### RFA Experiments on the T2R RFP Open loop control experiments

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Open loop control experiments in EXTRAP T2R RFP

### Outline

The theme of the workshop is back to the basics. Topics aimed at in this talk are:

- Assumption of mode rigidity
- Applicability of the linear model

Data shown:

- "Open loop" constant resonant control harmonic (qualitative information)
- "Open loop" pulsed resonant control harmonic (quantitative estimates of transfer functions, mode growth rates and mode damping rates)

### **Basics - Resistive- wall mode stability in the RFP**

Cylindrical plasma bounded by a thin wall: radius  $r_w$  and (long) penetration time  $\tau_w$ .

Natural growth rate,  $\gamma_{m,n}$ , of a non-rotating m=1 RWM is then defined by the stability index given by the discontinuity in the logarithmic derivative of the perturbed field at  $r_w$ . [ref C G Gimblett, Nuc Fus 26 (1986) p 617].

$$2\gamma_{m,n}\tau_w = r_w\Delta_{m,n}'.$$

An important assumption is that the mode structure in the plasma is **rigid**.

Therefore the plasma can be specified by the single parameter, the growth rate,  $\gamma_{m,n}$ , of the RWM.

An externally produced control field <u>or</u> a field error, at  $r_f > r_w$ , modifies  $\Delta_{m,n}'$ and thereby the growth rate for that (m,n)-harmonic.

To compare experiment and theory, examine the time dependence of the **RWM radial field** perturbation evaluated on the inside surface of the thin wall, **which is the location of the sensor coils in the experiment**.

## Linear model for the (m,n)-harmonic of the RWM including external error and control field harmonics

$$d_t b_{m,n} = \gamma_{m,n} b_{m,n} - \gamma_{m,n,w} (M_{m,n} I_{m,n} + b_{m,n}^{error})$$

#### where,

- $\mathbf{b}_{m,n}$  is the perturbed field measured at the sensor coil.
- $\gamma_{m,n}$  is the growth rate of the mode.
- $\gamma_{m,n,w} = (\tau_{m,n,w})^{-1}$  describes the diffusion rate of the harmonic at the thin wall and is determined only by the mode number and the wall parameters.
- $\mathbf{b}_{m,n}^{error}$  is that part due to an external inherent field error.
- $\mathbf{M}_{m,n}\mathbf{I}_{m,n}$  is the saddle-coil-produced control field ( $\mathbf{I}_{m,n}$ =current &  $\mathbf{M}_{m,n}$ =ratio field to current, [*Tesla/Amp*])

### T2R Coil system(s)



### **Control system**

#### **Sensors**

• 32x2 one-turn, m=1 flux loops measure radial magnetic flux through shell

16x2 saddle-coil current measurements

#### Controller

- digital controller, 64 sensor inputs, 32 coil current inputs
- real-time spatial FFT for toroidal harmonics
- Input feedback laws in the form of a matrix of complex gains

• 16x2= 32 preprogrammed control voltage outputs drive the saddle coil currents

#### **Actuators**

- m=1 connected saddle coils, L/R time constant 1 ms
- coil current 20 A, magnetic field 1 mT (1% of equil. poloidal field)
- high-bandwidth audio amplifiers, output power 700 Watt

### "Natural" mode amplitude and phase traces for standard discharge



- "Error field" mode (e.g. n=-2):
  - Linear growth
  - Wall locked
  - Reproducible phase
- RWM (e.g. n=-10):
  - Exponential growth
  - Wall locked
  - Reproducible phase

# Open loop preprogrammed constant external control field harmonic applied to n=6 unstable mode

What happens if a constant control harmonic is applied

- in phase with the natural mode (i.e. positive feedback orientation)?
- 180 degrees phase difference relative to the natural mode (i.e. negative feedback orientation)?

The data qualitatively demonstrates mode rigidity.



Amplitude of the mode is  $\approx$  1.0 mT; a. of the external perturbation is  $\approx$  0.02mT

# Open loop preprogrammed constant external control field harmonic applied to n=6 unstable mode

What happens if the control harmonic is turned on at a later time when the mode amplitude is larger ?

The data qualitatively demonstrates mode rigidity.

### Open loop RWM studies



Time (s)

Compensation can be obtained with a perturbation starting in the middle of the discharge but at the price of a higher amplitude.

This case can be compared with feedback operations

- unstable modes
- marginally unstable modes
- marginally stable modes
- robustly stable

Resonant field error amplification?

Measure growth and damping rates. Give indication of applicability of linear model. Analyze resonant field error amplification.

# Open loop experiments with a pre-programmed *pulsed* external control harmonic

#### Comment on the spectrum of unstable modes in an RFP



#### Harmonics for two modes are shown:

n=-4 (marginally unstable)

n=+12 (stable)



Black = current pulse to external saddle coil (Short pulse with constant phase) Green = b-external harmonic pulse measured by sensor coil. Blue = b-plasma harmonic for a reproducible reference discharge Red = b-plasma harmonic for a discharge with external perturbation applied.

#### Harmonics for two modes are shown:

n=-4 (marginally unstable)

n=+12 (stable)



#### Harmonics for two modes are shown:

n=-4 (marginally unstable)

n=+12 (stable)



### Open loop experiments





Theory: Calculations for a thin, smooth resistive cylinder Experiment(+): Measurements in vacuum using preprogrammed current waveforms for saddle coil currents.



Control field

Resonant field error amplifcation can be studied by subtracting the reference plasma shot from the plasma shot with the external resonant perturbation.

Use the linear model.

• Make a best fit to the data where the fitting parameters are the plasma growth (damping) rates and the ratio  $M = b_n/I_n$ .



#### Harmonics for two *unstable* modes: n= -11 & n=+5



Harmonics for a *marginally stable* mode (n= -2) & a stable mode (n=+14)



Harmonics for another *unstable* mode (n = -6) & a stable mode (n = +10)



Summary of growth (damping) rates and ratio  $M = b_n/I_n$  determined from best fit to measured data. Note!



Red "o" are values for cases with plasma & control harmonic

Blue "+" are values for control harmonic in vacuum

The mutuals,  $M_n = b_n/I_n$ , should be the same for best fit to vacuum data and to plasma data.

(Higher m numbers must be included to model current in saddle coils.)

#### Summary

Modeling of open loop control experiments in EXTRAP T2R RFP using the well known form:

$$d_t b_{m,n} = \gamma_{m,n} b_{m,n} - \gamma_{m,n,w} (M_{m,n} I_{m,n} + b_{m,n}^{error})$$

#### With fitting parameters:

- Growth (damping rates)
- Mutuals (field at sensor coil/current in saddle coil

Give the following values for growth (damping) and inherent error fields:

n	-11	-6	-4	-3	-2	+5
γ(ms⁻¹)	0.22+i0.15	0.05	>0.02	<0.01	<0.02	0.08+i0.03
b <sub>err</sub> (mT)		0.013	0.02	<0.01	0.1	
b <sub>err</sub> (phase)		<b>0</b> °	-145°		4 5 °	