



UKAEA



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# Rotation and Error Field influences on NTMs

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*with special thanks and considerable input from:*

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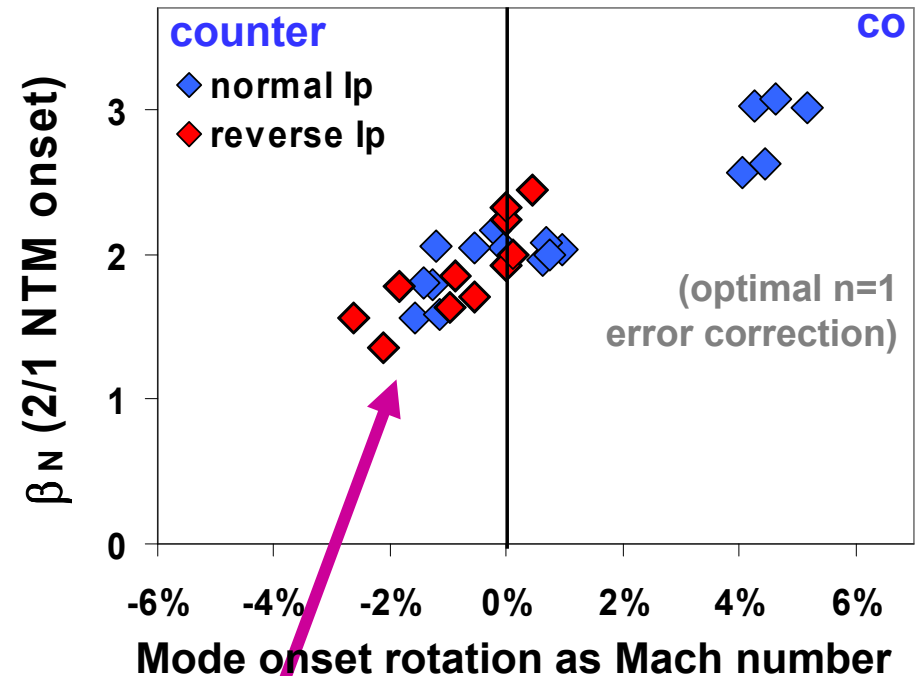


## Three Questions

- 1. Is there an asymmetry in the influence of rotation on tearing stability?**
- 2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?**
- 3. Does proximity to intrinsic tearing instability lower error field thresholds?**

# DIII-D normal & reverse $I_p$ data shows strong rotation trend

- Clear  $\beta_N$  fall with increasing counter rotation



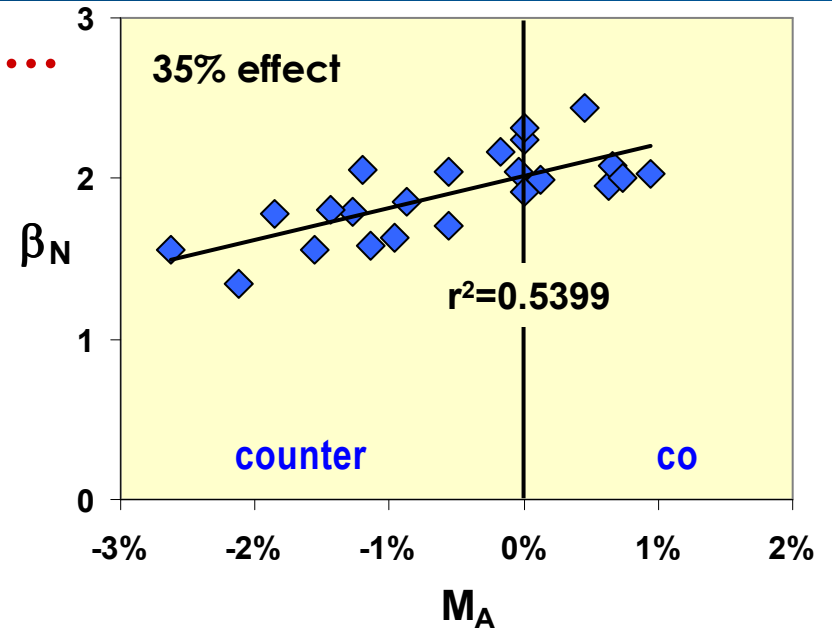
*Is counter rotation trend a 'real' effect in underlying tearing physics?*

