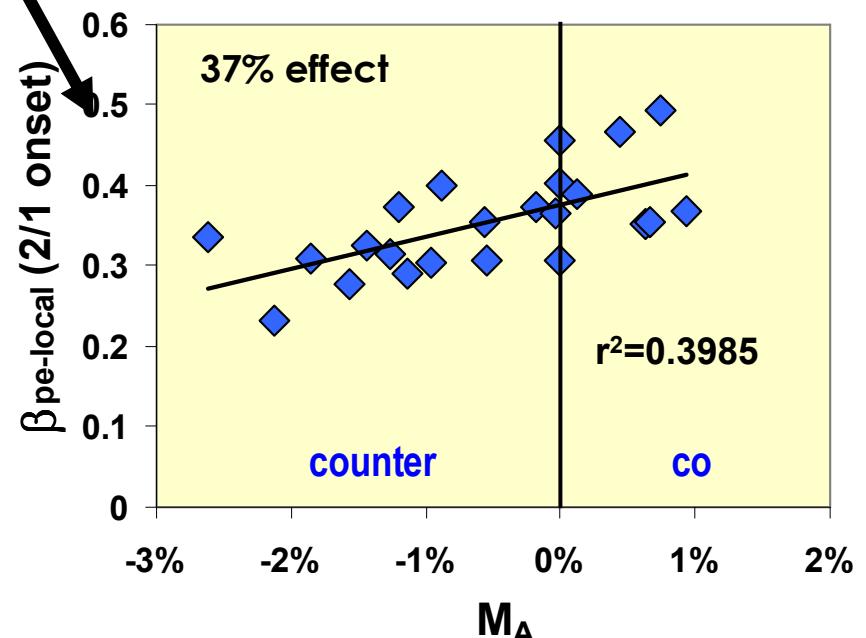
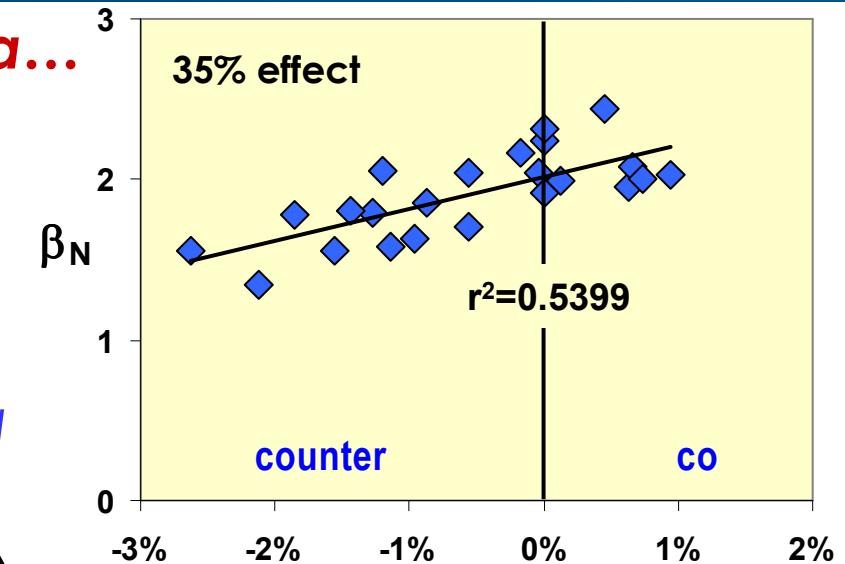
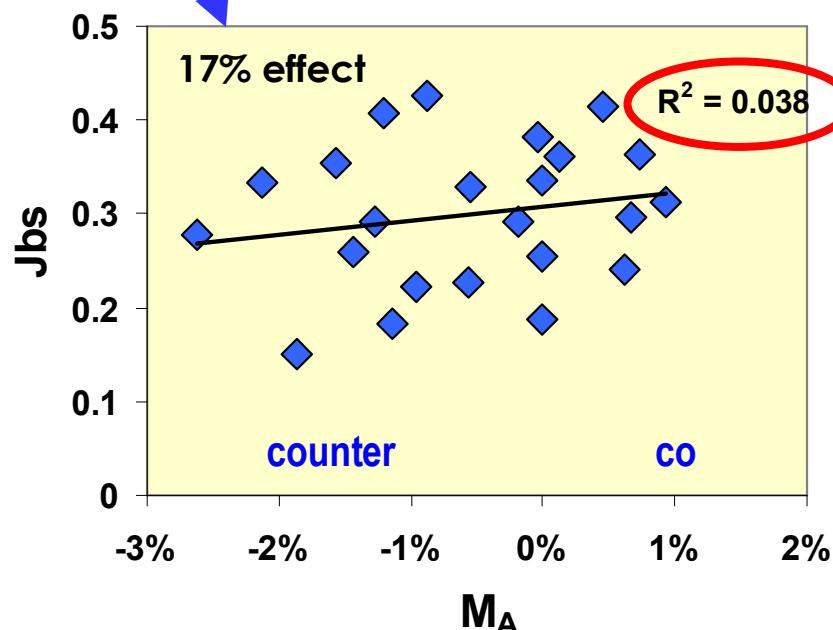
- Clear trend in β_N
- Similar trend in local β_{Pe}
- ...and in bootstrap measure (?)
 - *noisier – more local gradients used*



Fall in threshold with counter rotation is a real effect

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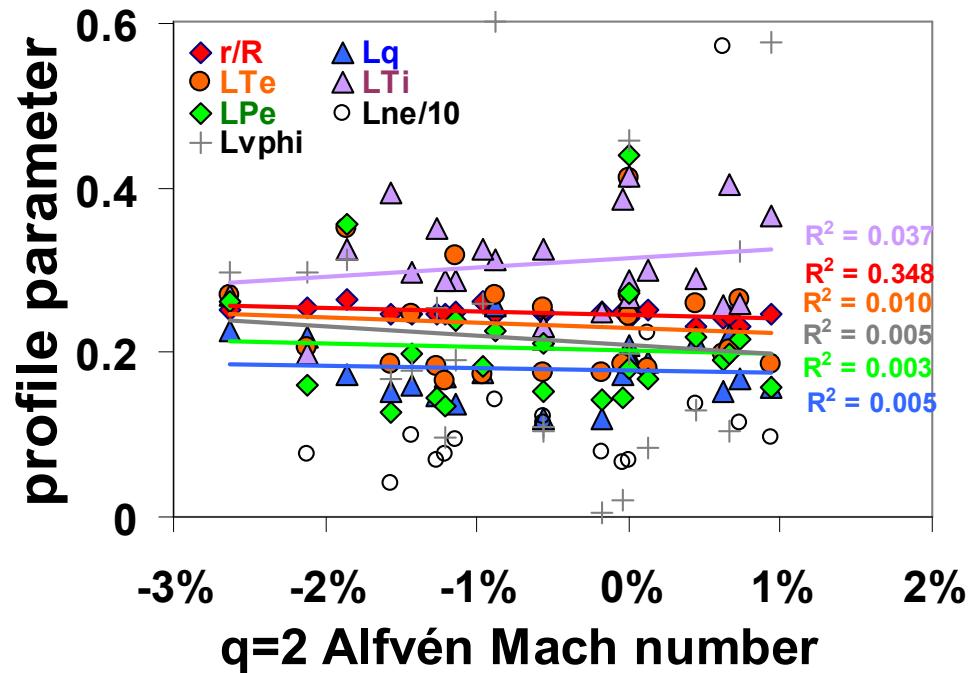
- Clear trend in β_N
- Similar trend in local β_{Pe}
- ...and in bootstrap measure (?)
 - noisier – more local gradients used
 - **Even noisier with full bootstrap**



