

# **RFX Program on Active Control**

#### Consorzio RFX - Associazione Euratom-ENEA sulla fusione - Padova, Italy

#### Presented by Stefano Martini



at the 9TH WORKSHOP ON MHD STABILITY CONTROL: "CONTROL OF MHD STABILITY: BACK TO THE BASICS": NOVEMBER 21-23, 2004, PPPL



Hopefully this is the last workshop...

OPS...

# I FORGOT A SLIDE FROM LAST YEAR WORKSHOP!

COVERING THE WHOLE PLASMA SURFACE





# The RFP dynamo

 The current profile in a RFP cannot be driven in steady state by a constant inductive electric field *E*<sub>o</sub>



 ....but RFP plasmas last much longer than the resistive diffusion time! (actually, as long as *E*<sub>o</sub> is applied)

 An additional "dynamo" electric field E<sub>d</sub> is necessary to maintain the toroidal magnetic flux.

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#### Turbulent dynamo: self-organization

A wide experimental and numerical database supports the MHD turbulent dynamo theory:



 $\left| \vec{E}_{d} - \left\langle \widetilde{v} \times \widetilde{b} \right\rangle \right|$ 

E<sub>d</sub> is produced by the coherent (non-linear) interaction of many MHD modes => Multiple Helicity (MH) dynamo





m=1 "dynamo" modes (resonant inside the Bt reversal surface)

m=0 non-linearly generated and/or linearly unstable

![](_page_6_Figure_3.jpeg)

Magnetic stochasticity allover the plasma !

![](_page_7_Picture_0.jpeg)

#### The slinky

Each mode is associated to an helical perturbation of the plasma

The Phase Locking of many modes results in a non-axisymmetric deformation, the so-called "slinky" t [ms] #12461

Braking torques by the vessel and fi errors cause Wall Locking of the slink

# Localised plasma-wall interaction $\Rightarrow$ 100 MW/m<sup>2</sup>

![](_page_7_Figure_6.jpeg)

# ONSORZIO RFX Previous MHD control experiments

## Previously MHD mode control on RFX based on :

- Reduction of field errors
- Control of modes via the B\u03c6 coils:
  - Active control of poloidal current:
    Pulsed => PPCD
    - Oscillating => OPCD
  - Active rotation of the locked modes (RTFM)

![](_page_9_Picture_0.jpeg)

# Pulsed Poloidal Current Drive

External poloidal current drive (first tested on MST) transiently quenches the spontaneous dynamo.

![](_page_9_Figure_3.jpeg)

![](_page_9_Picture_4.jpeg)

Strong reduction of magnetic fluctuations and improved confinement

## **Oscillating Poloidal Current Drive**

![](_page_10_Figure_1.jpeg)

![](_page_11_Figure_0.jpeg)

![](_page_12_Figure_0.jpeg)

The  $B\phi$  coils produce a traveling m=0 perturbation which exerts torque on q=0 island:

$$T_z^{0,1} \propto b_r^{0,1} B_r^{0,1}(r,1) \sin(\Delta \phi_{0,1})$$

Rotation opposed by drag of eddy currents in resistive vessel

$$T_{visc}^{m,n} \propto (b_r^{m,n})^2 \omega$$

A sufficiently high external field  $B_r^{0,1}$  overcomes the drag and lock in phase the 0,1 mode

#### **Continuous** Induced Rotation CONSORZIO RFX Enforcing the proper phasing during the start-up phase: continuous rotation for the whole discharge t [ms] #12350 80 60 40 20 I1 cm 0 90 180 270 360 toroidal angle $\Phi$ (deg)

![](_page_14_Picture_0.jpeg)

#### Three mode interaction

• m=1 modes experience a non linear torque:  $T_z^{1,n} \propto C_n b_r^{1,n} b_r^{1,n+1} b_r^{0,1} \sin(\phi^{1,n+1} - \phi^{1,n} - \phi^{0,1}) + C_{n-1} b_r^{1,n} b_r^{1,n-1} b_r^{0,1} \sin(\phi^{1,n-1} - \phi^{1,n} + \phi^{0,1})$ 

for sufficiently high external field:

- high n modes will co-rotate with (0,1) ext. perturbation
- low n modes will counter-rotate

• in general => 
$$\omega^{1,n+1} - \omega^{1,n} = \omega^{0,1}$$

![](_page_15_Figure_0.jpeg)

![](_page_16_Picture_0.jpeg)

#### 1MA Pulses with & without rotation

#### **NO rotation**

# with rotating modes

![](_page_16_Figure_4.jpeg)

![](_page_17_Picture_0.jpeg)

## The Single Helicity (SH) dynamo

- a theoretically predicted state with a unique m = 1 saturated resistive kink (<u>a pure helix wound on a torus</u>),
- Stationary LAMINAR dynamo mechanism with good helical flux surfaces