*– or just profile variation?*

# Fall in threshold with counter rotation is a real effect...

*Consider only low rotation DIII-D data...*

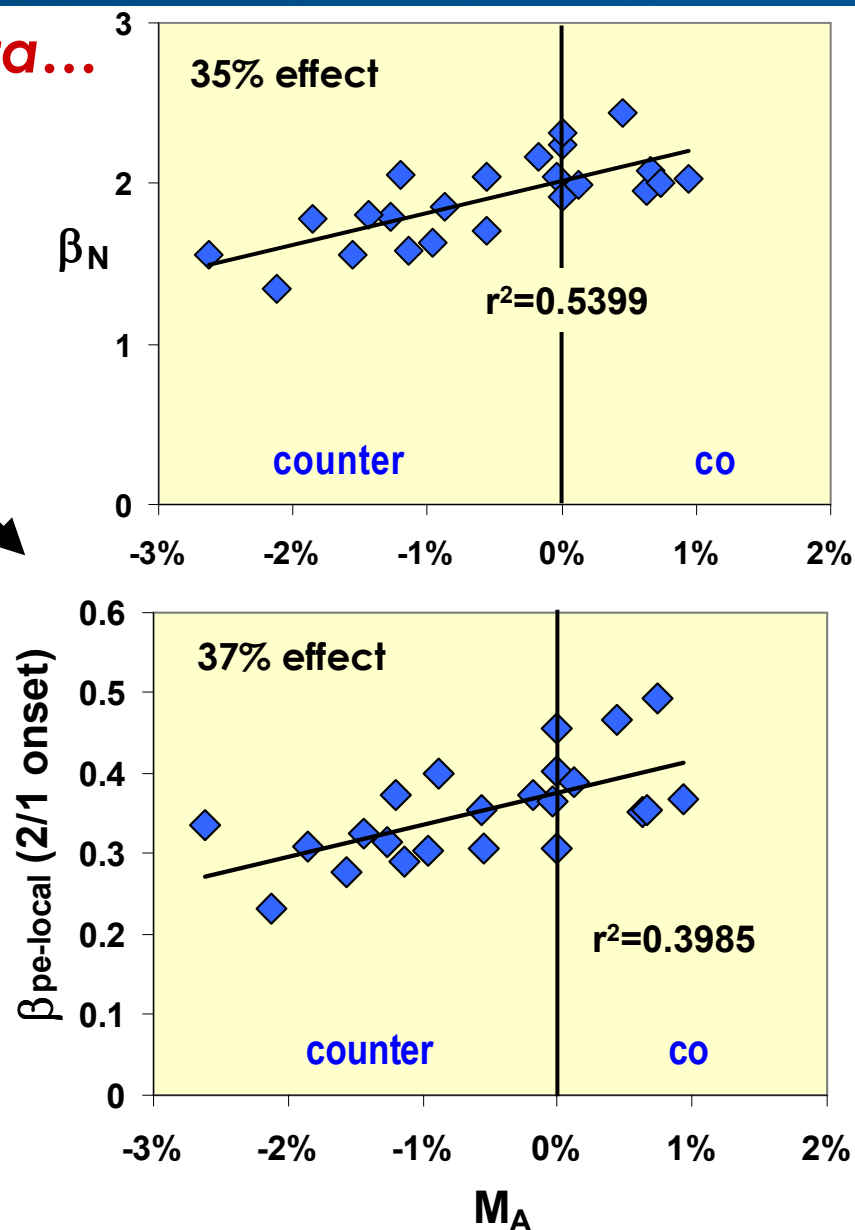
- Clear trend in  $\beta_N$  



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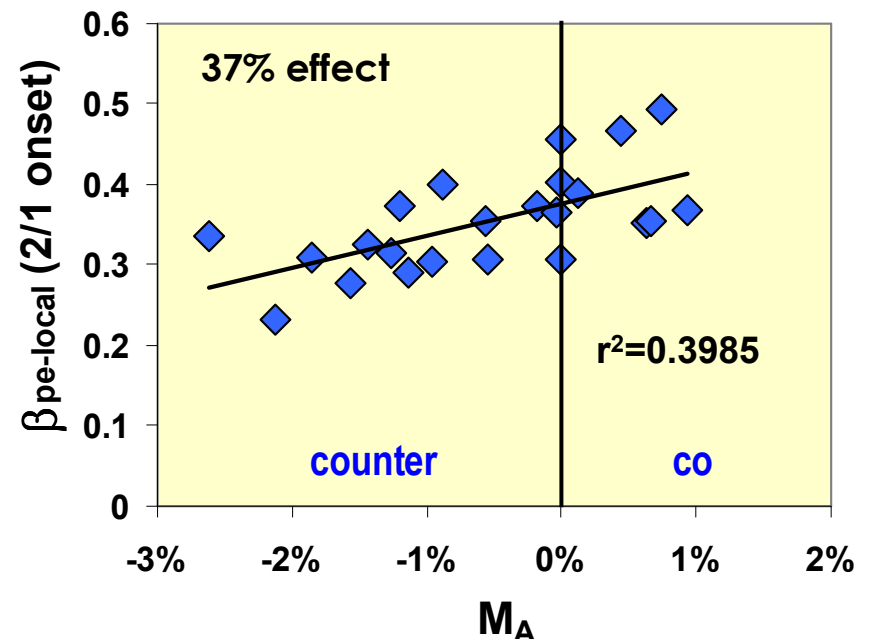
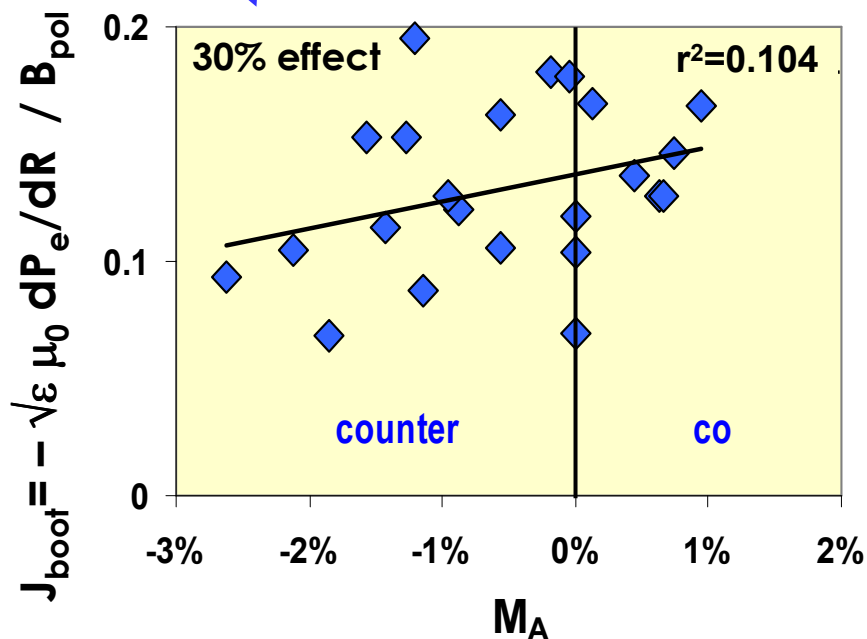
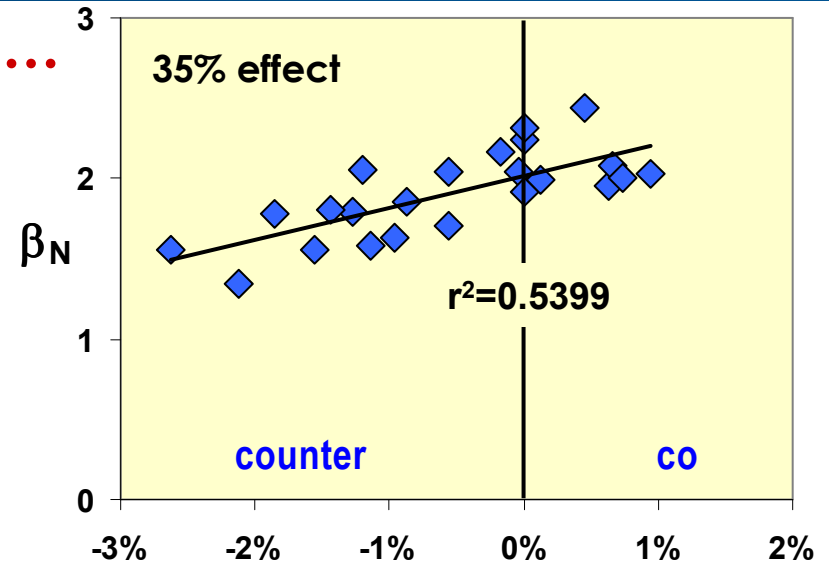
- Clear trend in  $\beta_N$
- Similar trend in local  $\beta_{pe}$



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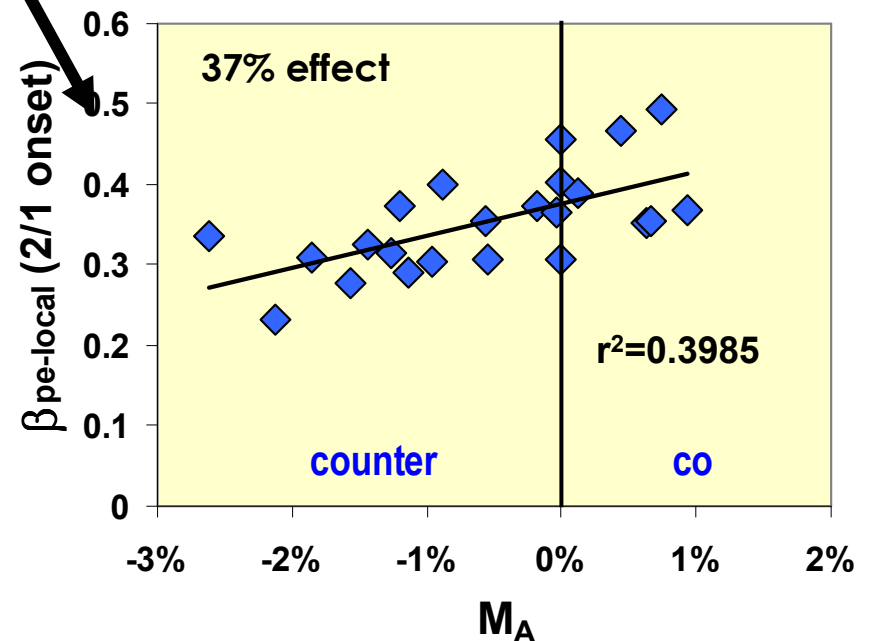
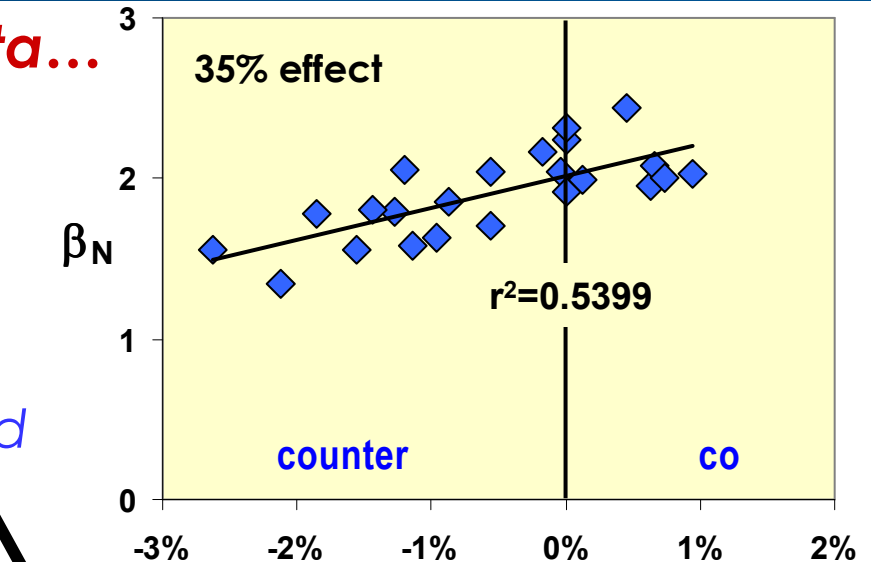
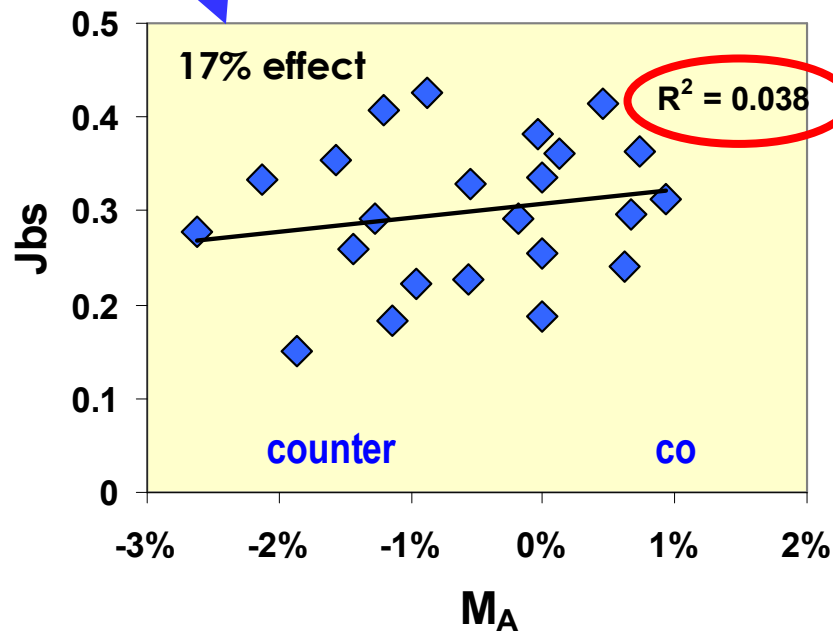
- Clear trend in  $\beta_N$
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- ...and in bootstrap measure (?)
  - *noisier – more local gradients used*