Is there a real trend in local parameters? Yes...

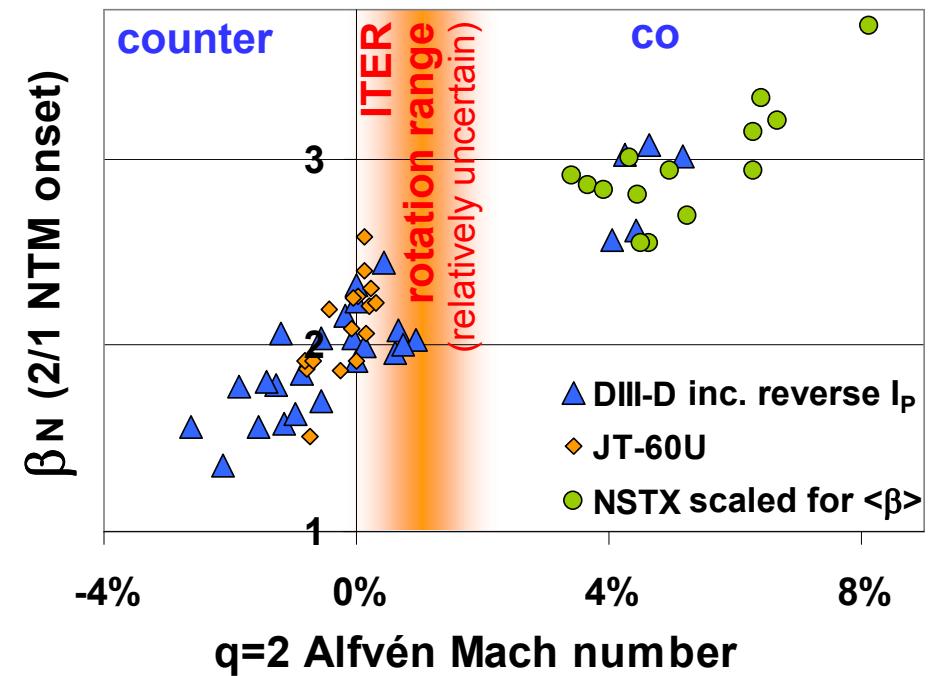
Examine local scale lengths:

- No significant trends →
 - No systematic variation in profiles with rotation
 - Effect observed in β_N and 'rough' local calculations corresponds to a real variation in NTM drives
 - Effect weakened in J_{BS} mainly due to noise



Cross-machine comparison confirms asymmetry

- JT-60U also shows a possible asymmetry in rotation role
 - Possibly steeper?



[Buttery et al., IAEA 2008]

First Question...

1. Is there an asymmetry in the influence of rotation on tearing stability?

– Yes

2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?

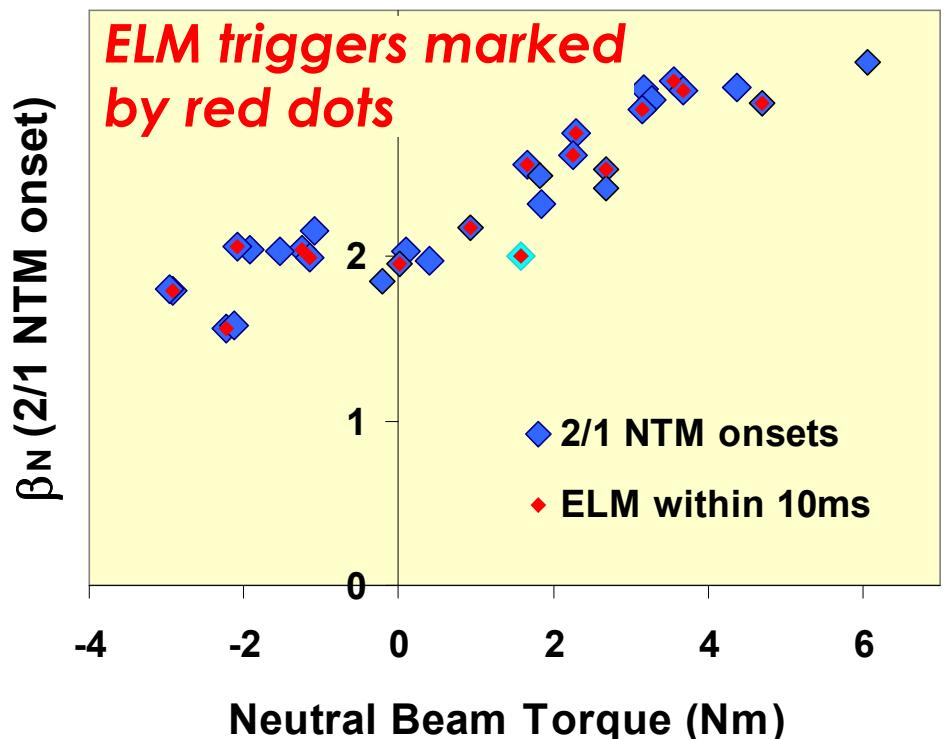
3. Does proximity to intrinsic tearing instability lower error field thresholds?