![](_page_17_Picture_4.jpeg)

Escande et al., PRL 85 (2000)

![](_page_18_Picture_0.jpeg)

#### Magnetic order with SH dynamo

Good magnetic flux surfaces in SH

![](_page_18_Figure_3.jpeg)

![](_page_18_Figure_4.jpeg)

SH

#### Turbulent (MH)

![](_page_19_Figure_0.jpeg)

The mode spectrum is dominated by one geometrical helicity

![](_page_19_Figure_2.jpeg)

![](_page_20_Picture_0.jpeg)

![](_page_20_Picture_1.jpeg)

# Therefore, with the aim of making a new step (hopefully) forward along the path to the "good RFP" we now have...

QSH alleviate the problems, but are not sufficient to reach the design target 2MA regime.

![](_page_21_Figure_0.jpeg)

First plasma with the new assembly mid December 2004

![](_page_22_Picture_0.jpeg)

#### Mode dynamics in RFPs

- Experimental evidence in several RFPs shows that the evolution of MHD modes, including the dynamo modes, depends on the magnetic boundary, and in particular on the shell:
  - thickness
  - proximity
  - geometry

![](_page_23_Picture_0.jpeg)

#### Conducting shell in RFPs

Scenarios for MHD control in the new RFX depend crucially on the effect of the modifications to shell geometry, proximity and time constant

Experiment	R/a m	b/a	$ au_{shell}ms$	$\tau_{pulse}$ ms	$ au_{pulse}/ au_{shel}$	
RFX92	2/0.457	1.24	450 150		1/3	
RFX new	2/0.459	1.11	50	150 ?	3?	
MST	1.5/0.51	1.07	400	60-90	_	
TPE RX	1.72/0.45	1.08 1.16	10 330	60	6 1/5	
T2R	1.24/0.183	1.08	6	20	>3	

![](_page_24_Figure_0.jpeg)

![](_page_25_Figure_0.jpeg)

![](_page_26_Picture_0.jpeg)

#### Conclusions on mode rotations

- Dynamo modes are spontaneously rotating in RFP devices with close fitting shell (even if a threshold in current might exist)
- Externally resonant RWM are seen in RFPs. Their growth time agrees with the shell time constant and they do no rotate
- There is a reasonable basis for spontaneous rotation of dynamo modes in the new RFX

![](_page_27_Picture_0.jpeg)

## Mode control experience in T2R

- As shown in previous talks by
  - Jim Drake (yesterday )
  - Roberto Paccagnella (today)
- During the last year a fruitful collaboration between the T2R and the RFX groups permitted to perform very interesting experiments on active mode control on T2R

![](_page_28_Picture_0.jpeg)

#### Feedback experiments on T2R

Amplitude and angular phase velocity for resonant tearing mode m=1, n=-14.

![](_page_28_Figure_3.jpeg)

![](_page_28_Figure_4.jpeg)

From: P. R. Brunsell, et al., "First results from intelligent shell experiments with partial coil coverage in the EXTRAP T2R reversed field pinch", 31st EPS, ECA Vol.28G, P-5.190 (2004) See also: P. Brunsell et al., Feedback stabilization of multiple resistive wall modes, to be published on PRI

![](_page_29_Figure_0.jpeg)

Rotating n=6 perturbation:. Freq.=100 Hz,  $\phi_0$ =0, different amplitudes.

![](_page_30_Picture_0.jpeg)

#### T2R experience with mode control

- Open loop experiments<sup>1</sup> clearly showed intrinsic error field reduction or amplification, depending on amplitude and phase of the applied external field.
- Feedback operations have shown clear reduction of MHD mode amplitudes and beneficial effects on plasma-wall interaction.
- Intelligent shell and individual/ multiple mode control schemes successfully implemented and compared
- <sup>1</sup> A B + Preke o Operioloopf control experimenter in FXTRAP 22 R RFP, yesterday talk

![](_page_31_Picture_0.jpeg)

![](_page_31_Picture_1.jpeg)

#### Main new components:

- 1. new toroidal field power supply
- 2. first wall with higher power handling capabilities
- 3. smoother and thinner shell
- 4. 192 saddle coils, covering the whole plasma boundary, each independently powered and feedback controlled
- 5. in-vessel system of magnetic and electrostatic probes

![](_page_32_Picture_0.jpeg)