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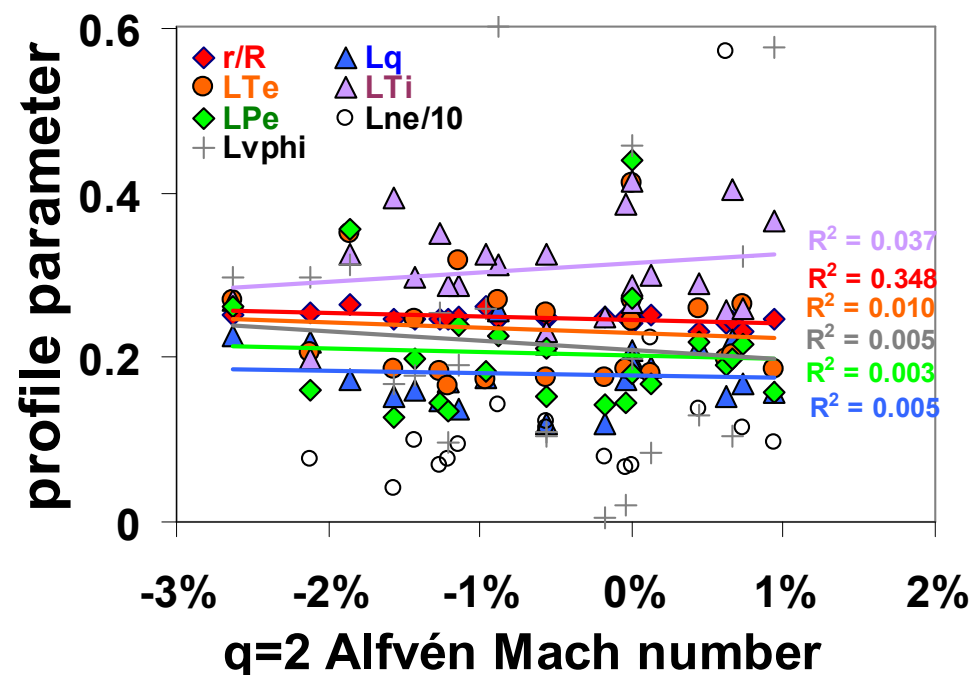
- Clear trend in  $\beta_N$
- Similar trend in local  $\beta_{pe}$
- ...and in bootstrap measure (?)
  - *noisier – more local gradients used*
  - *Even noisier with full bootstrap*



# Is there a real trend in local parameters? Yes...

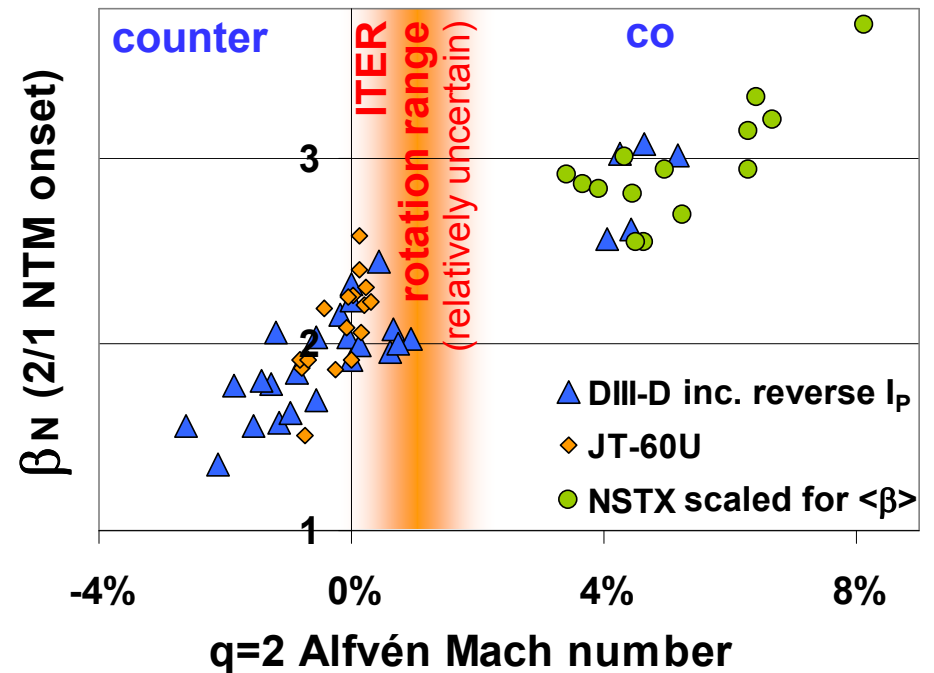
## Examine local scale lengths:

- No significant trends →
  - No systematic variation in profiles with rotation
  - Effect observed in  $\beta_N$  and 'rough' local calculations corresponds to a real variation in NTM drives
    - Effect weakened in  $J_{BS}$  mainly due to noise



# Cross-machine comparison confirms asymmetry

- JT-60U also shows a possible asymmetry in rotation role
  - *Possibly steeper?*



[Buttery et al., IAEA 2008]