ELM role in 2/1 triggering appears incidental

ELMs 'trigger' about half the 2/1 NTMs:

- **But trigger has no influence on NTM onset β_N**
 - And trigger type not correlated with rotation

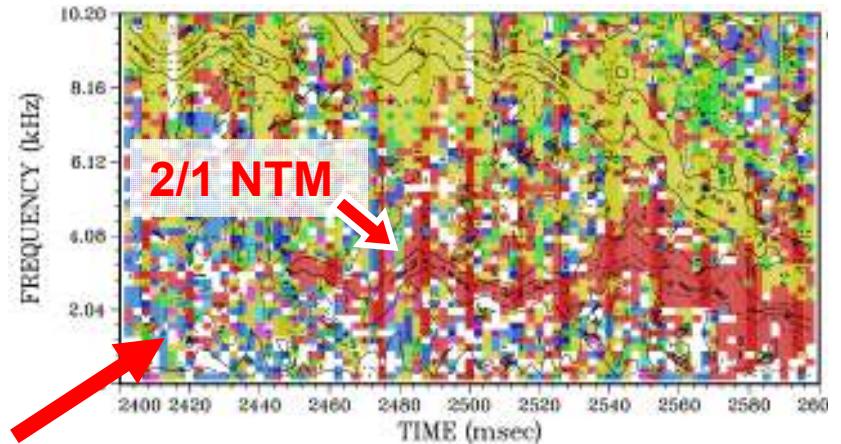


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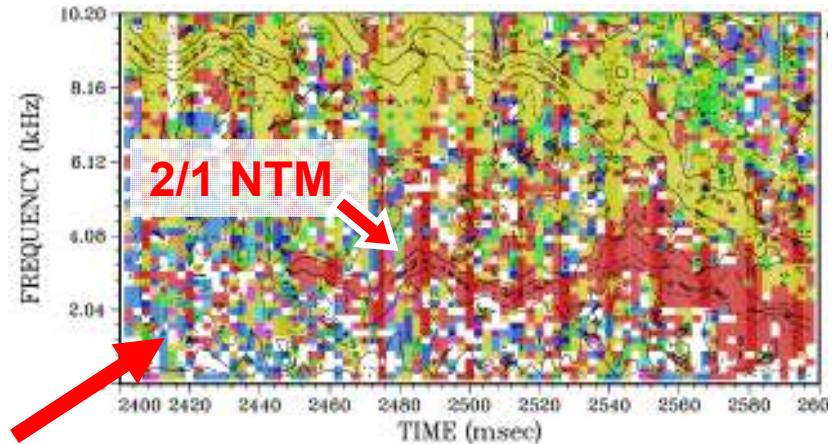
Triggerless NTMs come out the noise



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Triggerless NTMs come out the noise

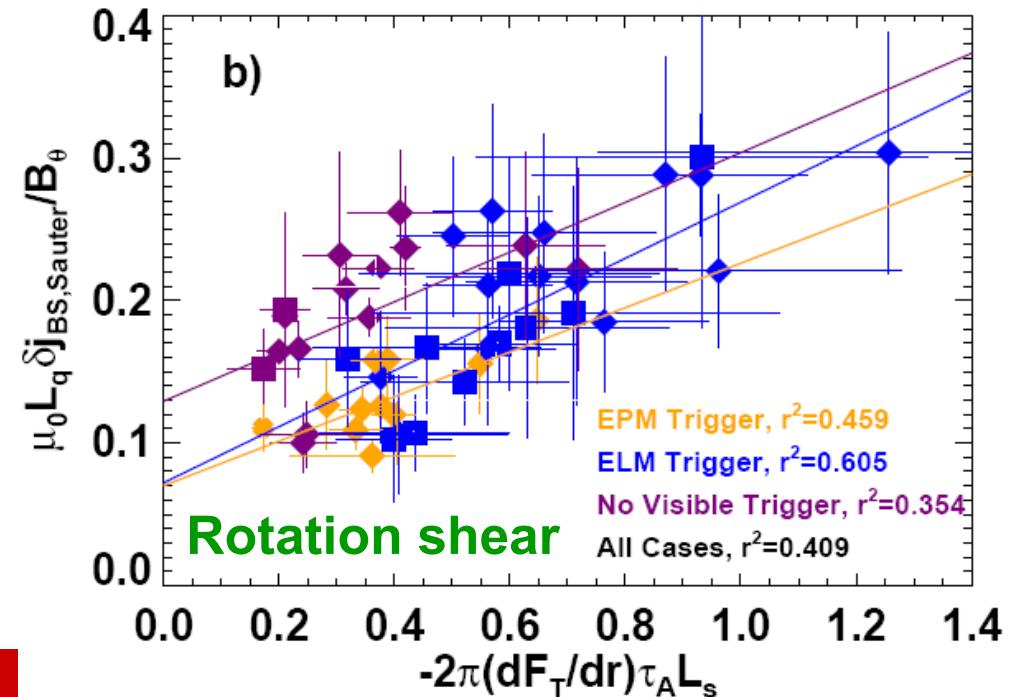
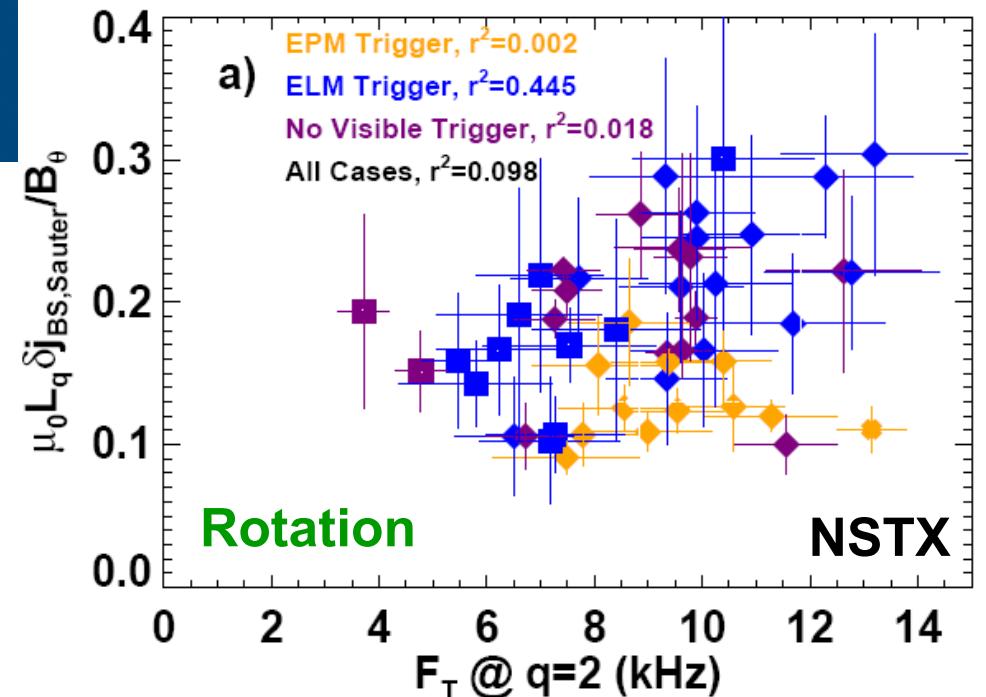
- NTM onset β is not about "triggered seed exceeding threshold width" $\leftarrow \rho^*$ dependent
- Instead: dictated by changes in the *intrinsic tearing stability* that govern the trigger-less modes
- Raises question of whether to expect a ρ^* dependence in $\beta_{\text{NTM onset}}$?