#### m=0 x RTFM & PPCD/OPCD

		Modified RFX			<i>RFX</i> 92	
Control strategy	Amplitude	Period (ms)	<b>F</b> ( <b>H</b> z)	Amplitude	Period (ms)	<b>F</b> ( <b>H</b> z)
RTFM m=0, n=1: B <sub>twall</sub> control	58 mT	40	25	10 mT	40	25
PPCD: V <sub>pol</sub> control	10 V	10	125	9 V	10	125
OPCD: V <sub>pol</sub> control	10 V	3 - 8	125 - 333	3 V	7	140
		B <sub>tor</sub>	new ≈ t 25 Hz	6 x B <sub>tor</sub> with 3k/	old A	

Compared to RFX 92 RTFM capability greatly enhanced, which is of utmost importance since

•RTFM was not possible at high density in RFX92

![](_page_33_Picture_0.jpeg)

#### The new shell

#### • One 3 mm Cu layer:

- 1 overlapped poloidal gap: 23° toroidal overlap
- 1 toroidal gap on high field side

![](_page_33_Picture_5.jpeg)

![](_page_34_Picture_0.jpeg)

#### New saddle coil system

- 4 poloidally: 90°
- 48 toroidally: 7.5°
- Complete toroidal coverage

each independently powered 24 kAt: 400 A × 60 turns

Wide spectrum of Fourier components :

![](_page_34_Picture_8.jpeg)

![](_page_35_Picture_0.jpeg)

#### Ex-vessel magnetic and thermal probes

#### Probes between vessel and shell

Integral probes:

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- 4 Rogowski coils for I<sub>D</sub>
- 8 toroidal voltage loops
- 6 poloidal voltage loops
- 32 partial V<sub>POL</sub> probes for halo currents
   48×4 saddle probes for B<sub>r</sub>
- 48 saddle coils for B<sub>r</sub> ( on eq.plane)
- Pick up probes (40×36×4 mm bi-axial) probe for  $B_T$  and  $B_P$  enamelled wire coils wound around single core):
  - 48 toroidal × 4 poloidal distribution
  - 2 higher resolution poloidal arrays

Magnetic probes total number  $\approx 650$ 

![](_page_36_Picture_13.jpeg)

Thermocouples:

![](_page_37_Picture_0.jpeg)

### Aim of RFX modifications

- Improve the design of the plasma front end
  - First wall power handling capability;
  - Vessel wall protection;
  - Plasma breakdown;
  - Axisymmetric equilibrium control;
  - Poloidal gap field error;
  - Toroidal gap field error.

#### Improve the active control of the MHD modes

- Increase the torque applied to the plasma through the m=0 mode for RTFM
- Produce m=1, n= 1-20 single o multiple mode to induce: mode rotation, "single helicity" and to actively control ext.& int. modes

![](_page_38_Picture_0.jpeg)

#### Low current scenario

- Theory (Guo, Fitzpatrick et al) and experiments (TPE-RX, EXTRAP T2R, MST) suggest that at low current RFX should see spontaneous dynamo mode rotation.
- This is suitable to concentrate efforts on RWM control

#### High current scenario (> 1 MA)

- Better for confinement improvement techniques (OPCD) and for interaction with "dynamo" modes (but higher walllocking probability).
- Passive shell (and EXTRAP T2R experience) might postpone RWM issue up to ≈50-100 ms

![](_page_39_Picture_0.jpeg)

Benchmark and improve old RFX performance

Actions by an applied m=0 mode (TF coils):

a. RTFM (also in closed loop mode)

b. PPCD/OPCD

c. OPCD+ RTFM

d. OFCD

![](_page_40_Picture_0.jpeg)

### Active actions through 192 saddle coils:

- Apply m =1 magnetic perturbations
  - Work on individual modes: one at the time or several simultaneously
- Realize an intelligent shell
  - Zeroing of radial field at the edge to maintain an effective close fitting shell.
  - Interesting also for QSH studies, since a smooth magnetic boundary facilitates their onset.

![](_page_41_Picture_0.jpeg)

#### Drive of m=1 magnetic perturbations

- Apply a monochromatic perturbation to affect one individual mode:
  - "pumping" the mode to drive QSH states through helical fields at the plasma boundary
  - Feedback stabilization of individual modes
  - inducing rotation of a single mode
- Apply several simultaneous geometrical helicities (various n's):
  - damping of main "dynamo modes"
  - feedback stabilization of RWM
  - breaking phase locking among "dynamo modes" with induction of modes differential rotations

![](_page_42_Picture_0.jpeg)

#### 2005 RFX program

- Plasma pulses start mid December 2004. The program for 2005 envisages 45 weeks of operation including 11 weeks of machine commissioning and 34 with plasma.
- Aim of first year is to test most of the increased flexibility of RFX covering many programs, including a first assessment of enhanced confinement regimes and active control of MHD instabilities.