## First Question...

**1. Is there an asymmetry in the influence of rotation on tearing stability?**

**– Yes**

**2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?**

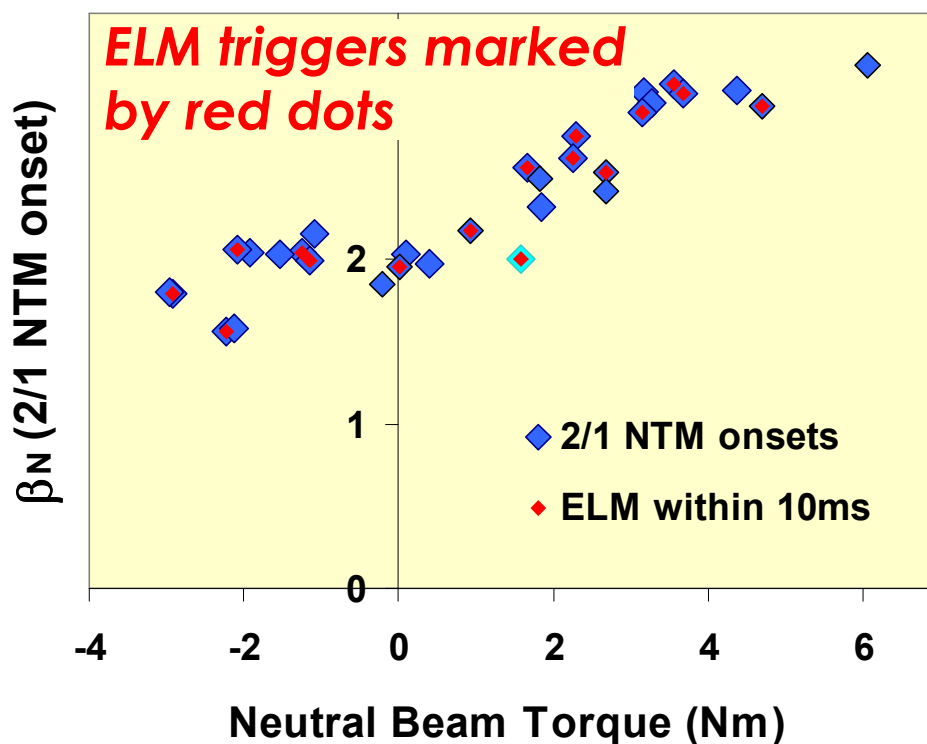
**3. Does proximity to intrinsic tearing instability lower error field thresholds?**

# ELM role in 2/1 triggering appears incidental

ELMs 'trigger' about half the 2/1 NTMs:

– *But trigger has no influence on NTM onset  $\beta_N$*

- *And trigger type not correlated with rotation*

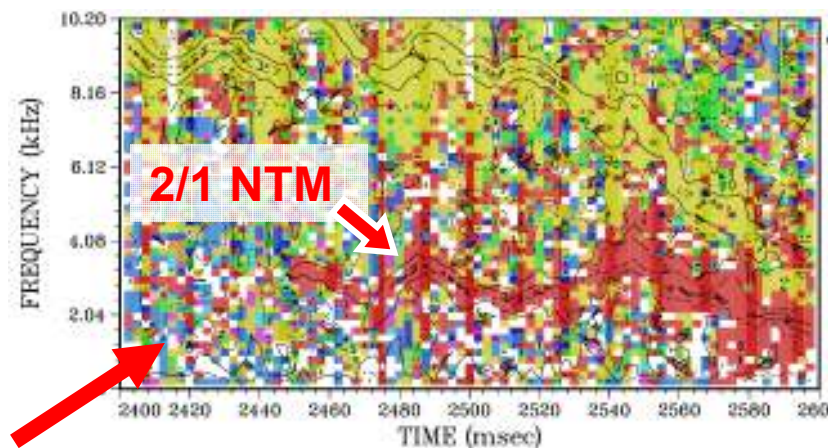


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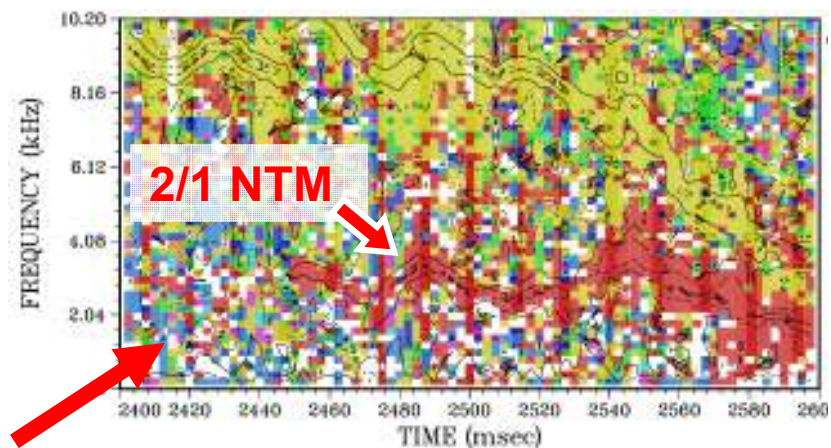
**Triggerless NTMs come out the noise**



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- But trigger has no influence on NTM onset  $\beta_N$ 
  - And trigger type not correlated with rotation



Triggerless NTMs come out the noise

- NTM onset  $\beta$  is not about “triggered seed exceeding threshold width”  $\leftarrow \rho^*$  dependent
- Instead: dictated by changes in the *intrinsic tearing stability* that govern the trigger-less modes
- Raises question of whether to expect a  $\rho^*$  dependence in  $\beta_{NTM \text{ onset}}$ ?

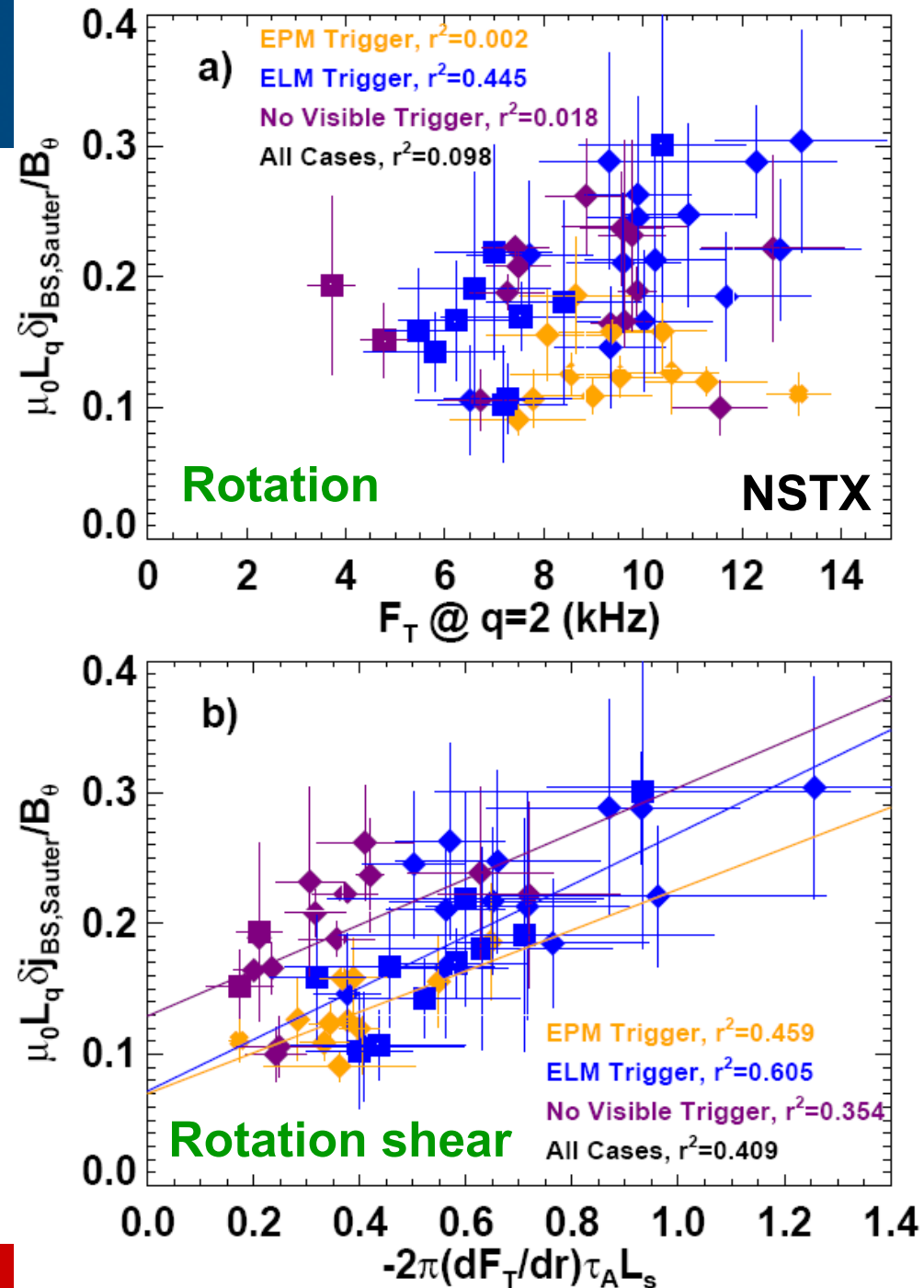
# NSTX observations suggest it is about intrinsic stability