NSTX observations suggest it is about intrinsic stability

NSTX can deconvolve rotation from rotation shear:

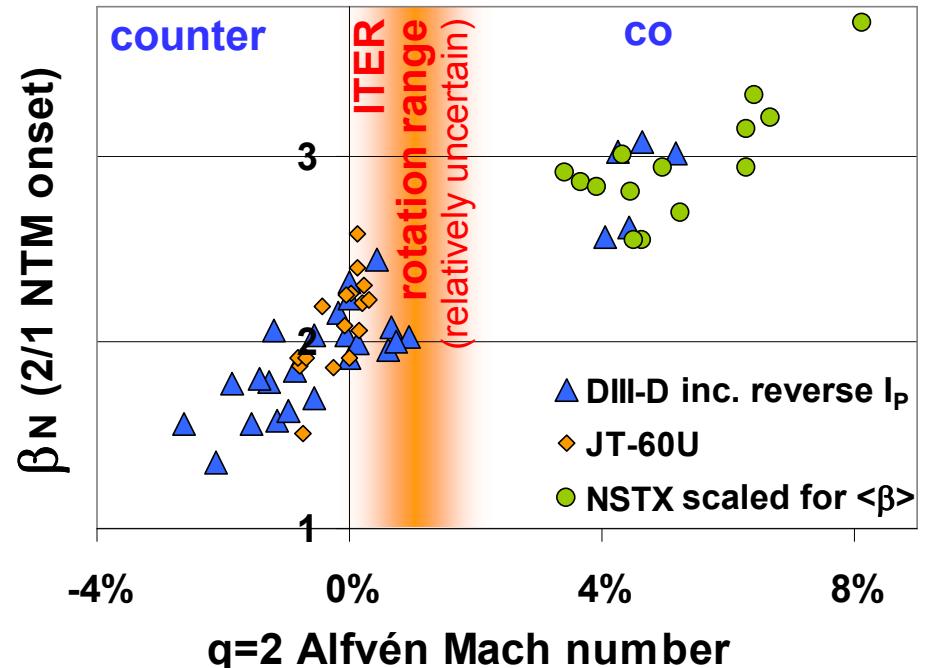
- *Rotation shear gives visibly clearer trends*
- *Suggests an action through intrinsic tearing stability*
 - External effects such as coupling, walls, etc. would depend on rotation
 - Though trigger type can play some role...



[S. Gerhardt, NF letter submitted]

Cross-machine comparison confirms asymmetry & suggest limit related to ideal MHD

- JT-60U also shows a possible asymmetry in rotation role
 - Possibly steeper?
- Devices line up when plotted with correction for $\langle \beta_N \rangle$
 - NSTX data scaled to get this
 - $\langle \beta_N \rangle$ relates to ideal limit
 - 'poles in Δ ' model
- Phenomenology suggests:
 - Tearing threshold arises from change in intrinsic tearing stability as ideal limit is approached
 - But rotation (relative to Alfvén) further changes the tearing stability



[Buttery et al., IAEA 2008]



Second Question...

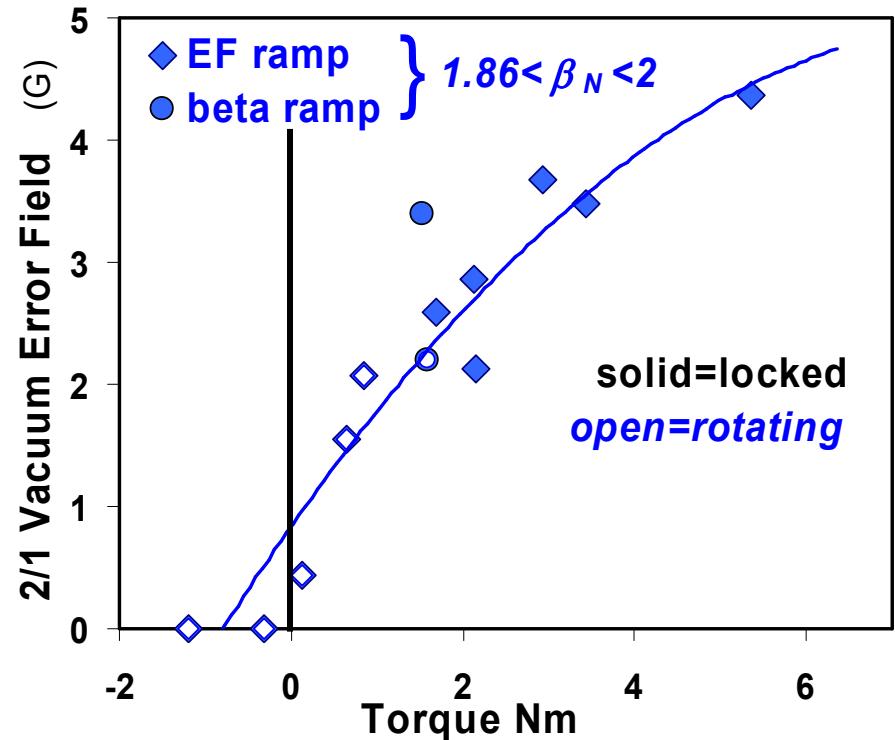
- 1. Is there an asymmetry in the influence of rotation on tearing stability?**
 - Yes
- 2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?**
 - Yes
- 3. Does proximity to intrinsic tearing instability lower error field thresholds?**



Error fields assist medium β_N tearing mode formation

Hold $\beta_N \sim 1.9$ and vary torque from shot to shot:

- ◆ Error field threshold falls with torque
- ◆ But rotating modes at low torque!
 - *Intrinsic tearing stability is being modified...*
 - ...by rotation perturbation?*