![](_page_43_Picture_0.jpeg)

Main objectives of first year

- Maximise the parameter range for spontaneous fast rotation of tearing modes.
- Establish a clear comparison with the reference passive operation of the old RFX.
- Explore scenarios for enhanced confinement.
- Active control of MHD instabilities:
  - feedback stabilisation of RWM,
  - control of single and multiple m=0,1 tearing modes
  - intelligent/wise shell.

![](_page_44_Picture_0.jpeg)

## 2005 planning

				Qtr 1, 2005			Qtr 2, 2005				Qtr 3, 200	5		Qtr 4, 2005		
0	Task Name	Duration	Dec	Jan	Feb	Mar	Apr	M	lay	Jun	Jul	Aug	Sep	Oct	Nov	Dec
11	SD1 - diagnostic	9 days	27/12	07/01												
	integration		_													
THE	C1 - commissioning	4 wks	10	/01	-04/02											
	c. comociona		10.		04/02											
à	EW-1 wall conditioning	2 days			*											
~	W-1 wan conditioning	,			l I											
a.	Dd	2 wko			<u> </u>											
1	P1 - plasma	2 1755		07/0	2	18/02										
-																
1	C2 - commissioning	3 wks			21/02	11/03										
1	P2 - plasma: l°phase	6 wks				14/03		2/04								
								1								
1	SD2 - diagnostic	3 wks					25/04		12005							
×	integration						25/04	-	13/05							
de.	FW 2 well conditioning	3 days						-								
1	FW-2 wall conditioning	5 00,5							η							
4									-							
1	P2 - plasma: ll°phase	6 WKS						17/05			27/06					
	C3 - commissioning	4 wks								28/06		25/07				
1	P3 - plasma	12 wks									26/07				25/10	
Ľ	, o presidente										20/07				0.10	
	SD3: maintenance	1 wk														
	5D5. maintenance											16/08 2	2/08			
1	B4 alternation de d	8 wko												<u> </u>		
	P4 - plasma: extended	OWNS												26/10		20
	P2&P3 campaigns															
	end of 2005 campaign	0 days														
																<u> </u>
Sh	utdown:	6 wee	ks			Thu 21/	10/04									v.1
Co	mmissioning	11 wee	eks													
Pla	anned experimental campaigns	: 26 wee	ks + 8 \	weeks (e	xtensi	ion and/o	r mainte	enan	ce)							

#### P2 e: feedback control of m=0 modes

![](_page_45_Figure_1.jpeg)

- Simulations show that the transport in the q=0 region is determined by amplitude and phases of m=0 and m=1 modes
- Acting on the phases of m=0 modes can influence closed structures in the reversal region
- Minimising m=0 amplitudes is important also for favouring QSH

# CONSORZIO RFX P2 g: experiments on QSH

![](_page_46_Picture_1.jpeg)

- Investigate conditions which help onset of QSH states
  - Parameter scans
  - Magnetic boundary optimization
    - Feedback controlled equilibrium
    - P/OPCD

#### Diagnostic improvements will allow

- Particle and energy confinement studies
- Ion dynamics measurements
- Determination of the plasma flow correlated with QSH

![](_page_46_Figure_11.jpeg)

![](_page_47_Picture_0.jpeg)

- Aim: suppressing the dynamo and establishing the confinement and β limits for the RFP configuration
- Rationale: 3-D MHD simulations show that a stochastic plasma reaches a condition of low amplitude modes by applying proper time-dependent magnetic boundary conditions (R.A.Nebel et al, PoP 2002)
- The decay rate is about  $-\gamma \approx -10/\tau R$
- In RFX a first test of this prediction will be performed

![](_page_47_Picture_6.jpeg)

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### P2 i: Oscillating Field Current Drive

![](_page_48_Figure_2.jpeg)

and plasma regimes)

#### P3 1b: Active Control of tearing modes

Open loop and feedback control on single/multiple dynamo modes including:

induction of QSH regimes

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 drag of locked tearing modes into slow rotation and control of their relative phases.

#### Encouraging results from T2R:

- Pre-programmed helical perturbations with resonant helicities (open-loop)
- Feedback suppression of other reconant modes (closed loop)

![](_page_49_Figure_7.jpeg)

![](_page_50_Picture_0.jpeg)

#### **RFX-Tokamak operation**

- With its highly flexible diagnostic and control system, RFX could contribute also to studying MHD mode control on tokamak plasmas
- A maximum Bφ = 0.6 T allows us to set up a Tokamak with:
  - v I = 100 kA @ q(a)=3
  - A total flux swing of 6-7 Vs permits to sustain the plasma for times much longer than the 50 ms shell time constant
- We are open to suggestions/proposal for collaborations also in this area!

![](_page_51_Picture_0.jpeg)

![](_page_52_Picture_0.jpeg)

![](_page_52_Picture_1.jpeg)