*NSTX can deconvolve rotation from rotation shear:*

– *Rotation shear gives visibly clearer trends*

➤ *Suggests an action through intrinsic tearing stability*

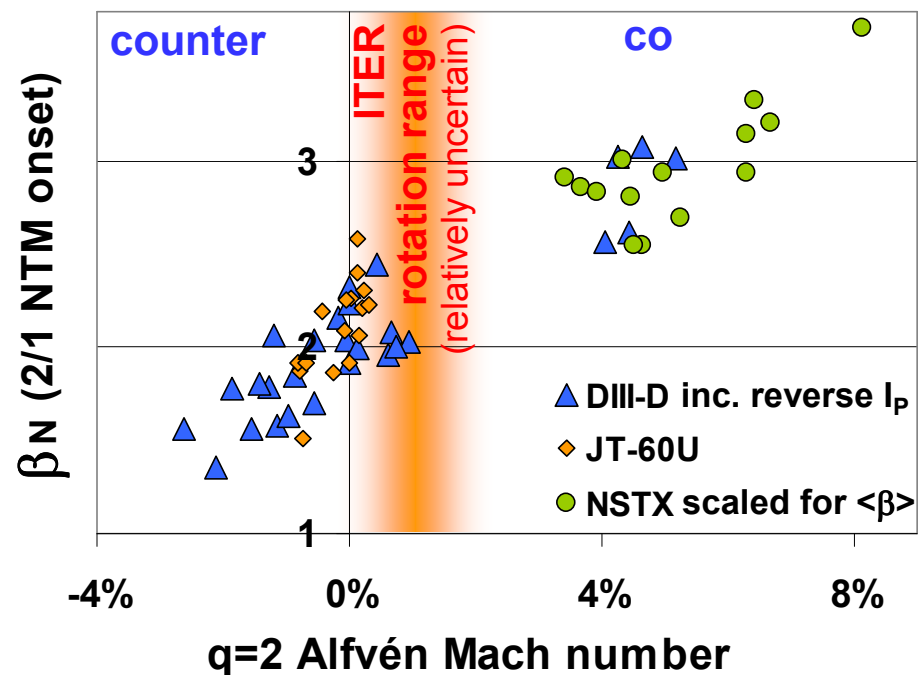
- External effects such as coupling, walls, etc. would depend on rotation
- Though trigger type can play some role...



[S. Gerhardt, NF letter submitted]

# Cross-machine comparison confirms asymmetry & suggest limit related to ideal MHD

- JT-60U also shows a possible asymmetry in rotation role
  - *Possibly steeper?*
- Devices line up when plotted with correction for  $\langle \beta_N \rangle$ 
  - NSTX data scaled to get this
  - $\langle \beta_N \rangle$  relates to ideal limit
  - 'poles in  $\Delta$ ' model



[Buttery et al., IAEA 2008]

- Phenomenology suggests:
  - **Tearing threshold arises from change in intrinsic tearing stability as ideal limit is approached**
  - **But rotation (relative to Alfvén) further changes the tearing stability**

## Second Question...

**1. Is there an asymmetry in the influence of rotation on tearing stability?**

– Yes

**2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?**

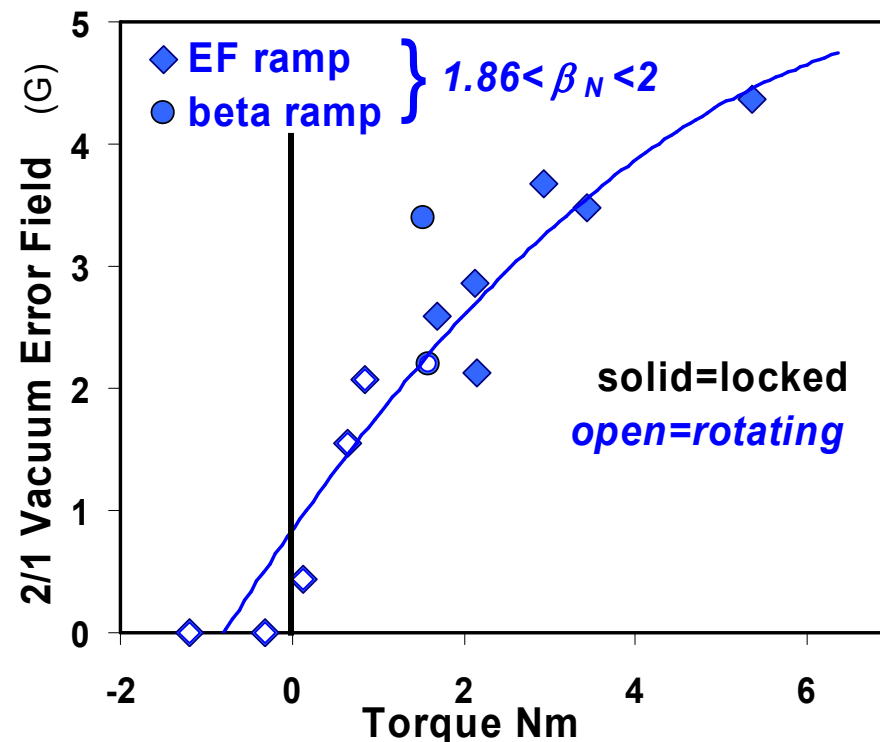
– Yes

**3. Does proximity to intrinsic tearing instability lower error field thresholds?**

# Error fields assist medium $\beta_N$ tearing mode formation

Hold  $\beta_N \sim 1.9$  and vary torque from shot to shot:

- ◆ Error field threshold falls with torque
- ◇ But rotating modes at low torque!
  - *Intrinsic tearing stability is being modified...  
...by rotation perturbation?*

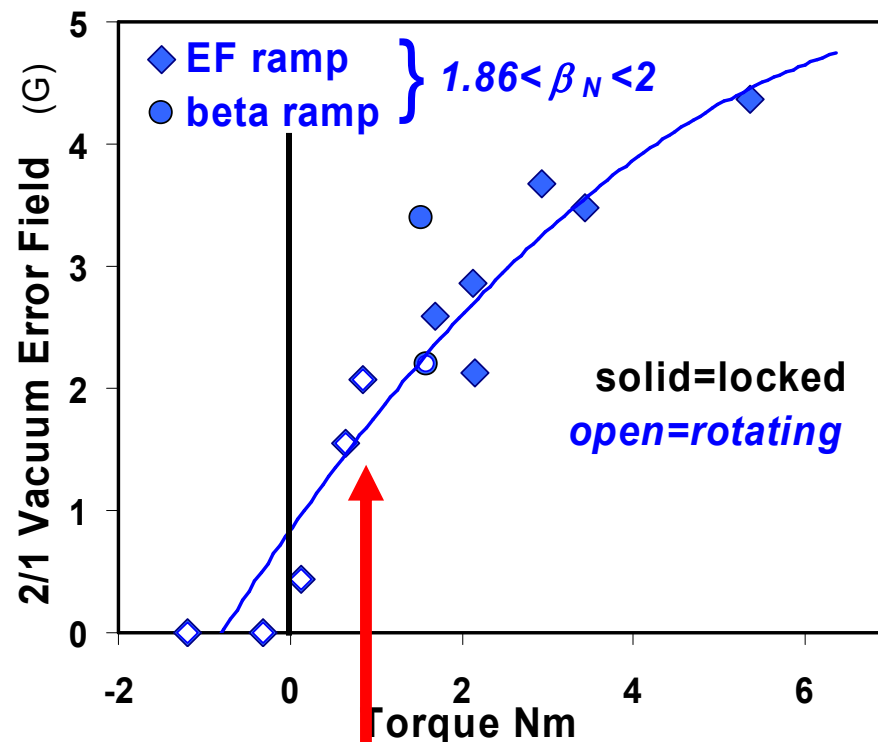


(◆ Similar to advanced scenario observations of Reimerdes: PO3.00011)