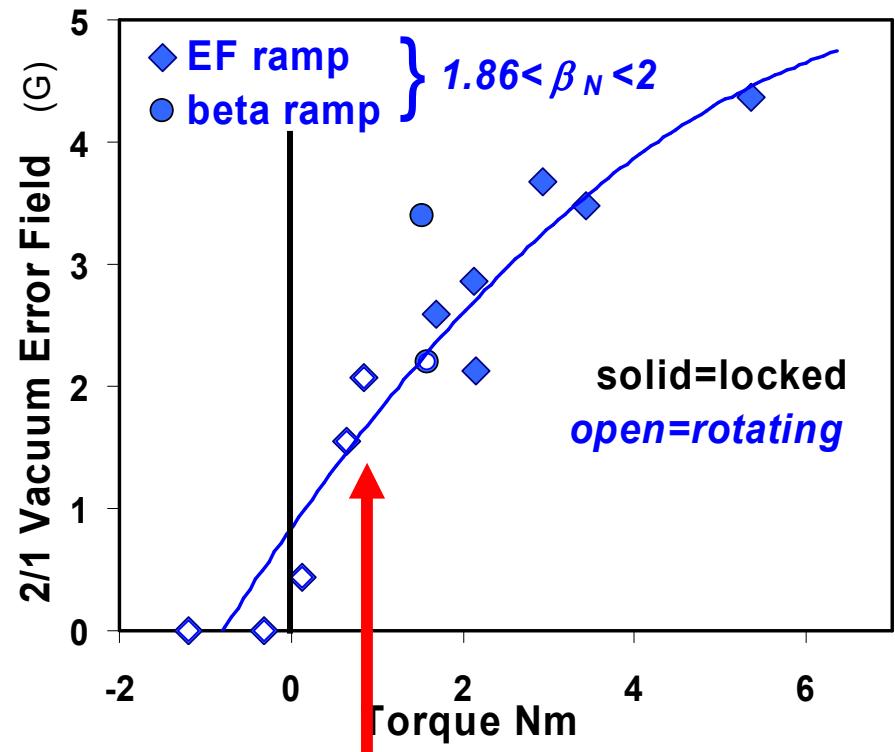


(◆ Similar to advanced scenario observations of Reimerdes: PO3.00011)

Error fields assist medium β_N tearing mode formation

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ITER relevant torques/rotations
just stable with good error correction:

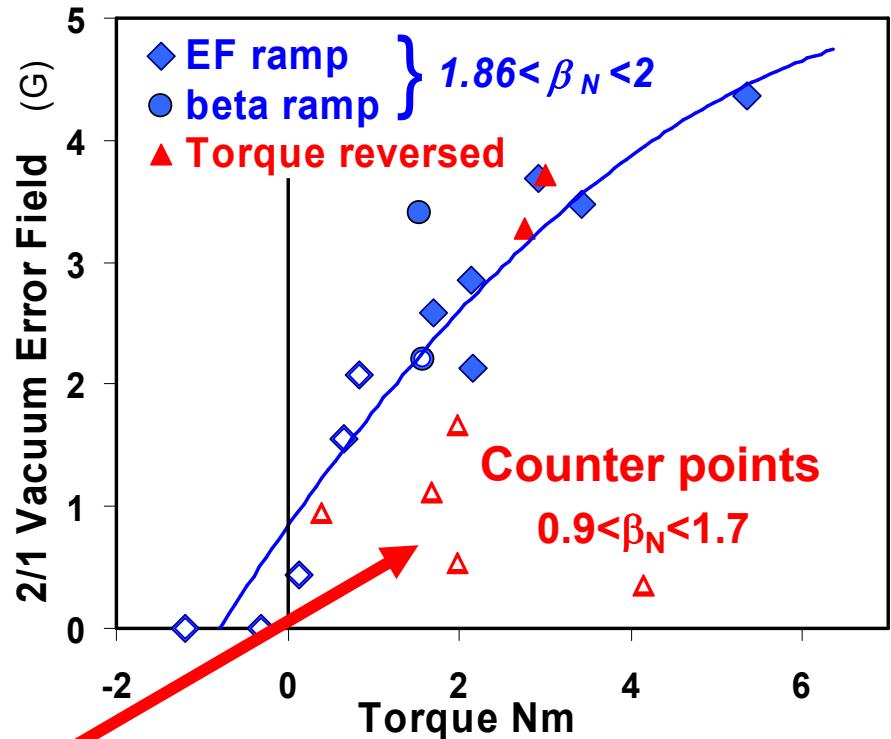
$$\delta B_{21}/B_T < 1.10^{-4}$$



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- ◆ Error field threshold falls with torque
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Compare with counter torque (Δ)

- Error field thresholds are lower!
 - Despite generally being at lower β_N values!
 - Is this to do with mode rotations?...



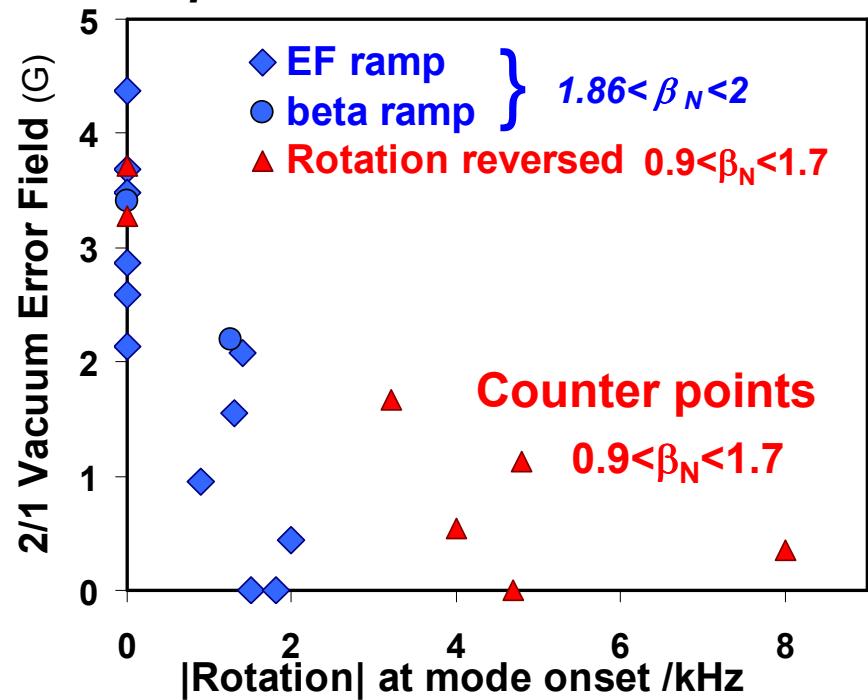
Error fields assist medium β_N tearing mode formation

Compare **co** and **counter** rotating cases:

- Counter points rotate faster!