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ITER relevant torques/rotations  
just stable with good error correction:

$$\delta B_{21}/B_T < 1.10^{-4}$$

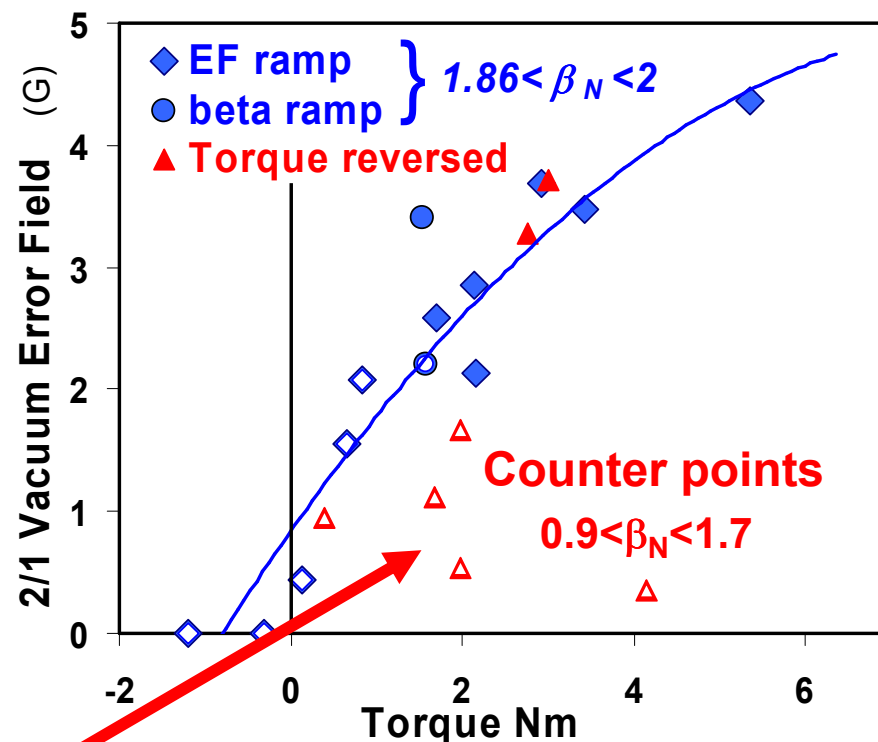
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- ◆ Error field threshold falls with torque
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  - *Intrinsic tearing stability is being modified...*  
*...by rotation perturbation?*

Compare with counter torque ( $\triangle$ )

- **Error field thresholds are lower!**
- **Despite generally being at lower  $\beta_N$  values!**
  - *Is this to do with mode rotations?*



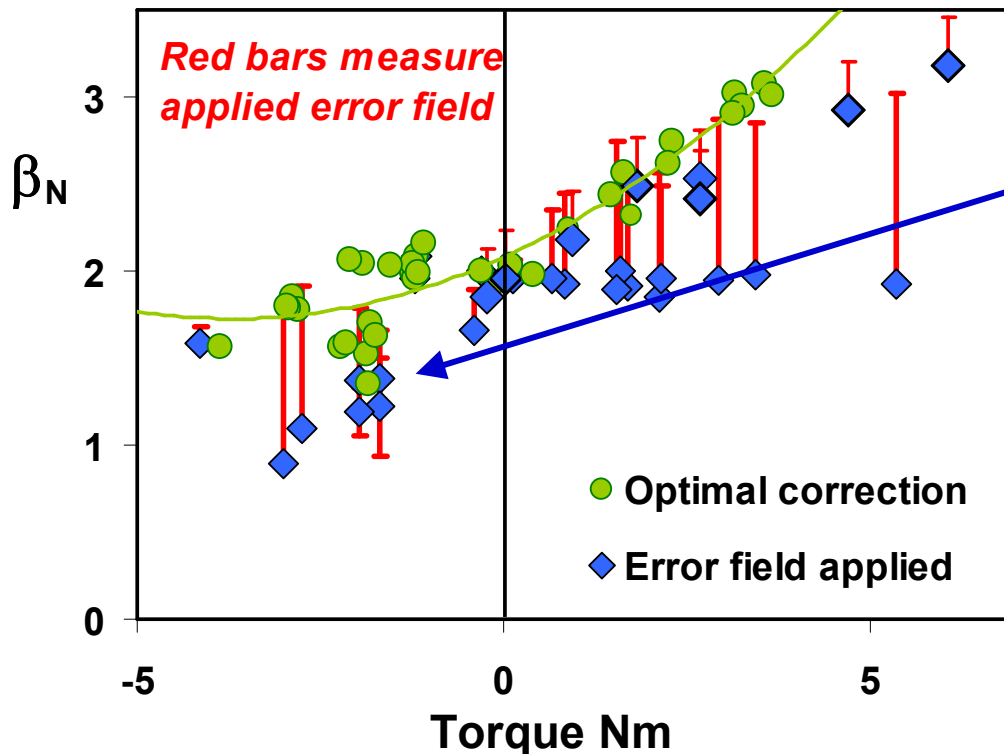
## Compare **co** and **counter** rotating cases:

- Re-plot vs mode onset rotation:***



# Amount of error field needed depends on proximity to NTM limit at a given torque?

*Full data set gives an interesting picture:*



- Error fields 'close the gap' in  $\beta_N$  with NTM  $\beta_N$  limit (○)
  - note low  $\beta_N$  points needing little error field to lower  $\beta_{N-onset}$  further
- *Is this a new error field amplification effect?*
  - Brought on by proximity to classical tearing?
  - Or asymmetry in rotation influence?

# Amount of error field needed depends on proximity to NTM limit at a given torque?

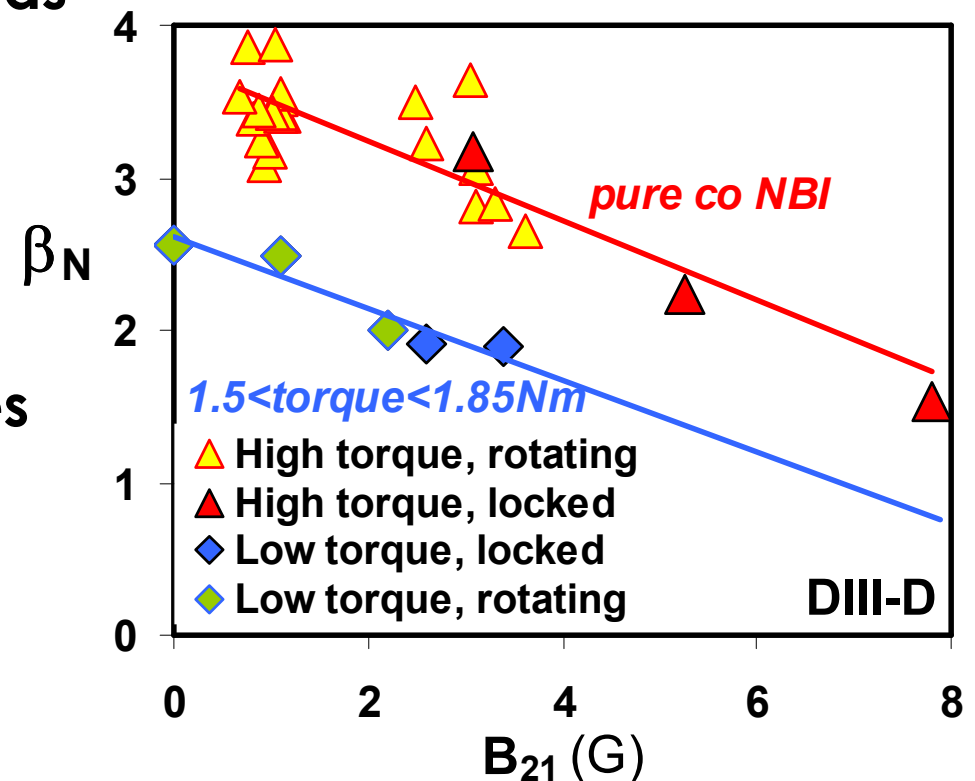
- $\beta_N$  threshold falls as error fields increase