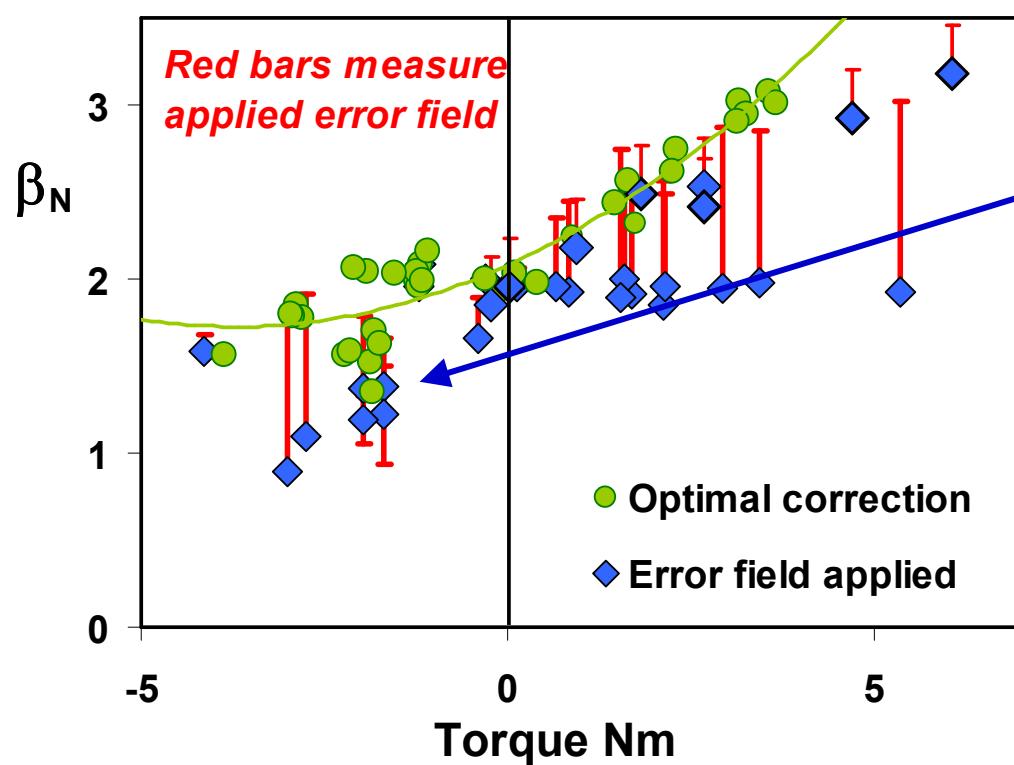
- Once again:
Counter rotation seems intrinsically less stable than co
 - This time seen through error field thresholds
- **Is error field sensitivity picking up on decreased intrinsic tearing stability at low & counter rotation?**

Re-plot vs mode onset rotation:



Amount of error field needed depends on proximity to NTM limit at a given torque?

Full data set gives an interesting picture:



- Error fields 'close the gap' in β_N with NTM β_N limit (○)
 - note low β_N points needing little error field to lower $\beta_{N\text{-onset}}$ further
- *Is this a new error field amplification effect?*
 - Brought on by proximity to classical tearing?
 - Or asymmetry in rotation influence?



Amount of error field needed depends on proximity to NTM limit at a given torque?

- β_N threshold falls as error fields increase

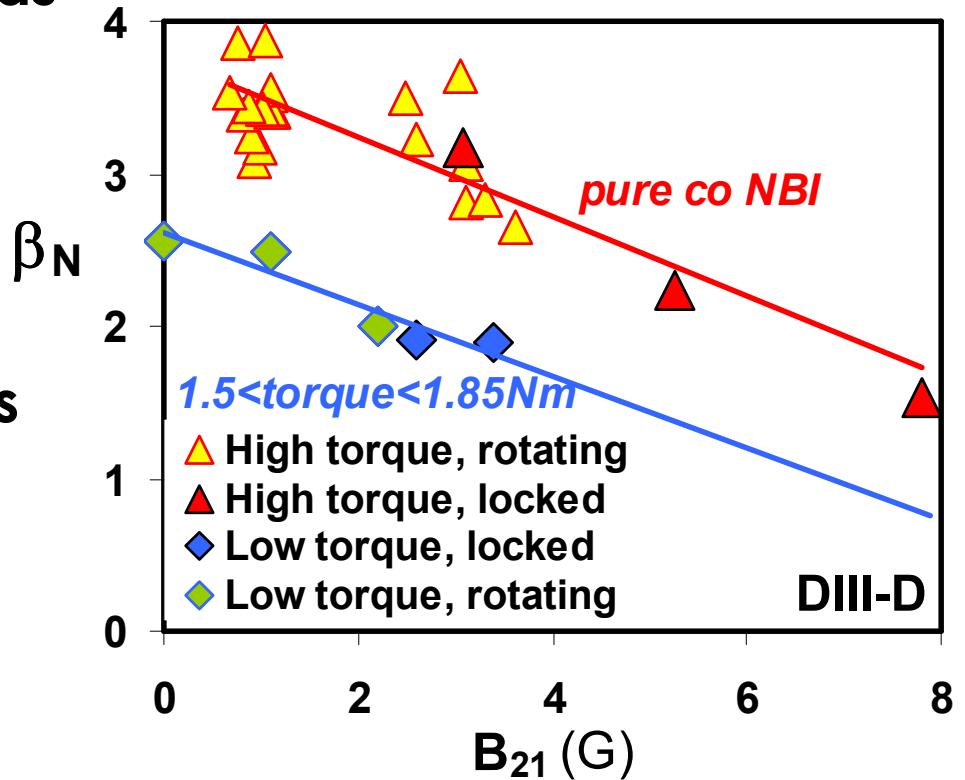
or equivalently

- Error field sensitivity increases at high β_N & low rotation

– *Should it?*

...shielding still strong?

- *Suggests revised error field correction requirements required for ITER at baseline and hybrid operating points*



Conclusion: Three Questions Answered

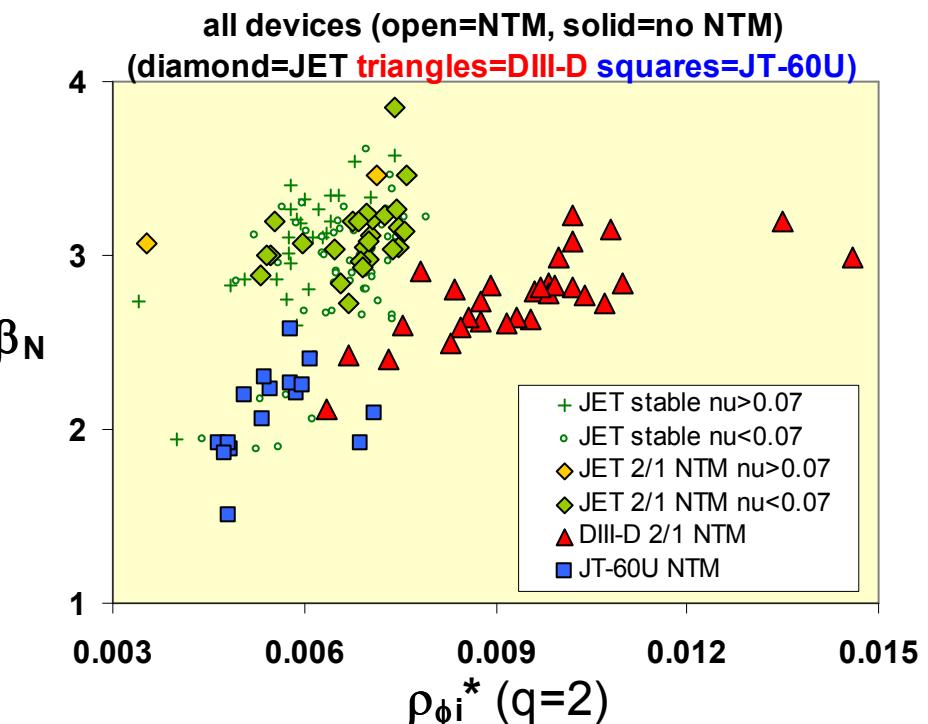
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 - Yes



This is good news – ρ^* dependent physics may not be dominant

Explore hybrid scenario 2/1 NTM β limits:

- JET sits well above trend in ρ^* from DIII-D
 - In 2/1 thresholds & stable data
- JET even somewhat higher in absolute β_N
 - Possibly q profile and/or fast particle effects
- JT-60U lower due to low rotation



But that's another talk...!



More experiments needed!

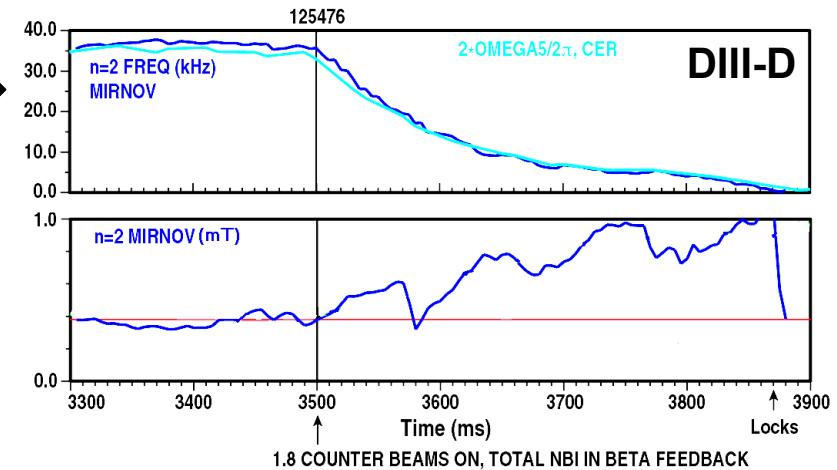
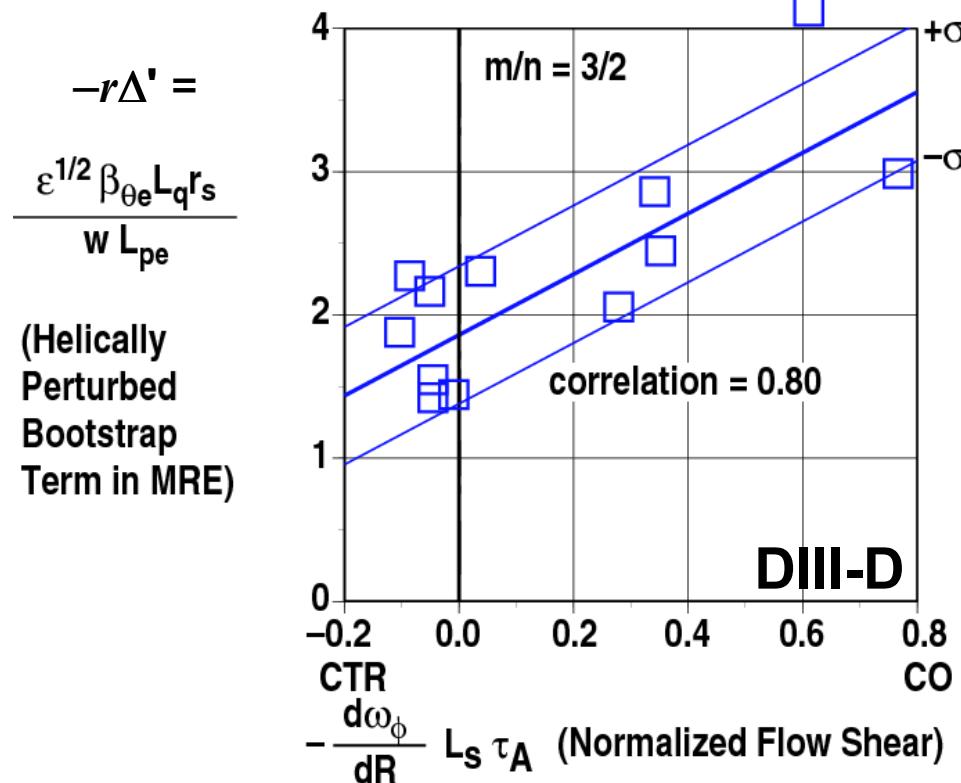
- Measure n_e, B_T scaling of error field sensitivity for ITER-like baselines so we can extrapolate
- Scan error field sensitivity in low β_N and rotation regime to deconvolve effects more thoroughly
- Test rotation effect in hybrid scenarios, which rely on high β_N access
- Look for minimum with counter rotation



Reserve slides...