*or equivalently*

- Error field sensitivity increases at high  $\beta_N$  & low rotation

– *Should it?*

*...shielding still strong?*



- *Suggests revised error field correction requirements required for ITER at baseline and hybrid operating points*

## Conclusion: Three Questions Answered

**1. Is there an asymmetry in the influence of rotation on tearing stability?**

**– Yes**

**2. Is 2/1 mode onset threshold mostly governed by intrinsic tearing stability?**

**– Yes**

**3. Does proximity to intrinsic tearing instability lower error field thresholds?**

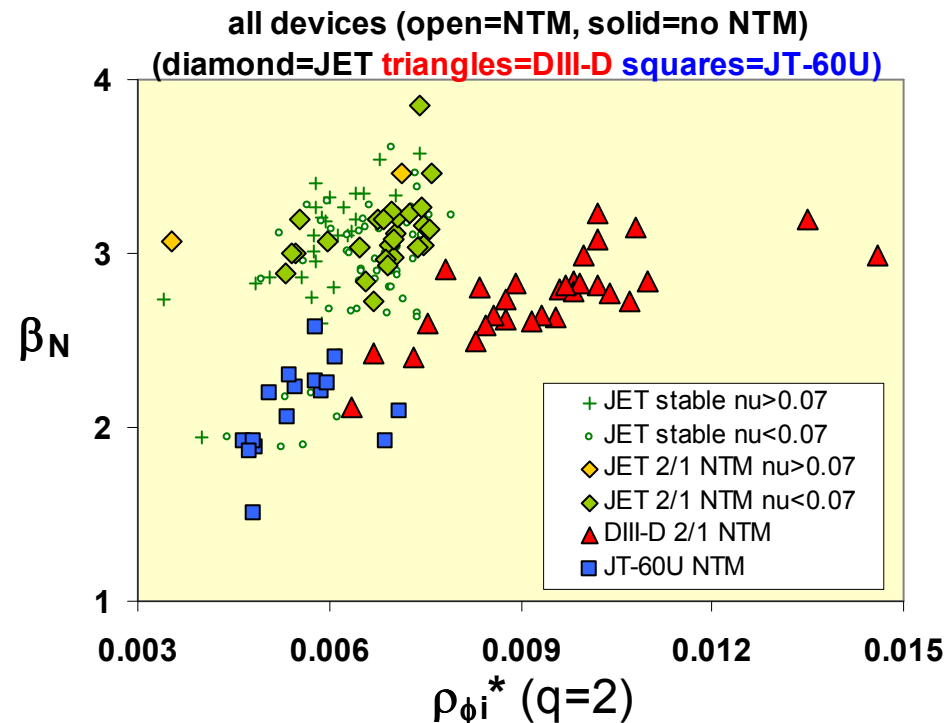
**– Yes**

This is good news –

$\rho^*$  dependent physics may not be dominant

Explore hybrid scenario 2/1 NTM  $\beta$  limits:

- **JET** sits well above trend in  $\rho^*$  from **DIII-D**
  - In 2/1 thresholds & stable data
- **JET** even somewhat higher in absolute  $\beta_N$ 
  - Possibly  $q$  profile and/or fast particle effects
- **JT-60U** lower due to low rotation



*But that's another talk...!*

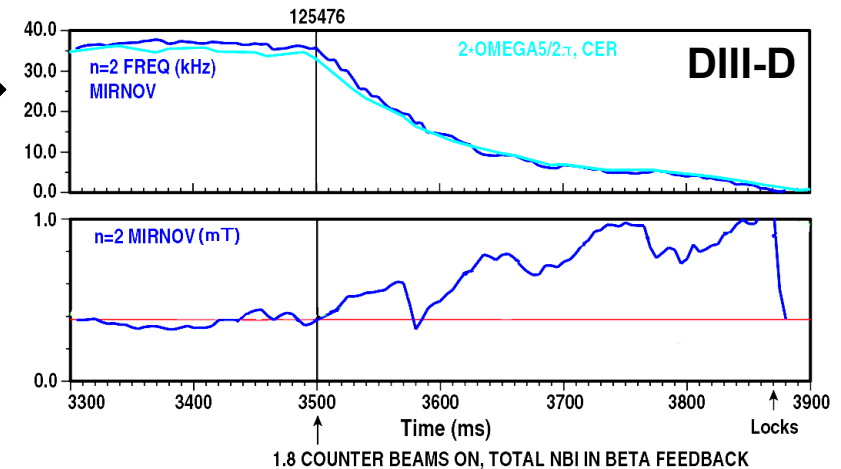
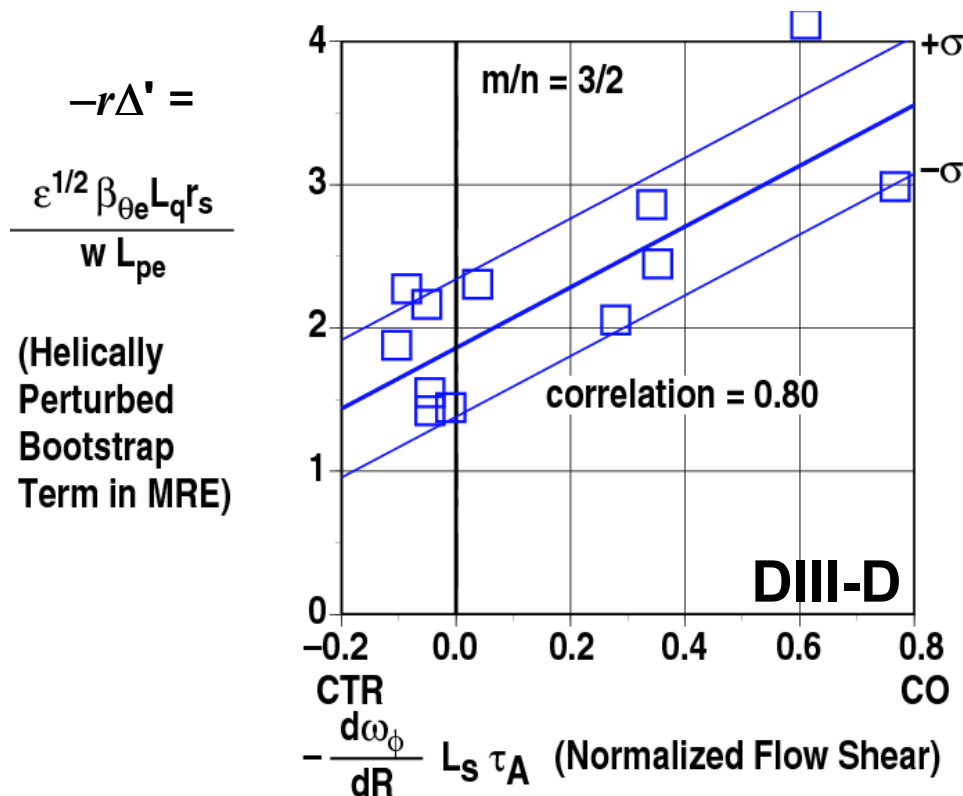
# More experiments needed!

- Measure  $n_e, B_T$  scaling of error field sensitivity for ITER-like baselines so we can extrapolate
- Scan error field sensitivity in low  $\beta_N$  and rotation regime to deconvolve effects more thoroughly
- Test rotation effect in hybrid scenarios, which rely on high  $\beta_N$  access
- Look for minimum with counter rotation

**Reserve slides...**

# Saturated 3/2 behaviour shows rotation improves intrinsic stability

- Islands get bigger as rotation falls →
  - Calculate matching  $\Delta'$  from modified Rutherford eqn:



- Fits show mode less stable at low rotation
  - Larger  $w$  (note  $1/w$  term)
- Not clear if rotation  $\Delta 1$  or  $\Delta 2$ 
  - ...or if sign dependence

# Flow shear could play stabilising role

- Theoretically flow shear impacts intrinsic tearing stability
  - But flow and its shear are degenerate in DIII-D

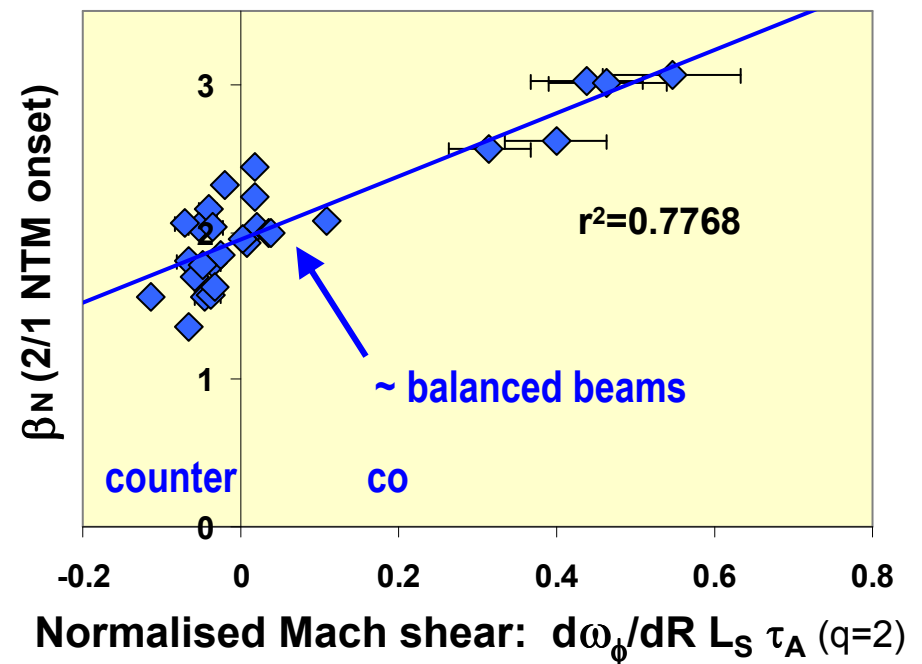
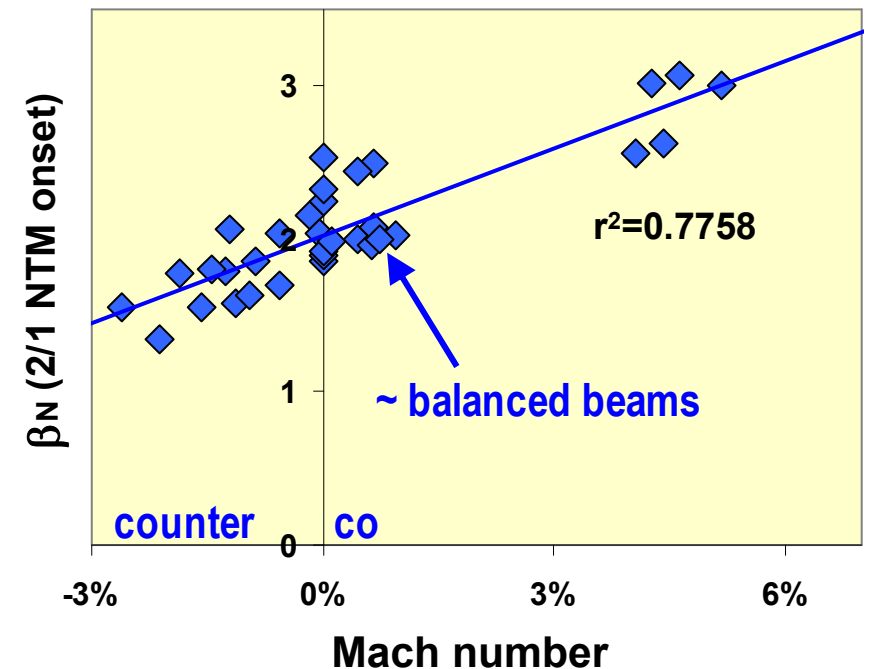
→ see *NSTX* [1]

& see [2] for study of DIII-D saturated modes

See:

<sup>1</sup>S. Gerhardt poster APS 2008 NP6.00100

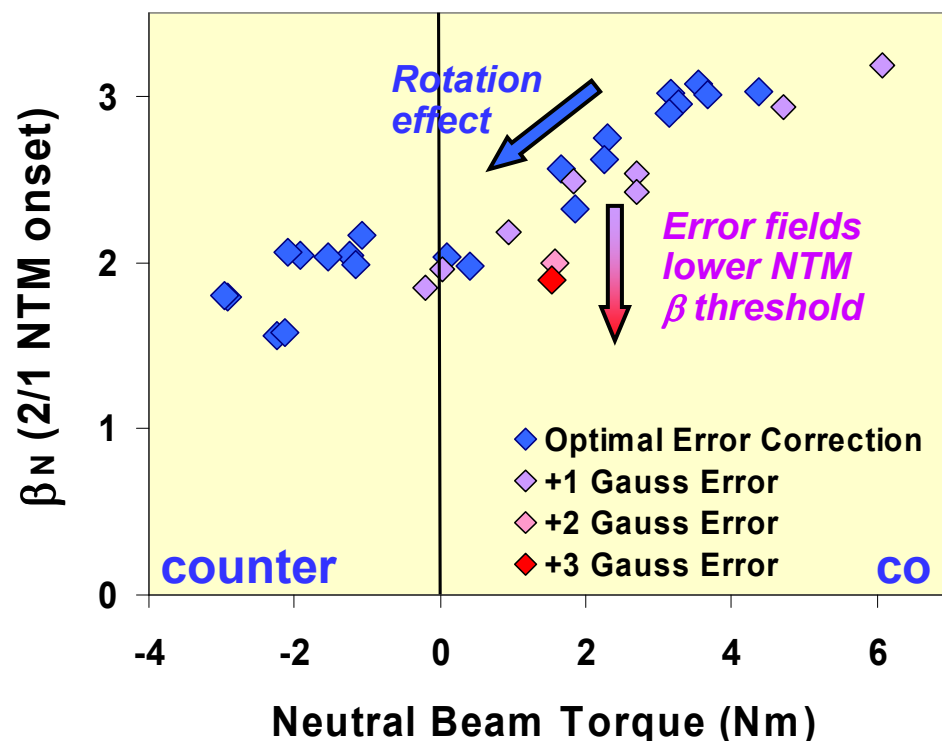
<sup>2</sup>R J La Haye poster APS 2008 JP6.00087



# Previous NTM & error field study raised many questions

DIII-D 2006 showed lower rotation has lower 2/1 onset  $\beta_N$

– *and error fields can lower it further...*



**But:**

- Is it **tearing stability** or **triggering physics** changing?
- Is counter rotation destabilising?
- How do **error fields** influence thresholds?  
– *especially at low rotation*

**Understanding is important:**

- Prevalence of 2/1 NTMs
- ECCD control requirements
- Error field correction needs
- Rotation requirements