Saturated 3/2 behaviour shows rotation improves intrinsic stability

- Islands get bigger as rotation falls →
 - Calculate matching Δ' from modified Rutherford eqn:

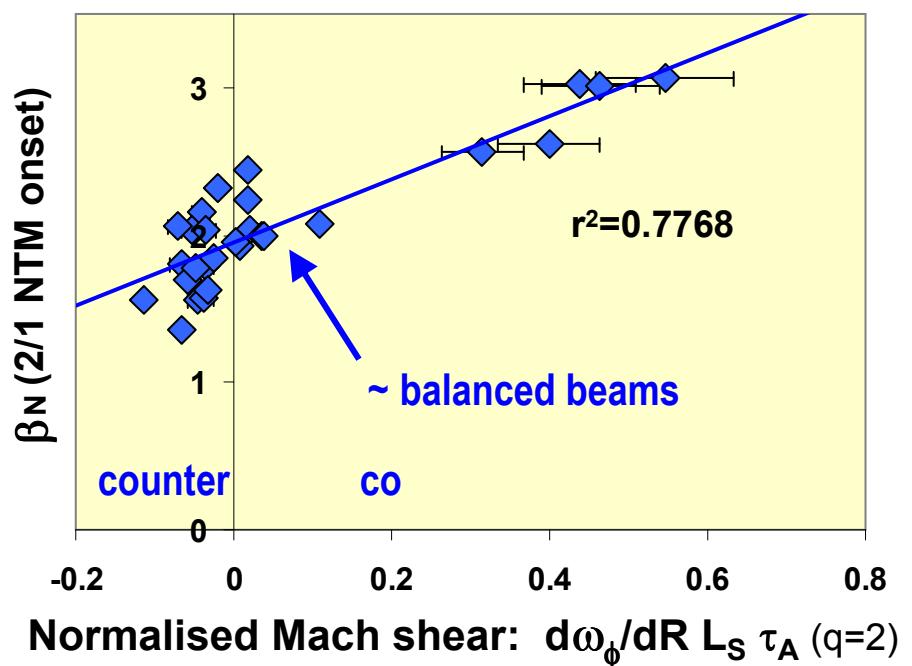
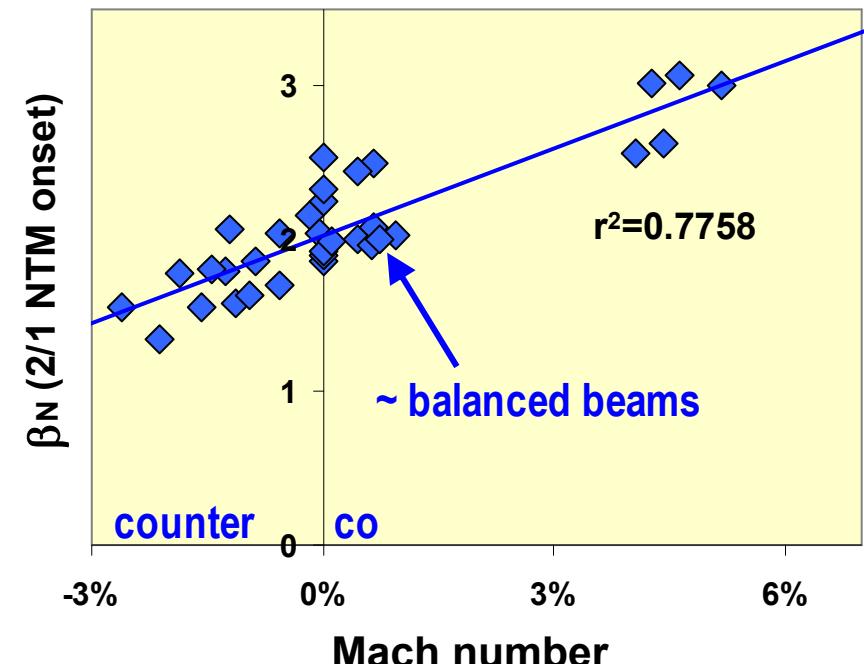


- Fits show mode less stable at low rotation
 - Larger w (note $1/w$ term)
- Not clear if rotation $\wedge 1$ or $\wedge 2$
 - ...or if sign dependence

Flow shear could play stabilising role

- Theoretically flow shear impacts intrinsic tearing stability
 - But flow and its shear are degenerate in DIII-D

→ see NSTX [1]
& see [2] for study of DIII-D saturated modes



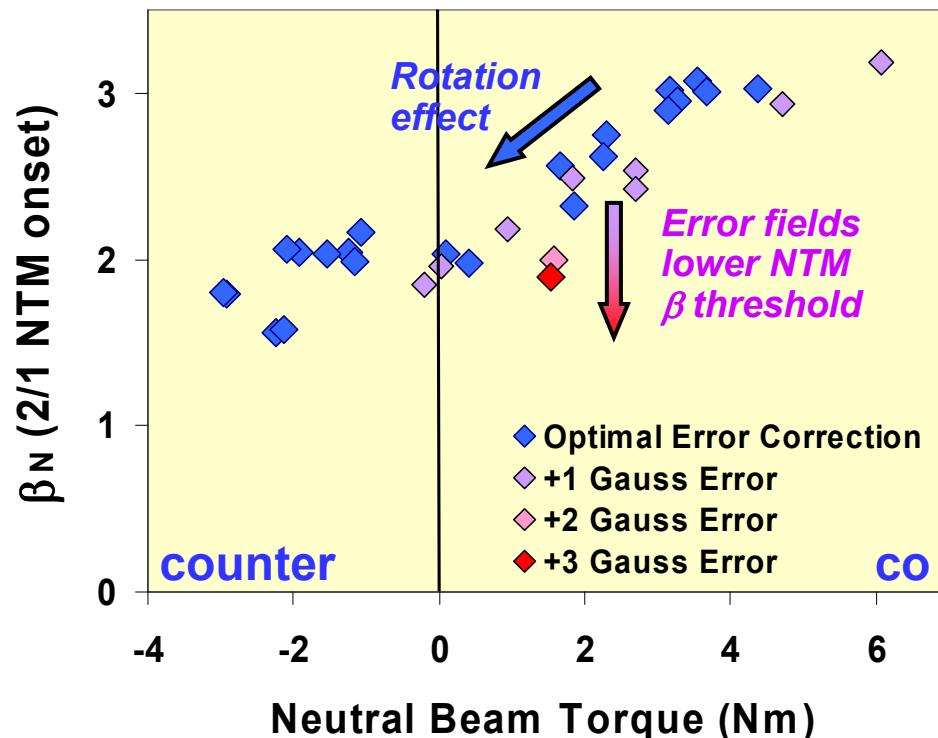
See:

¹S. Gerhardt poster APS 2008 NP6.00100

²R J La Haye poster APS 2008 JP6.00087

Previous NTM & error field study raised many questions

DIII-D 2006 showed lower rotation has lower 2/1 onset β_N
– and error fields can lower it further...



But:

- Is it **tearing stability** or **triggering physics** changing?
- Is counter rotation destabilising?
- How do **error fields** influence thresholds?
 - especially at low rotation

Understanding is important:

- Prevalence of 2/1 NTMs
- ECCD control requirements
- Error field correction needs
- Rotation requirements